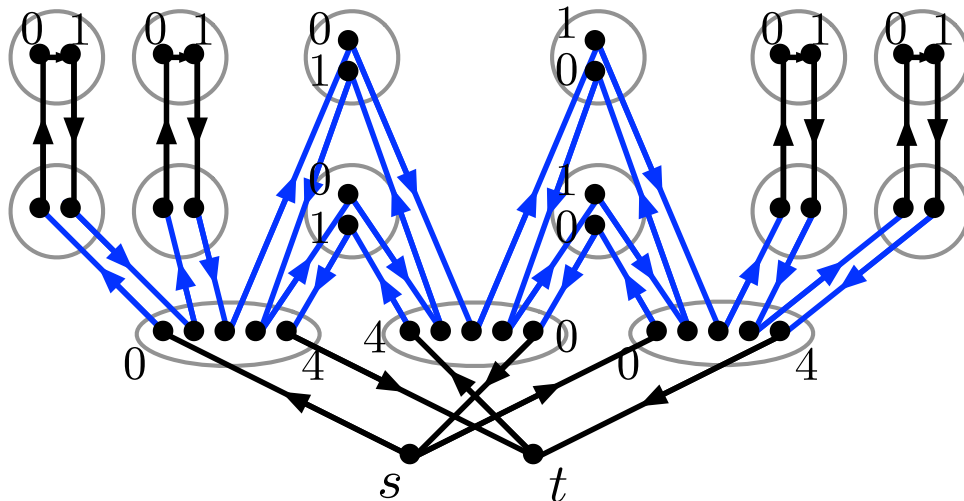


Quantum algorithm for deciding st -connectivity



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USC

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arXiv:1203.2603 [quant-ph]

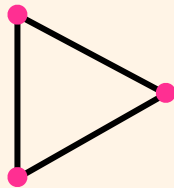
① st-connectivity

Is there a path from s to t ?

② Path-detection

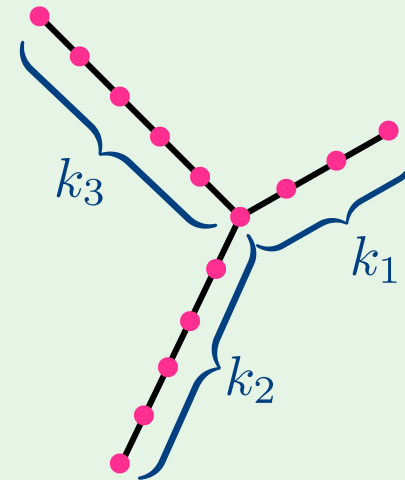
Is there *any* path of length k ?

③ Triangle subgraph/not-a-minor
promise problem



Does G contain a triangle, or is it acyclic?

④ Claw-detection



Detect a $\{k_1, k_2, k_3\}$ subdivided claw

Input: G 's adjacency matrix, an $\binom{n}{2}$ -bit string

Query complexity

Goal: Evaluate function f on input x

Resource: $\sum_j \alpha_j |j\rangle \rightarrow \boxed{x \in \{0, 1\}^n} \rightarrow \sum_j \alpha_j (-1)^{x_j} |j\rangle$

Algorithm:



New st -connectivity quantum query algorithm

$$O(\sqrt{M R_{st}}) = O(n\sqrt{d}) \text{ queries,}$$

possible edges

if s and t are promised either to be within distance d ,
or be disconnected

Applications
incl. learning graphs

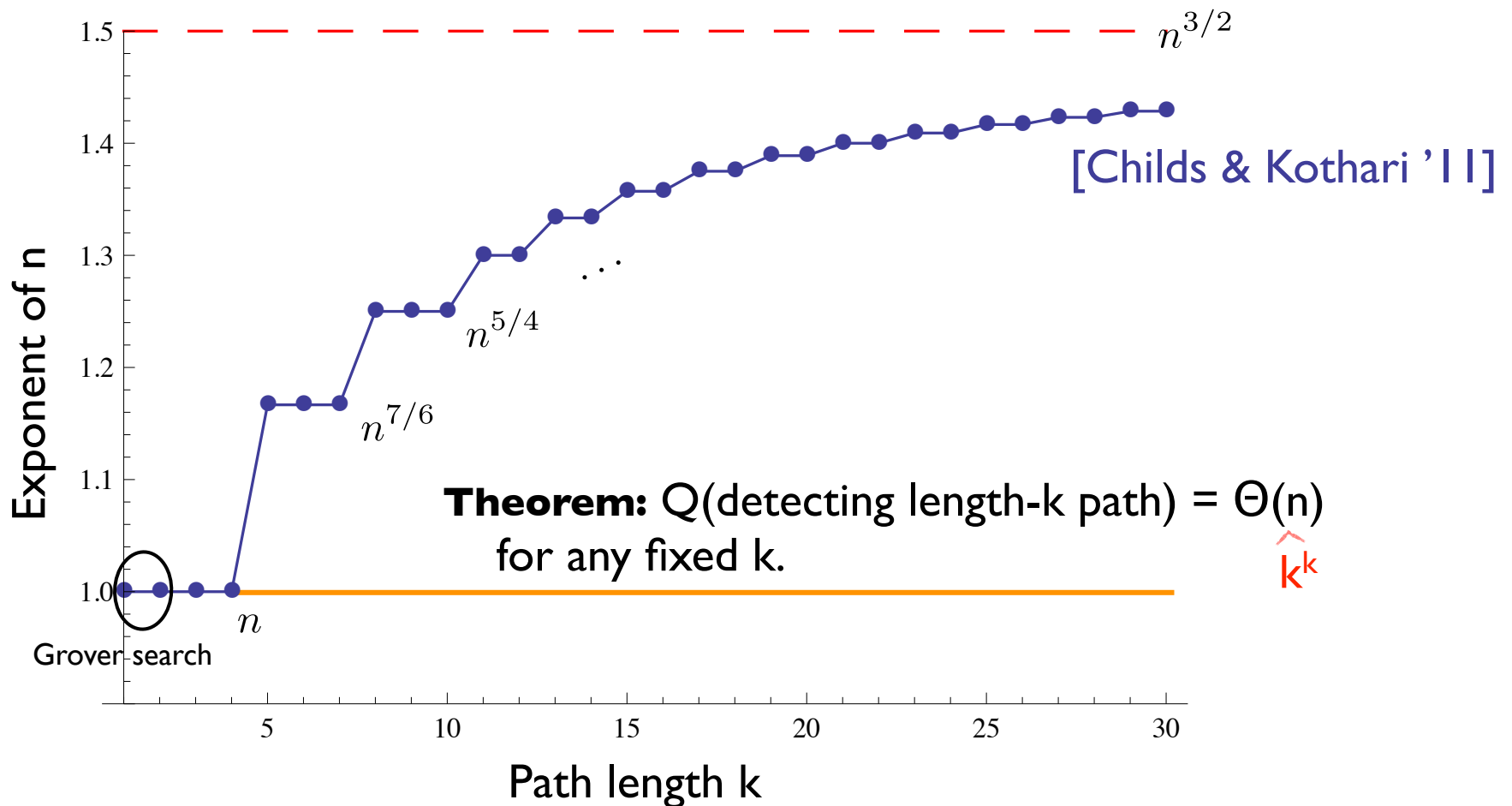
Log space

Efficiently
implementable


Connections
to random &
quantum walks

Application: Path detection

Does G contain a path of length k ?

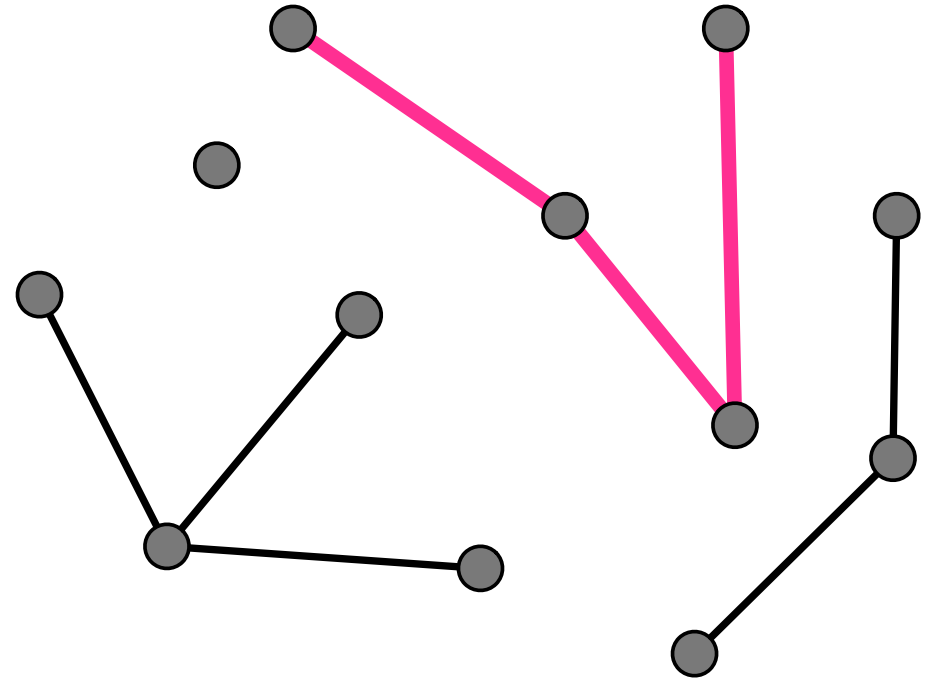


Application: Path detection


Does G contain  ?

Algorithm

- Randomly color vertices by $\{0, \dots, k\}$.
Discard badly colored edges.
(Hopefully a path is colored correctly.)

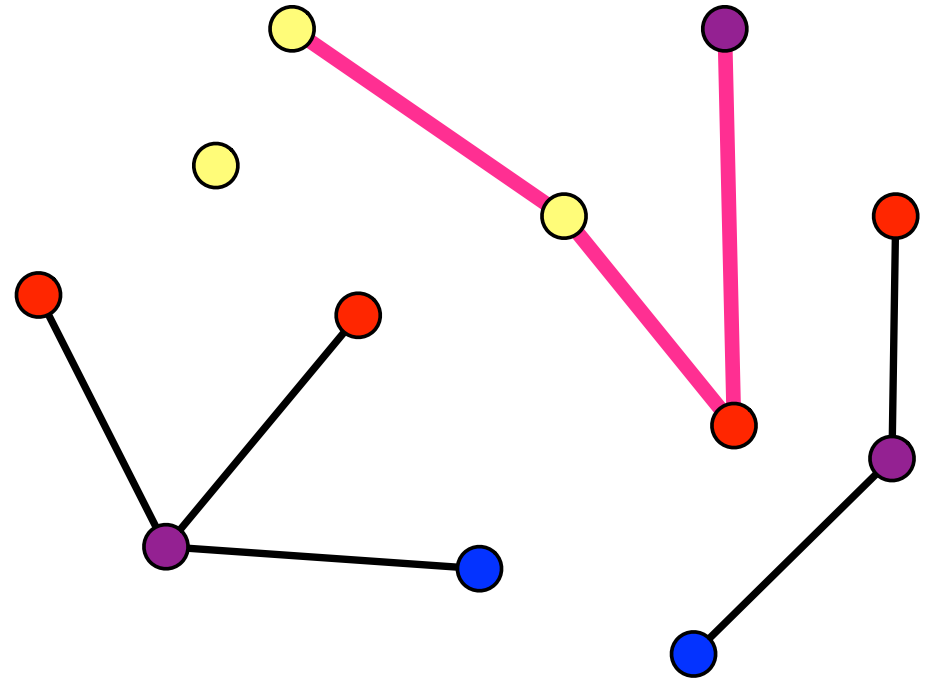


Application: Path detection


Does G contain  ?

Algorithm

- Randomly color vertices by $\{0, \dots, k\}$.
Discard badly colored edges.
(Hopefully a path is colored correctly.)

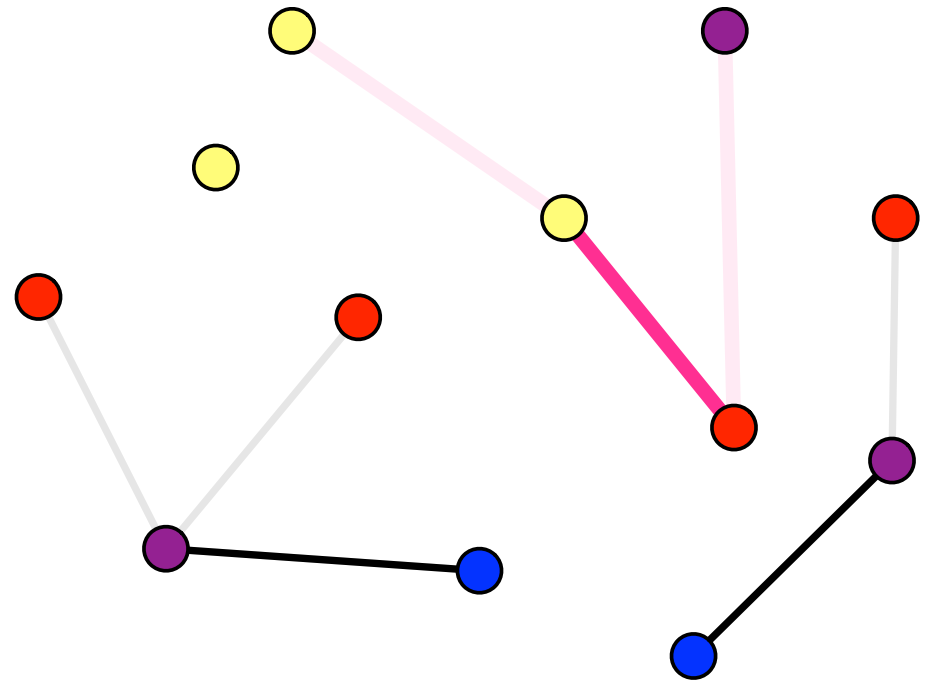


Application: Path detection


Does G contain  ?

Algorithm

- Randomly color vertices by $\{0, \dots, k\}$.
Discard badly colored edges.
(Hopefully a path is colored correctly.)

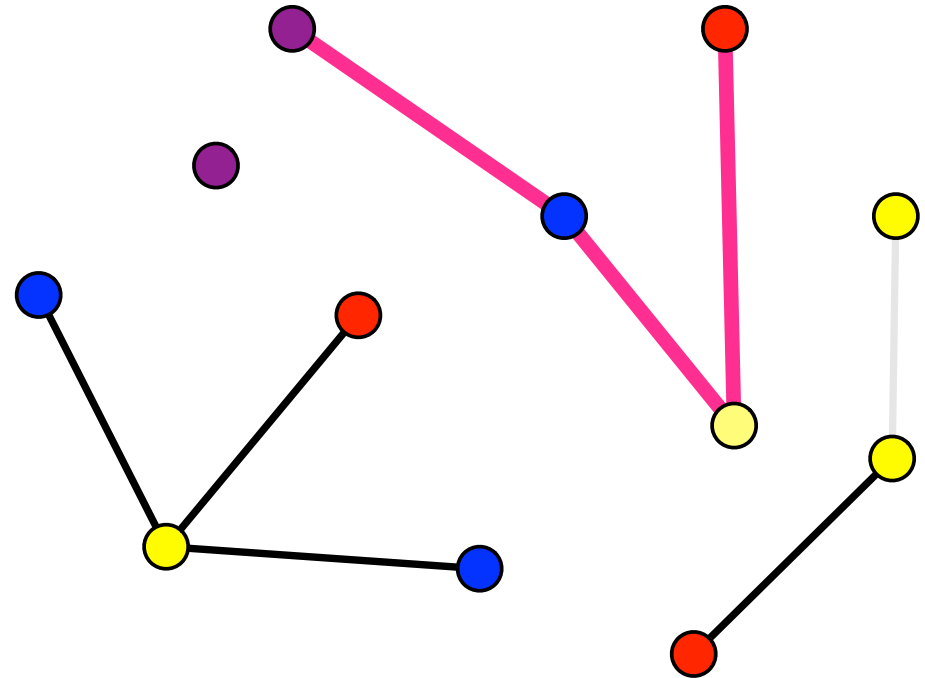


Application: Path detection


Does G contain  ?

Algorithm

- Randomly color vertices by $\{0, \dots, k\}$.
Discard badly colored edges.
(Hopefully a path is colored correctly.)



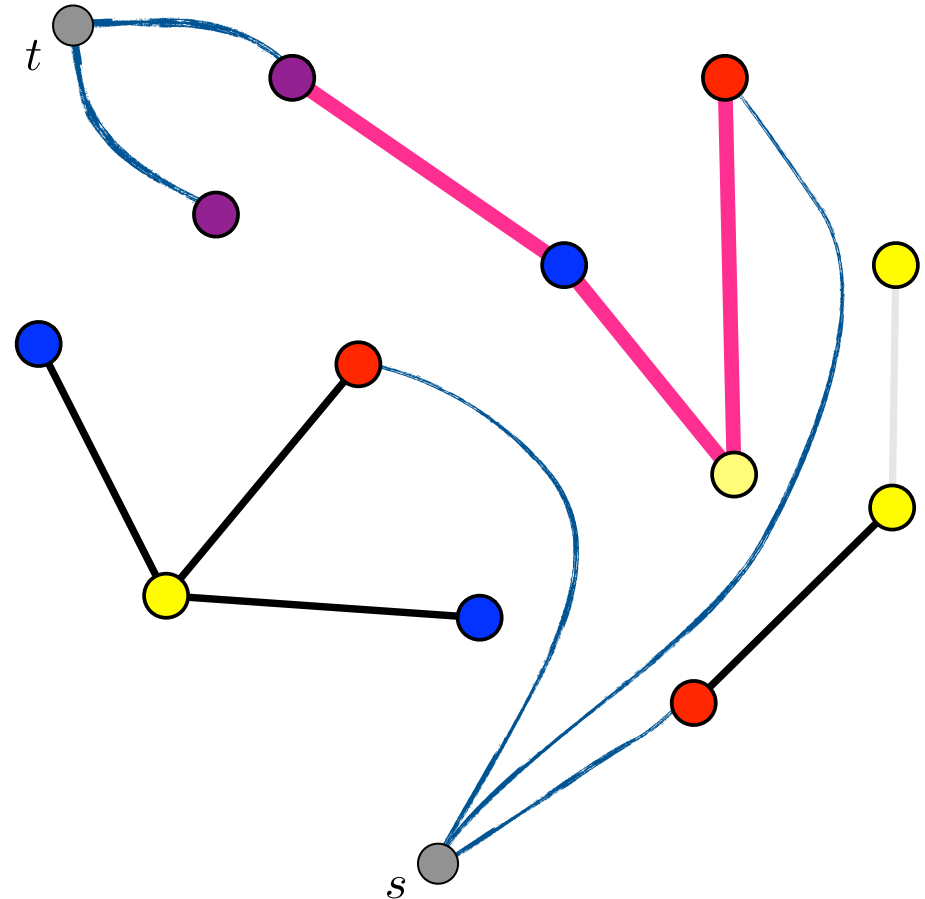
Application: Path detection

Does G contain  ?

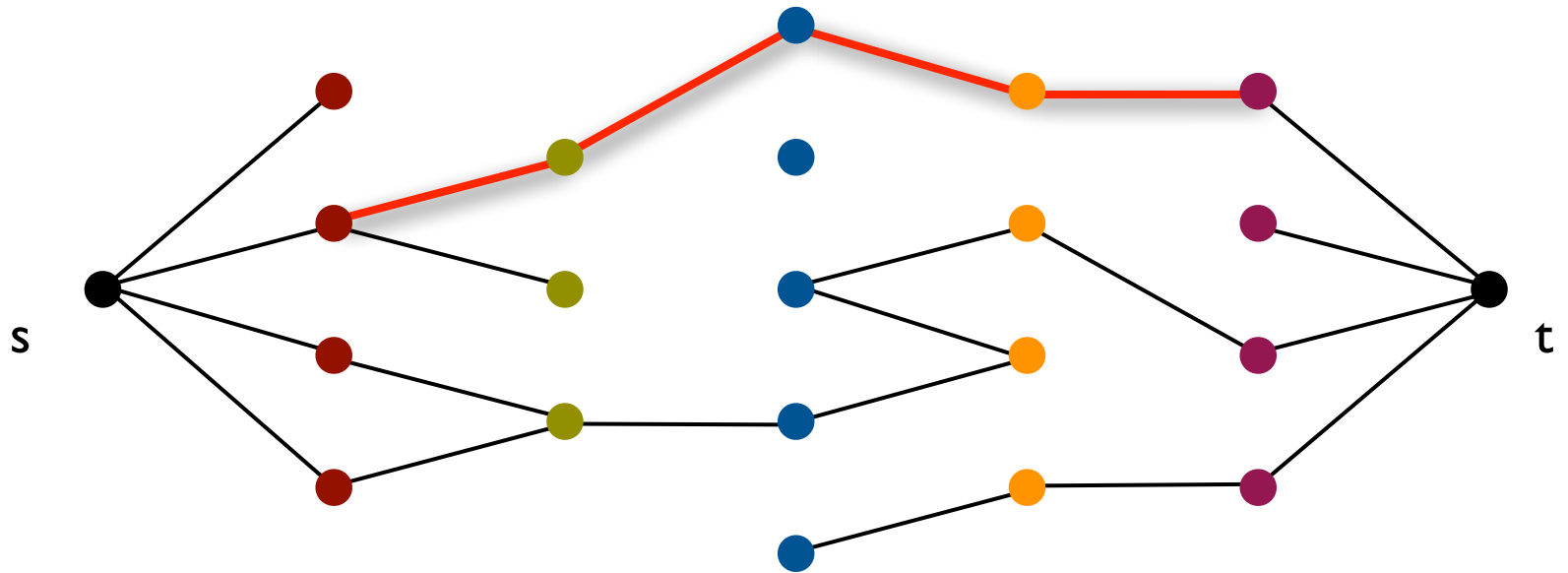
Algorithm

- Randomly color vertices by $\{0, \dots, k\}$.
Discard badly colored edges.
(Hopefully a path is colored correctly.)
- Attach s to color-0 vertices,
and t to color- k vertices.
- Run s - t connectivity.

$$O(n\sqrt{k+3}) = O(n)$$

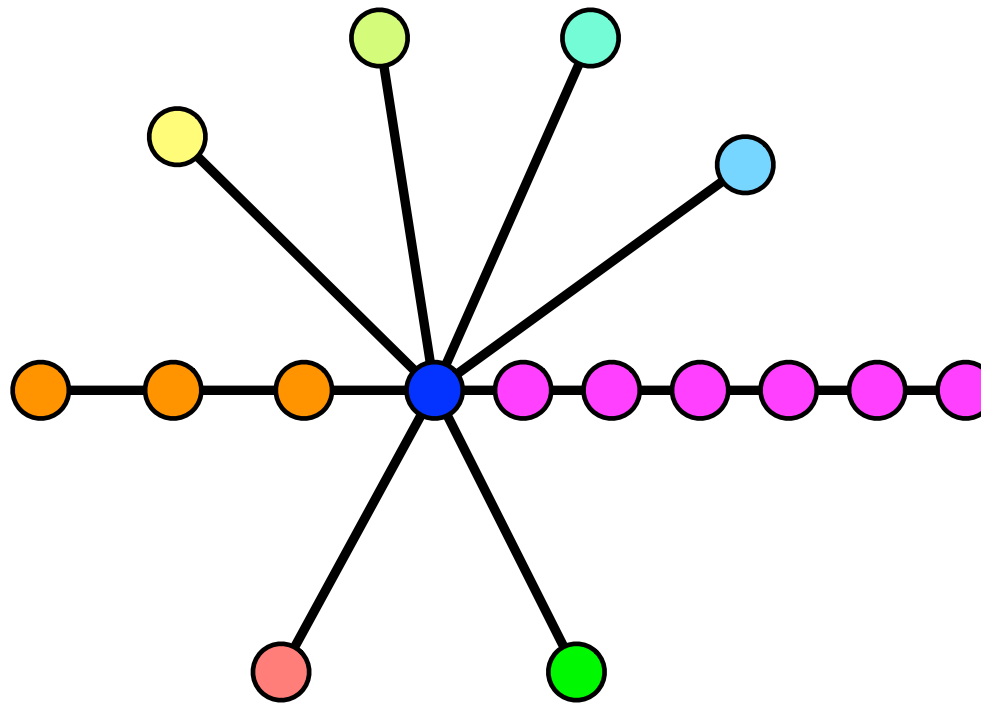


Application: Path detection
Does G contain a path of length k ?



Application: Subgraph detection

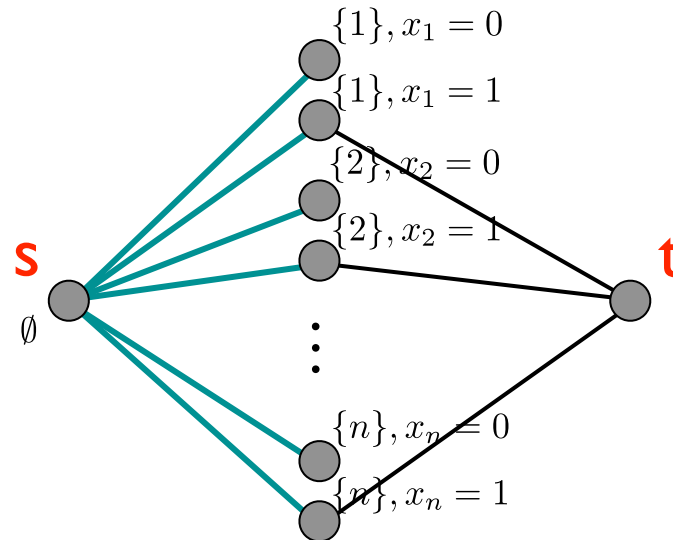
Star with two subdivided legs



Example application: Learning graphs

- Learning graphs (with input-independent weights) are a reduction to st -connectivity on graphs of a restricted form (not complete)

- Example: Grover search



- Complexity = $\sqrt{(\text{max cut size})} \sqrt{(\max_{\mathbf{x}} R_{st}(\mathbf{x}))}$

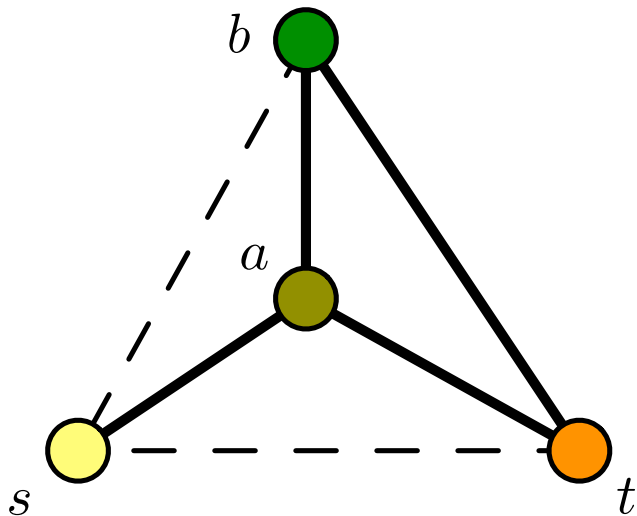
Span programs

- Span program $P =$
 - Target vector $|\tau\rangle$
 - Input vectors, each labeled by (index j , variable value b)
- $P(\mathbf{x}) := 1$ iff $|\tau\rangle$ can be reached using input vectors labeled by $(1, \mathbf{x}_1), \dots, (n, \mathbf{x}_n)$

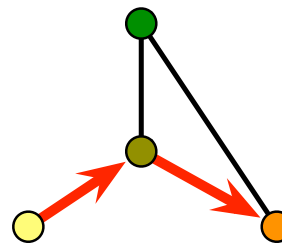
st -connectivity

- $|\tau\rangle = |t\rangle - |s\rangle \in \mathbf{R}^V$
- input vector $|u\rangle - |v\rangle$ labeled by $(A_G)[u,v] = 1$, i.e., the input vector can be used if the edge is present

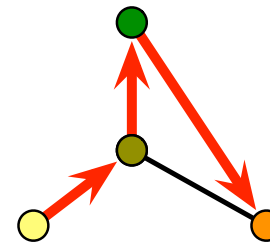
“Witnesses” to $P(\mathbf{x})=1 \Leftrightarrow$ balanced s - t flows



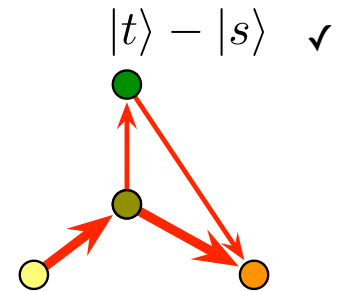
$$\begin{array}{r} |a\rangle - |s\rangle \\ + |t\rangle - |a\rangle \\ \hline |t\rangle - |s\rangle \end{array} \checkmark$$



$$\begin{array}{r} |a\rangle - |s\rangle \\ |b\rangle - |a\rangle \\ + |t\rangle - |b\rangle \\ \hline |t\rangle - |s\rangle \end{array} \checkmark$$



$$\begin{array}{r} |a\rangle - |s\rangle \\ \frac{1}{3}(|b\rangle - |a\rangle) \\ \frac{1}{3}(|t\rangle - |b\rangle) \\ + \frac{2}{3}(|t\rangle - |a\rangle) \\ \hline |t\rangle - |s\rangle \end{array} \checkmark$$

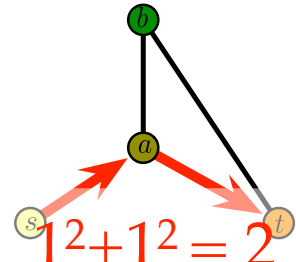
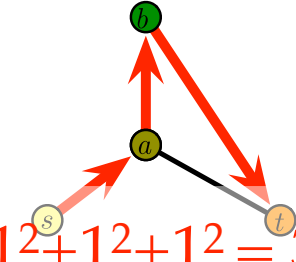


Witness size(P) = max_x wsize(P,x)

Case P(x)=I

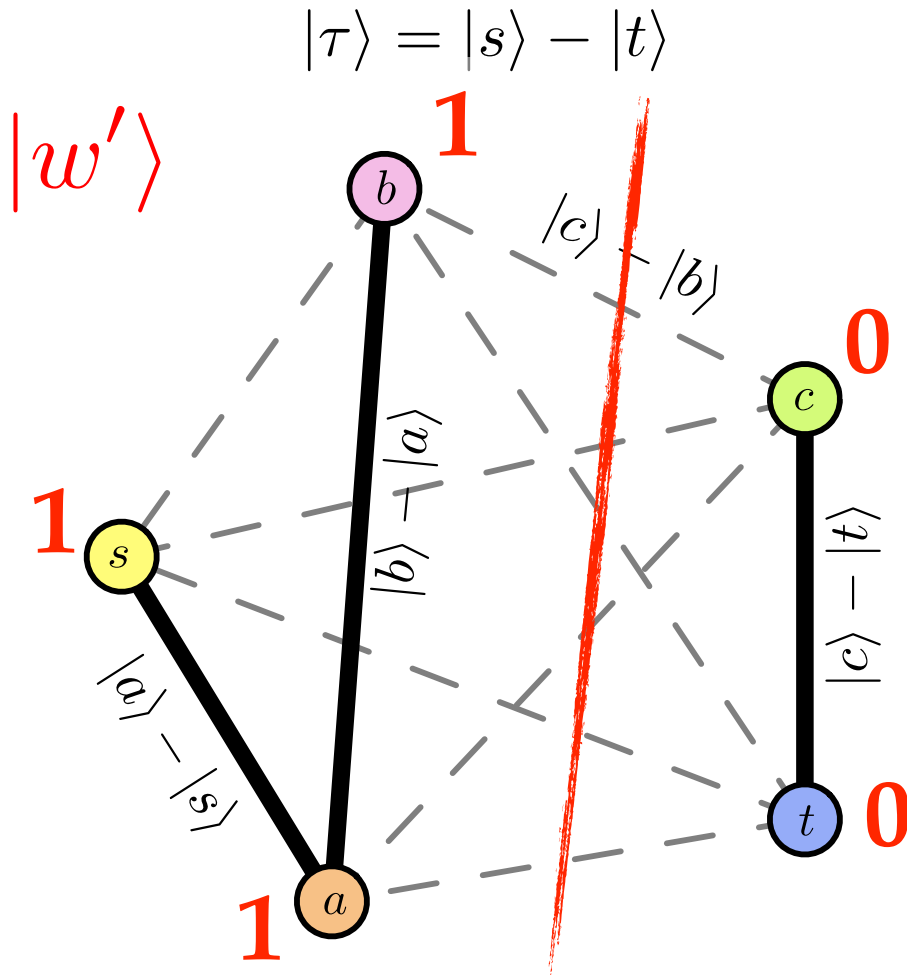
$$|\tau\rangle = \sum_{\substack{\text{available} \\ \text{input vectors } |v\rangle}} w_v |v\rangle$$

$$\text{wsize}(P, x) = \min \sum_v |w_v|^2$$

$\frac{ a\rangle - s\rangle + t\rangle - a\rangle}{ t\rangle - s\rangle} \quad \checkmark$	 <p style="color: red; font-weight: bold; font-size: 1.2em;">2</p>	$\frac{\begin{aligned} & a\rangle - s\rangle \\ &+ \frac{1}{3}(b\rangle - a\rangle) \\ &+ \frac{1}{3}(t\rangle - b\rangle) \\ &+ \frac{2}{3}(t\rangle - a\rangle) \end{aligned}}{ t\rangle - s\rangle} \quad \checkmark$ <p style="color: red; font-weight: bold; font-size: 1.2em;">1² + 1² = 2</p>
$\frac{ a\rangle - s\rangle + b\rangle - a\rangle + t\rangle - b\rangle}{ t\rangle - s\rangle} \quad \checkmark$	 <p style="color: red; font-weight: bold; font-size: 1.2em;">3</p>	$1^2 + \frac{1}{3}^2 + \frac{1}{3}^2 + \frac{2}{3}^2 = \frac{5}{3}$ <p style="color: red; font-weight: bold; font-size: 1.5em; border: 2px solid red; border-radius: 50%; padding: 5px; display: inline-block;">5/3</p>

wsize(P_{STCONN}, G) = R_{st}(G) ≤ d(s,t) ≤ n

Witness size(P) = max_x wsize(P,x)

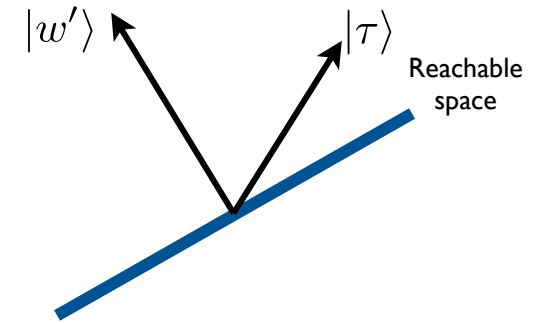


Case P(x)=0

$|\tau\rangle \notin \text{Span}(\text{available input vectors } |v\rangle)$

$\Rightarrow \exists |w'\rangle \perp \text{available vectors}$

$$\langle w' | \tau \rangle = 1$$



$$\text{wsize}(P, x) = \min \sum_v |\langle w' | v \rangle|^2$$

$$\text{wsize}(P_{\text{STCONN}}, G) = \text{cut size}(G) \leq n^2/4$$

Witness size(P) = \max_x wsize(P,x)

Case P(x)=1

$$|\tau\rangle = \sum_{\substack{\text{available} \\ \text{input vectors } |v\rangle}} w_v |v\rangle$$

$$\text{wsize}(P, x) = \min \sum_v |w_v|^2$$

Case P(x)=0

$$\Rightarrow \exists |w'\rangle \perp \text{available vectors} \\ \langle w' | \tau \rangle = 1$$

$$\text{wsize}(P, x) = \min \sum_v |\langle w' | v \rangle|^2$$

st-connectivity

s connected to t:

$$\text{wsize}(P_{\text{STCONN}}, G) = R_{\text{st}}(G) \leq d(s,t) \leq n$$

s not connected to t:

$$\text{wsize}(P_{\text{STCONN}}, G) \leq n^2$$

$$\text{Witness size}(P) = \sqrt{\max_{x: P(x)=1} \text{wsize}(P,x) \max_{x: P(x)=0} \text{wsize}(P,x)}$$

Case $P(x)=1$

$$|\tau\rangle = \sum_{\substack{\text{available} \\ \text{input vectors } |v\rangle}} w_v |v\rangle$$

$$\text{wsize}(P, x) = \min \sum_v |w_v|^2$$

Case $P(x)=0$

$$\Rightarrow \exists |w'\rangle \perp \text{available vectors} \\ \langle w' | \tau \rangle = 1$$

$$\text{wsize}(P, x) = \min \sum_v |\langle w' | v \rangle|^2$$

st-connectivity

s connected to t:

$$\text{wsize}(P_{\text{STCONN}}, G) = R_{\text{st}}(G) \leq d(s,t) \leq n$$

s not connected to t:

$$\text{wsize}(P_{\text{STCONN}}, G) \leq n^2$$

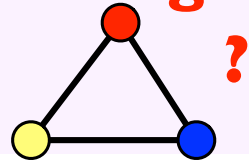
Theorem:

$$Q(f) = \Theta \left(\min_{P \text{ eval to } f} \text{wsize}(P) \right)$$

space: # qubits = $\log(\# \text{ input vectors})$

Application?: Triangle detection

Does G contain

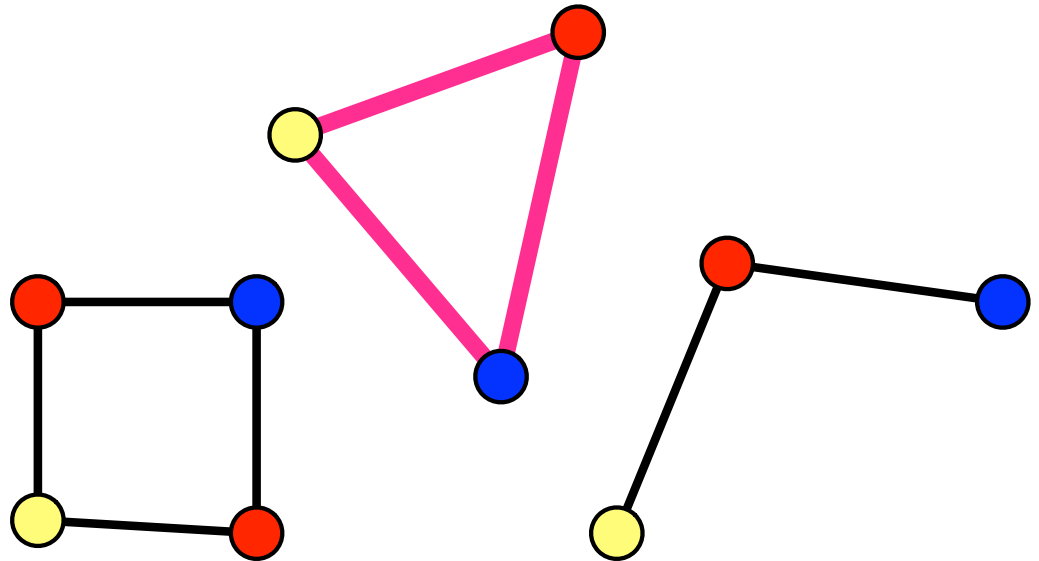


Algorithm?

- Randomly color vertices. Split yellow vertices in two. Keep only edges

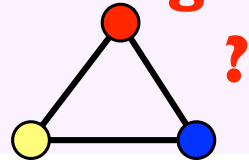


- Attach s to vertices (1),
t to vertices (2)
- Run s-t connectivity.



Application?: Triangle detection

Does G contain

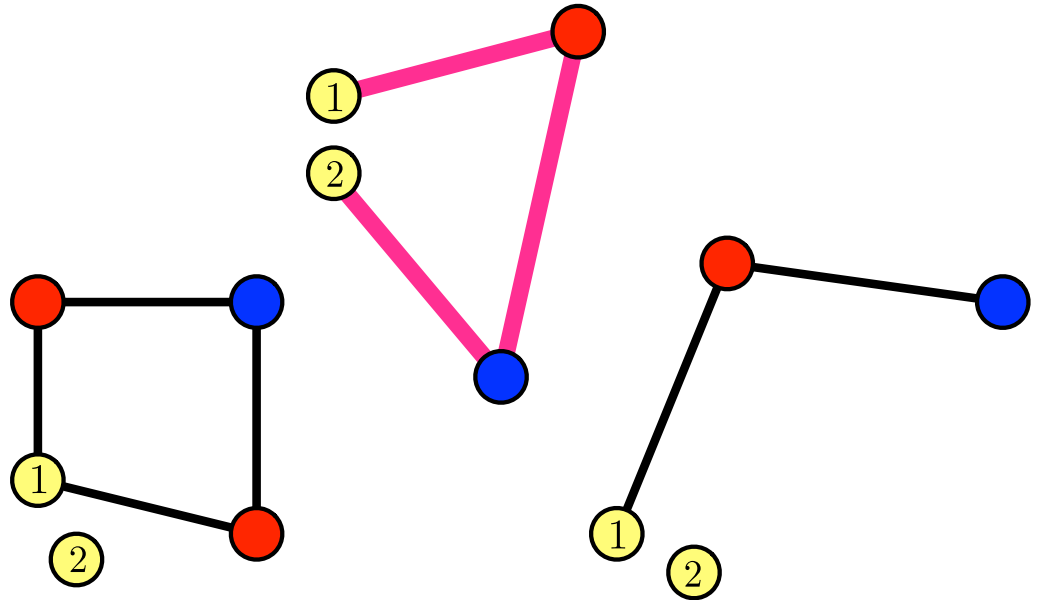


Algorithm?

- Randomly color vertices. Split yellow vertices in two. Keep only edges

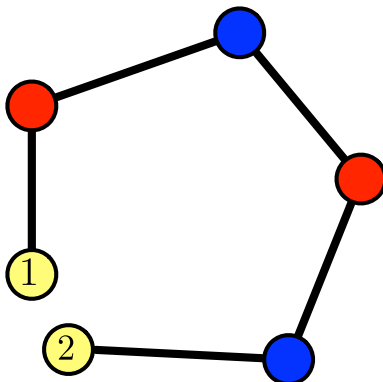


- Attach s to vertices ①, t to vertices ②
- Run s-t connectivity.

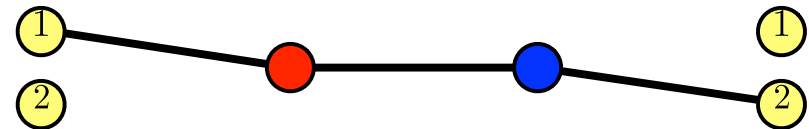


It doesn't work! It correctly detects triangles, but also:

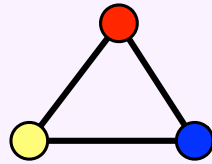
Odd cycles (triangle is a minor)



Paths (first & last vertices needn't match)






We'll fix this...



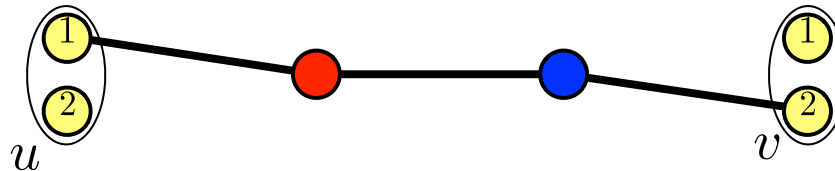
detection

Algorithm

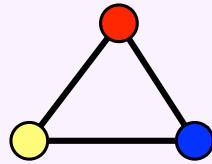
- Randomly color vertices. Split yellow vertices.
Keep edges 
- Attach s to vertices , t to vertices 
- Run s - t connectivity with breadcrumbs

$$|u, 1\rangle - |s\rangle + |\text{crumb } u\rangle$$

$$|t\rangle - |u, 2\rangle - |\text{crumb } u\rangle$$



$$|t\rangle - |s\rangle + |\text{crumb } u\rangle - |\text{crumb } v\rangle \neq |\tau\rangle$$



detection

Algorithm

- Randomly color vertices. Split yellow vertices. Keep edges
- Attach s to vertices , t to vertices
- Run s - t connectivity with breadcrumbs

$$|u, 1\rangle - |s\rangle + |\text{crumb } u\rangle$$

$$|t\rangle - |u, 2\rangle - |\text{crumb } u\rangle$$

Witness size G contains : $wsize = |^2 + |^2 + |^2 = O(I)$

G does not contain minor $\Rightarrow G$ acyclic $\Rightarrow G$ a forest:

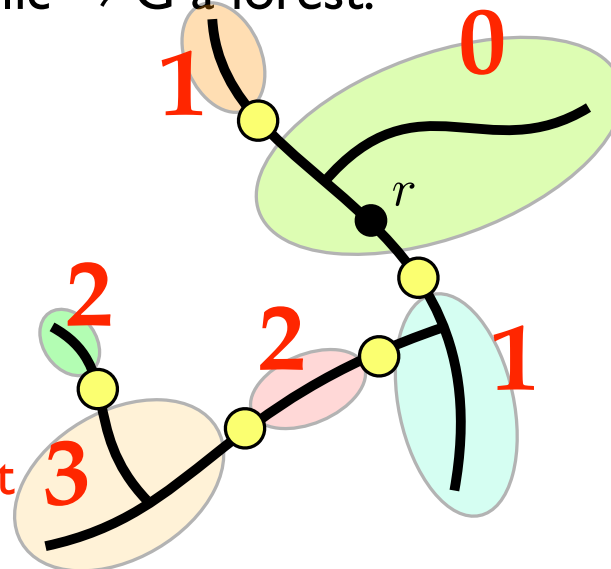
$$\text{Set } \langle s | w' \rangle = 1, \langle t | w' \rangle = 0 \Rightarrow \langle \tau | w' \rangle = 1 \checkmark$$

Across edges , set $\langle u | w' \rangle = \langle v | w' \rangle$

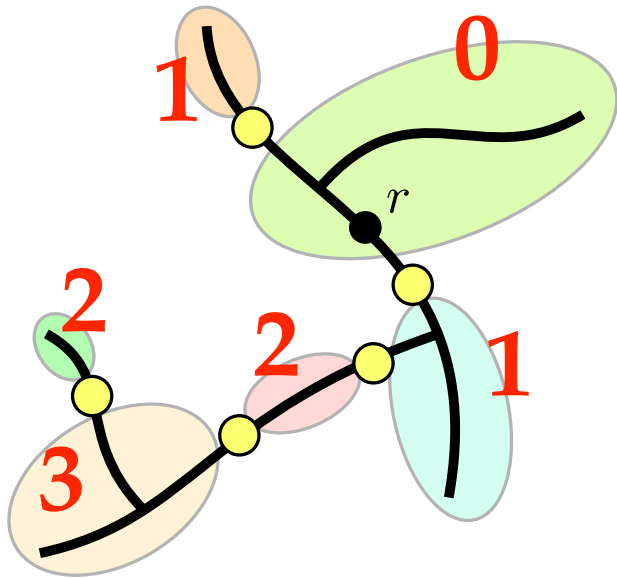
$$\text{Set } \langle \text{crumb } u | w' \rangle = -\langle u, 2 | w' \rangle$$

$$\langle u, 1 | w' \rangle = 1 + \langle u, 2 | w' \rangle$$

to fix all coefficients up to additive constant



Witness size (acyclic case)



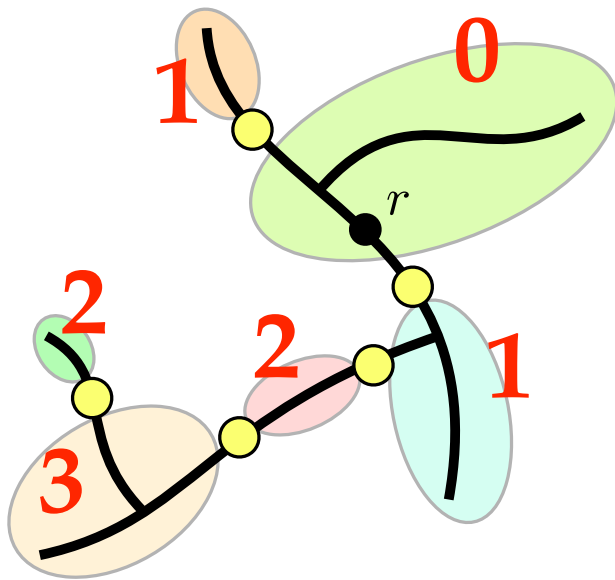
$$\text{wsize} = \min_{\text{witnesses } |w'\rangle} \sum_{\text{input vectors } |v\rangle} |\langle w'|v\rangle|^2$$

$$\leq n^2 \cdot \max_v |\langle v|w'\rangle|^2 \leq n^4$$

input
vectors

No good

Witness size (acyclic case)



$$\begin{aligned} \text{wsize} &= \min_{\text{witnesses } |w'\rangle} \sum_{\text{input vectors } |v\rangle} |\langle w'|v\rangle|^2 \\ &\leq \sum_{\text{vertices } u} |\langle u|w'\rangle|^2 \cdot n \\ &\quad \text{\# input vectors incident to } u \end{aligned}$$

Discarding edges 

⇒ Each edge removed with probability $1/3$

$$\Rightarrow \mathbb{E}_{\text{random coloring}}[\text{wsize}] \leq \sum_{\text{vertices } u} \left(\sum_{j=1}^{\infty} j^2 (2/3)^j \right) \cdot n = O(n^2)$$

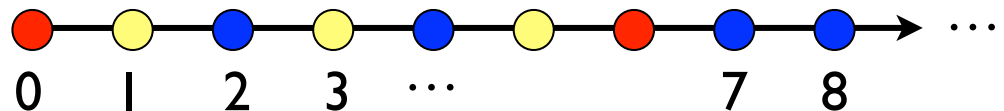
Theorem: There exists an $O(n)$ -query quantum algorithm that distinguishes between:

- graphs containing a triangle subgraph, and
- graphs that do not contain a triangle as a minor.

Space complexity

- Algorithms need to look up the color of a vertex
- For detecting a length- k path P_{k+1} , $(k+1)$ -wise independence of the coloring suffices
⇒ $\log(n)$ space for the hash function
- But analysis for triangle-detection algorithm requires full independence
⇒ $\Theta(n)$ space of quantum RAM

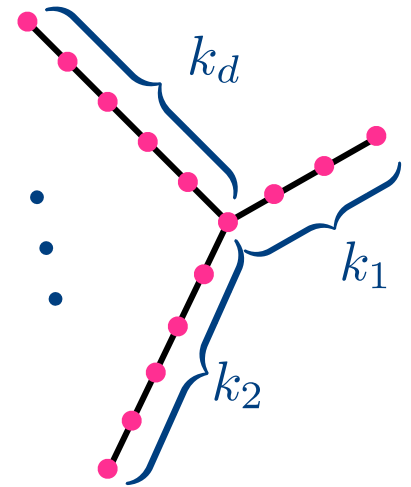
$$\mathbb{E}_{\text{random coloring}}[\text{wsize}] \leq \sum_{\text{vertices } u} \underbrace{\left(\sum_{j=1}^{\infty} j^2 (2/3)^j \right)}_{\mathbb{E}[(\text{distance from 0 before two vertices are given same color})^2]} \cdot n = O(n^2)$$



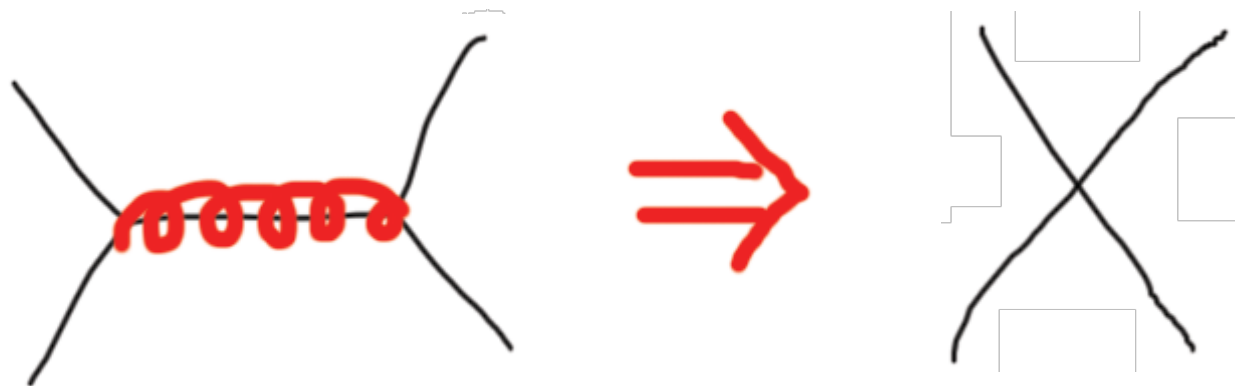
Subdivided stars

Theorem: For any fixed k_1, \dots, k_d , there exists an $O(n)$ -query quantum algorithm that distinguishes between:

- graphs containing a $\{k_1, \dots, k_d\}$ subdivided star, and
- graphs not containing said subdivided star as a minor.



Corollary: $O(n)$ -query quantum algorithm for detecting $\{k_1, k_2, k_3\}$ subdivided star (“claw”).

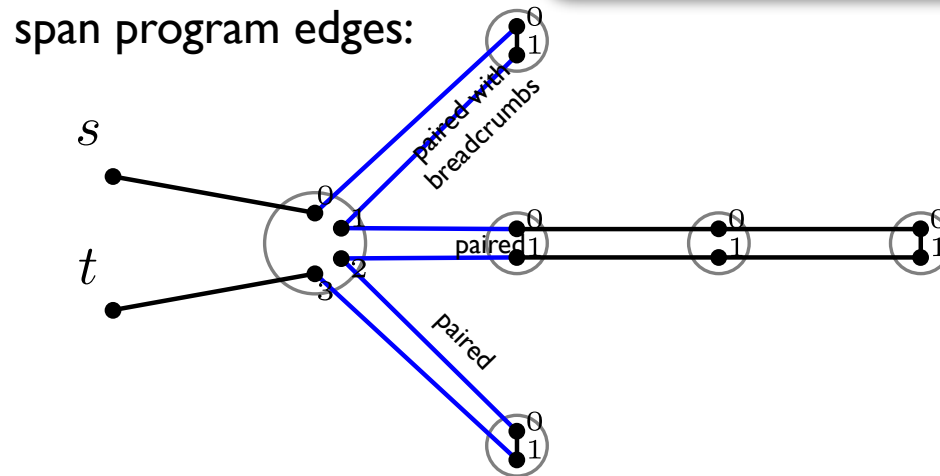
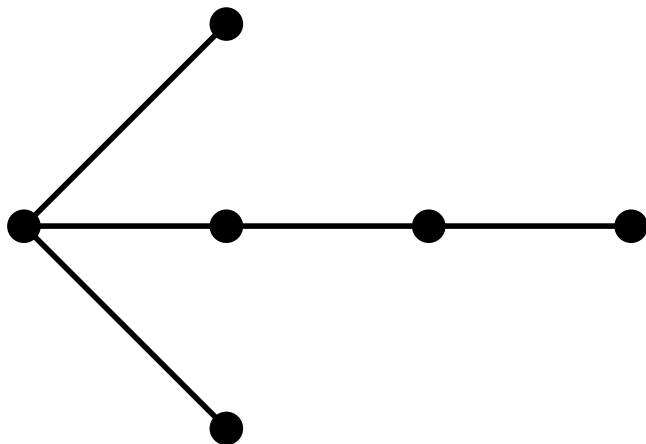


Subdivided star subgraph/not-a-minor problem

Algorithm

- Randomly color vertices of G by vertices of subdivided star. Keep only correctly colored edges.
- Evaluate the span program for s - t connectivity with breadcrumbs...

Example: $G=T$



Idea: s - t path traverses the subdivided star, out and back each leg.
Paired edges force path to use same return edge.

Open problems:

- Does the same algorithm work for any trees/forests?
- Characterize for what graphs breadcrumb trick works.
- Is the query complexity of the subgraph/not-a-minor problem always $O(n)$?

Time-efficient implementations

Span-program evaluation algorithm

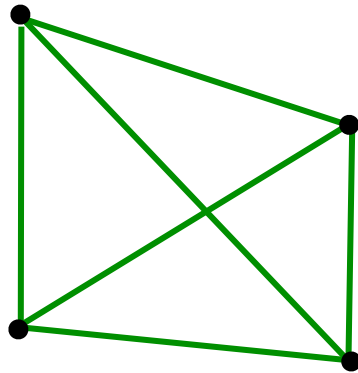
Run phase estimation on

$$\mathcal{O}_x \cdot \text{Ref} \left(\text{Ker} \left(\begin{array}{c|c} \text{target} & \\ \text{vector} & \\ \hline \text{input} & \\ \text{vectors} & \end{array} \right) \right)$$

st-connectivity

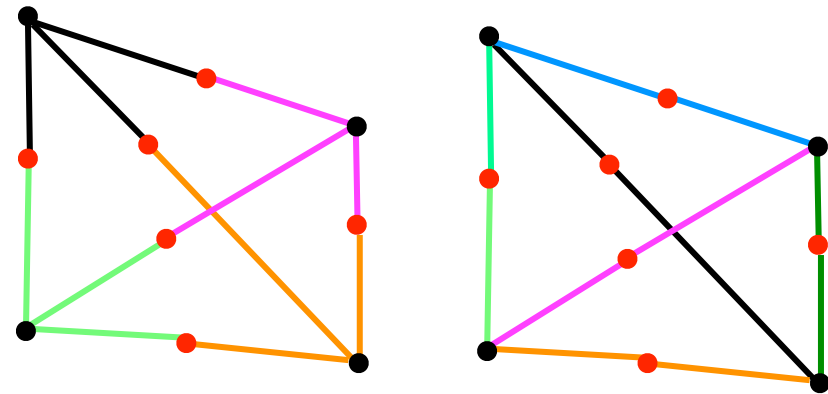
$$\text{Ker} \begin{pmatrix} 1 & & 1 & & \\ -1 & 1 & & & \\ & -1 & -1 & \dots & \end{pmatrix} = \{\text{balanced flows in } K_n\}$$

Implementing the reflection about the set of balanced flows in K_n



1. Factor the solution

- into constraints on original vertices & on edge vertices—now commuting



2. Use phase estimation to **isolate** the $+1$ eigenspace, reflect, uncompute

Open problems

- Is $O(n\sqrt{d})$ promise st-connectivity query complexity optimal?
- Efficient implementations of learning graphs
- Combine learning graphs with breadcrumb trick
- Connection to quantum walks
- Algorithms based on the superposition over the electrical flow
—are exponential speedups possible?