

Hierarchical Models

Projections and Shadows
Hierarchical Models
[Angel Ch. 8]

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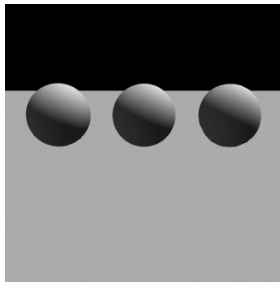
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Roadmap

- Last lecture: Viewing and projection
- Today:
 - Shadows via projections
 - Hierarchical models
- Next: Polygonal Meshes, Curves and Surfaces
- Goal: background for Assignment 2 (next week)

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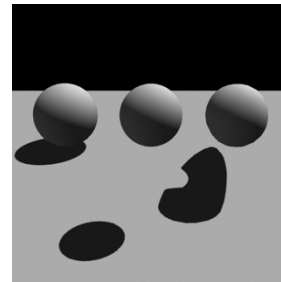
Importance of shadows



Source: UNC

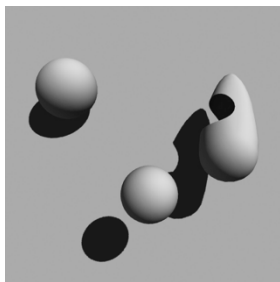
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Importance of shadows



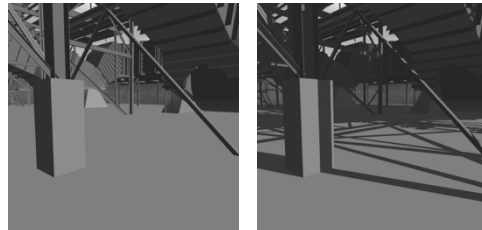
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Importance of shadows



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Importance of shadows



Without shadows

With shadows

Source: UNC

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Doom III

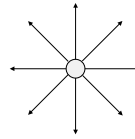


Source: Wikipedia

Reported to spend 50% of time rendering shadows!

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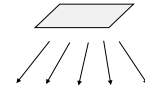
Light sources



point light source



directional light source



area light source

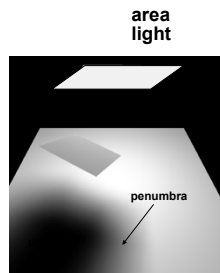
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Hard and soft shadows



Source: UNC

Hard shadow



Soft shadow

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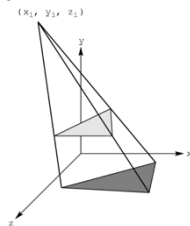
Shadow Algorithms

- With visibility tests
 - Accurate yet expensive
 - Example: ray casting or ray tracing
 - Example: 2-pass z-buffer [Foley, Ch. 16.4.4] [RTR 6.12]
- Without visibility tests (“fake” shadows)
 - Approximate and inexpensive
 - Using a model-view matrix “trick”

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Shadows via Projection

- Assume light source at $[x_l, y_l, z_l]^T$
- Assume shadow on plane $y = 0$
- Viewing = shadow projection
 - Center of projection = light
 - Viewing plane = shadow plane
- View plane in front of object
- Shadow plane behind object



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Shadow Projection Strategy

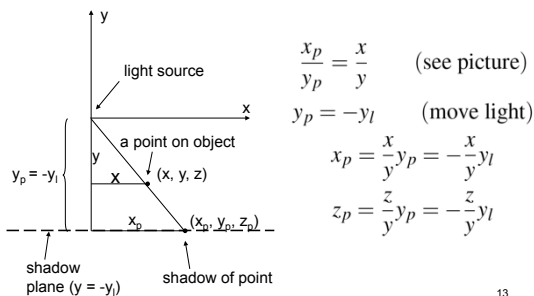
- Move light source to origin
- Apply appropriate projection matrix
- Move light source back
- Instance of general strategy: compose complex transformation from simpler ones!

$$T = \begin{bmatrix} 1 & 0 & 0 & -x_l \\ 0 & 1 & 0 & -y_l \\ 0 & 0 & 1 & -z_l \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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Derive Equation

- Now, light source at origin



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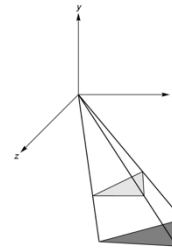
Light Source at Origin

- After translation, solve

$$M \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = w \begin{bmatrix} -\frac{x y_l}{y} \\ -y_l \\ -\frac{z y_l}{y} \\ 1 \end{bmatrix}$$

- w can be chosen freely
- Use w = -y / y_l

$$M \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \\ -\frac{y}{y_l} \end{bmatrix}$$



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Shadow Projection Matrix

- Solution of previous equation

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -\frac{1}{y_l} & 0 & 0 \end{bmatrix}$$

- Total shadow projection matrix

$$S = T^{-1} M T = \dots$$

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Implementation

- Recall column-major form

```
GLfloat m[16] =
{1.0, 0.0, 0.0, 0.0,
 0.0, 1.0, 0.0, -1.0 / y_l,
 0.0, 0.0, 1.0, 0.0,
 0.0, 0.0, 0.0, 0.0};
```

- y_l is light source height
- Assume drawPolygon(); draws object

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Saving the ModelView Matrix State

- Assume xl, yl, zl hold light coordinates
- Core OpenGL code (compatibility code is similar)

```
openGLMatrix->MatrixMode(OpenGLMatrix::ModelView);
// here, set the model view matrix, in the usual way
// ...

drawPolygon(); // draw normally
openGLMatrix->PushMatrix(); // save current matrix
openGLMatrix->Translate(xl, yl, zl); // translate back
openGLMatrix->MultMatrix(m); // project
openGLMatrix->Translate(-xl, -yl, -zl); // move light to origin

float ms[16];
openGLMatrix->GetMatrix(ms); // read the shadow matrix
```

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Saving the ModelView Matrix State (cont.)

```
// upload the shadow matrix to the GPU
glUniformMatrix4fv(h_modelViewMatrix, 1, GL_FALSE, ms);

drawPolygon(); // draw polygon again for shadow

// restore original modelview matrix
openGLMatrix->PopMatrix();
openGLMatrix->GetMatrix(ms);
glUniformMatrix4fv(h_modelViewMatrix, 1, GL_FALSE, ms);

// continue rendering more objects, as usual ...
```

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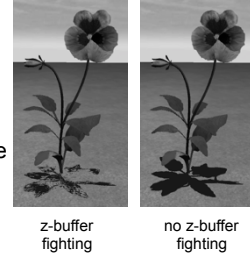
The Matrix and Attribute Stacks

- Mechanism to save and restore state
 - {OpenGLMatrix::, gl}PushMatrix();
 - {OpenGLMatrix::, gl}PopMatrix();
- Apply to current matrix
- In compatibility profile, can also save current attribute values
 - Examples: color, lighting
 - glPushAttrib(GLbitfield mask);
 - glPopAttrib();
 - Mask determines which attributes are saved
 - This feature has been removed in the core profile

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Drawing on a Surface

- Shimmering (“z-buffer fighting”) when drawing shadow on surface
- Due to limited precision of depth buffer
- Solution: slightly displace either the surface or the shadow (glPolygonOffset in OpenGL)

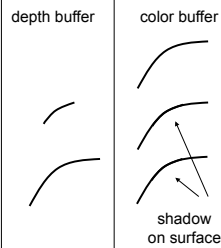


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Drawing on a Surface

Or use general technique

1. Set depth buffer to read-only, draw surface
2. Set depth buffer to read-write, draw shadow
3. Set color buffer to read-only, draw surface again
4. Set color buffer to read-write



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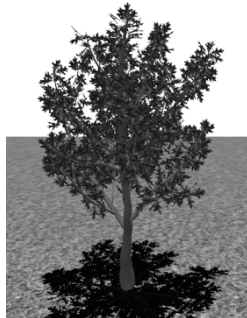
Outline

- Projections and Shadows
- Hierarchical Models

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Hierarchical Models

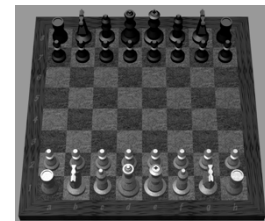
- Many graphical objects are structured
- Exploit structure for
 - Efficient rendering
 - Example: tree leaves
 - Concise specification of model parameters
 - Example: joint angles
 - Physical realism
- Structure often naturally hierarchical



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Instance Transformation

- Often we need several instances of an object
 - Wheels of a car
 - Arms or legs of a figure
 - Chess pieces



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Instance Transformation

- Instances can be shared across space or time
- Write a function that renders the object in “standard” configuration
- Apply transformations to different instances
- Typical order: scaling, rotation, translation

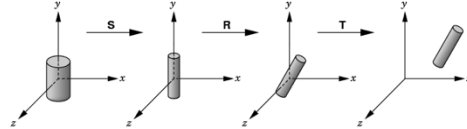


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Sample Instance Transformation

```

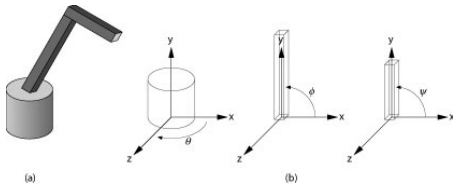
openGLMatrix->MatrixMode(OpenGLMatrix::ModelView);
openGLMatrix->LoadIdentity();
openGLMatrix->Translate(...);
openGLMatrix->Rotate(...);
openGLMatrix->Scale(...);
// ... upload modelview matrix to GPU, as usual ...
renderCylinder(...);
    
```



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Drawing a Compound Object

- Example: simple “robot arm”

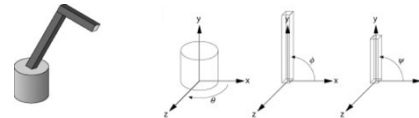


Base rotation θ , arm angle ϕ , joint angle ψ

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Hierarchical Objects and Animation

- Drawing functions are time-invariant and draw the object in a canonical position:
drawBase(); drawLowerArm(); drawUpperArm();
- Can be easily stored in a VBO
- Change parameters of model with time



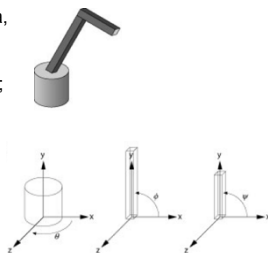
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Interleave Drawing & Transformation

- h_1 = height of base, h_2 = length of lower arm
- This is pseudocode (must upload matrix to GPU)

```

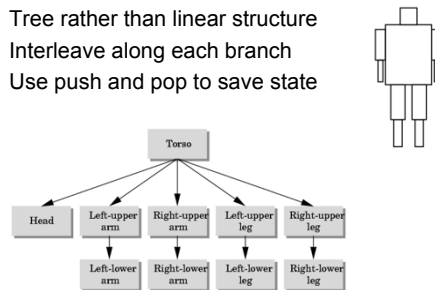
void drawRobot(GLfloat theta,
              GLfloat phi, GLfloat psi)
{
    Rotate(theta, 0.0, 1.0, 0.0);
    drawBase();
    Translate(0.0, h1, 0.0);
    Rotate(phi, 0.0, 0.0, 1.0);
    drawLowerArm();
    Translate(0.0, h2, 0.0);
    Rotate(psi, 0.0, 0.0, 1.0);
    drawUpperArm();
}
    
```



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More Complex Objects

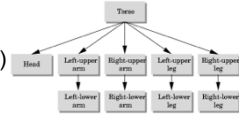
- Tree rather than linear structure
- Interleave along each branch
- Use push and pop to save state



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Hierarchical Tree Traversal

- Order not necessarily fixed (breadth-first, depth-first, etc.)
- Example:



```
void drawFigure()
{
    PushMatrix(); // save          Translate(...);
    drawTorso();                 Rotate(...);
    Translate(...); // move head drawLeftUpperArm();
    Rotate(...); // rotate head Translate(...)
    drawHead();                 Rotate(...)
    PopMatrix(); // restore      drawLeftLowerArm();
    PushMatrix();               PopMatrix();
    ... }

```

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Using Tree Data Structures

- Can make tree form explicit in data structure

```
typedef struct treenode
{
    GLfloat m[16];
    void (*render) ( );
    struct treenode *sibling;
    struct treenode *child;
} treenode;
```

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Initializing Tree Data Structure

- Initializing transformation matrix for node


```
treenode torso, head, ...;
// in init function
LoadIdentity();
Rotate(...);
GetMatrix(torso.m);
```
- Initializing pointers


```
torso.render = drawTorso;
torso.sibling = NULL;
torso.child = &head;
```

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Generic Traversal: Recursion

```
void traverse (treenode *root)
{
    if (root == NULL)
        return;
    PushMatrix();
    MultMatrix(root->m);
    root->render();
    if (root->child != NULL)
        traverse(root->child);
    PopMatrix();
    if (root->sibling != NULL)
        traverse(root->sibling);
}
```

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Summary

- Projections and Shadows
- Hierarchical Models

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Notes

- Next lecture: polygonal meshes, curves and surfaces
- Assignment 1 is due in one week

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