

CSCI 420 Computer Graphics  
Lecture 4

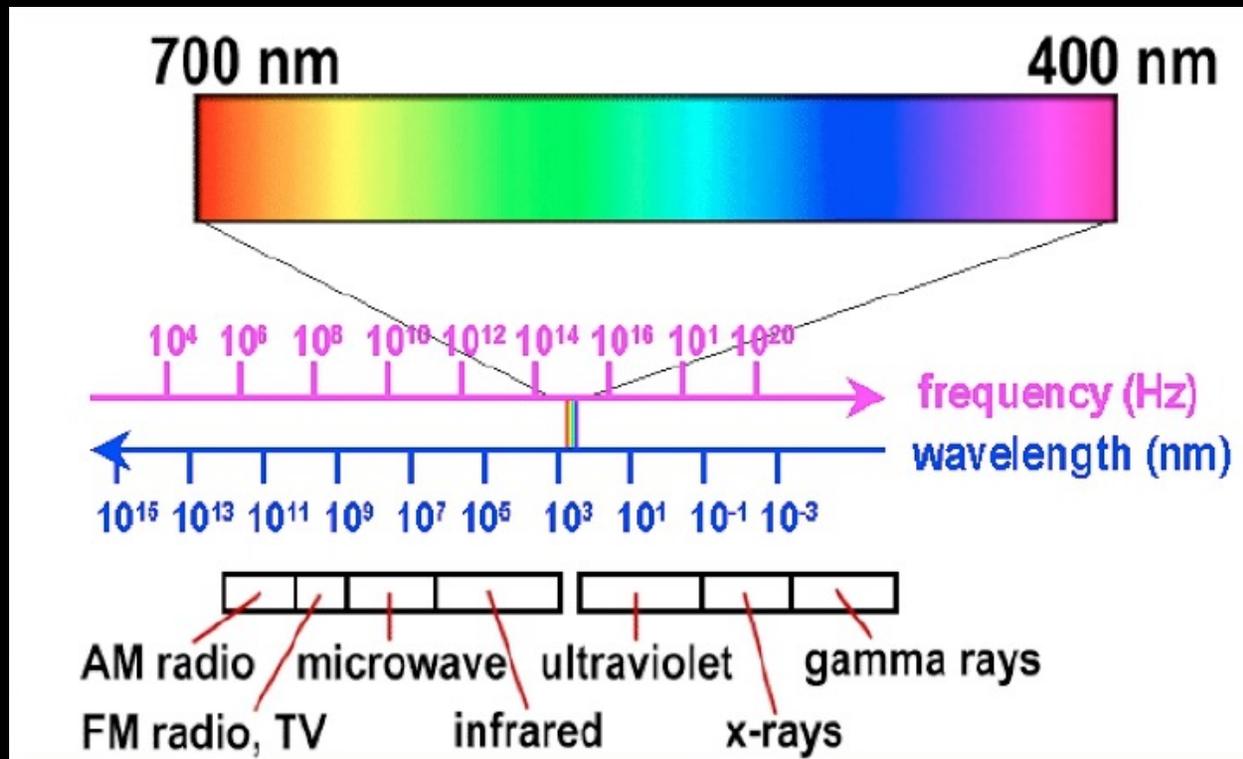
# Color and Hidden Surface Removal

Client/Server Model  
Callbacks  
Double Buffering  
Physics of Color  
Flat vs Smooth Shading  
Hidden Surface Removal  
[Angel Ch. 2]

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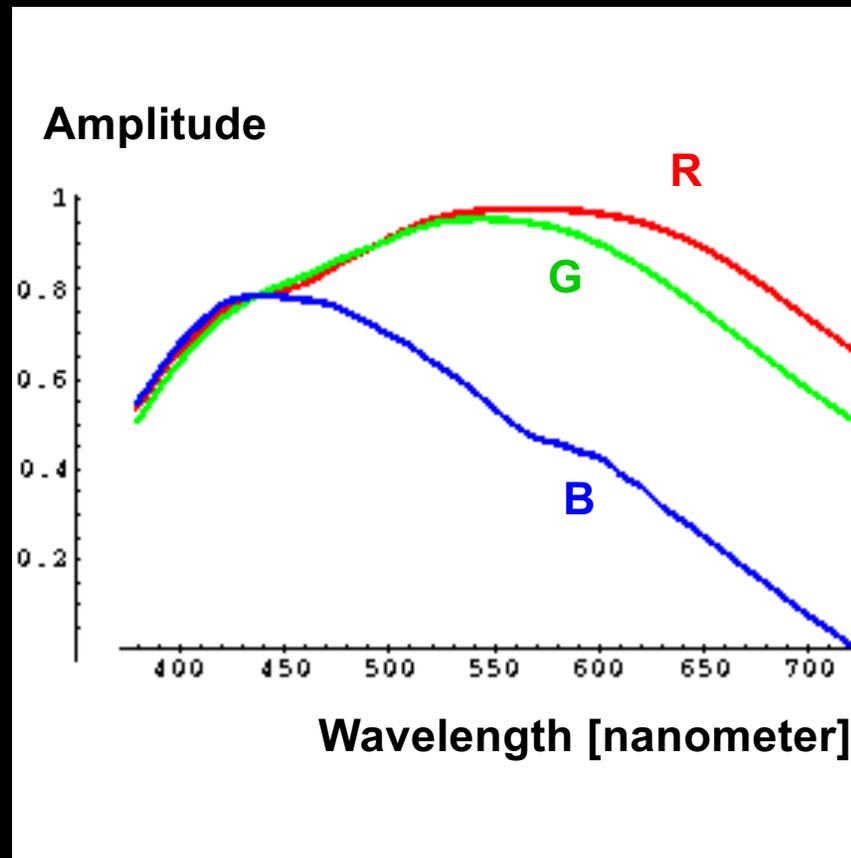
# Physics of Color

- Electromagnetic radiation
- Can see only a tiny piece of the spectrum



# Color Filters

- Eye can perceive only 3 basic colors
- Computer screens designed accordingly



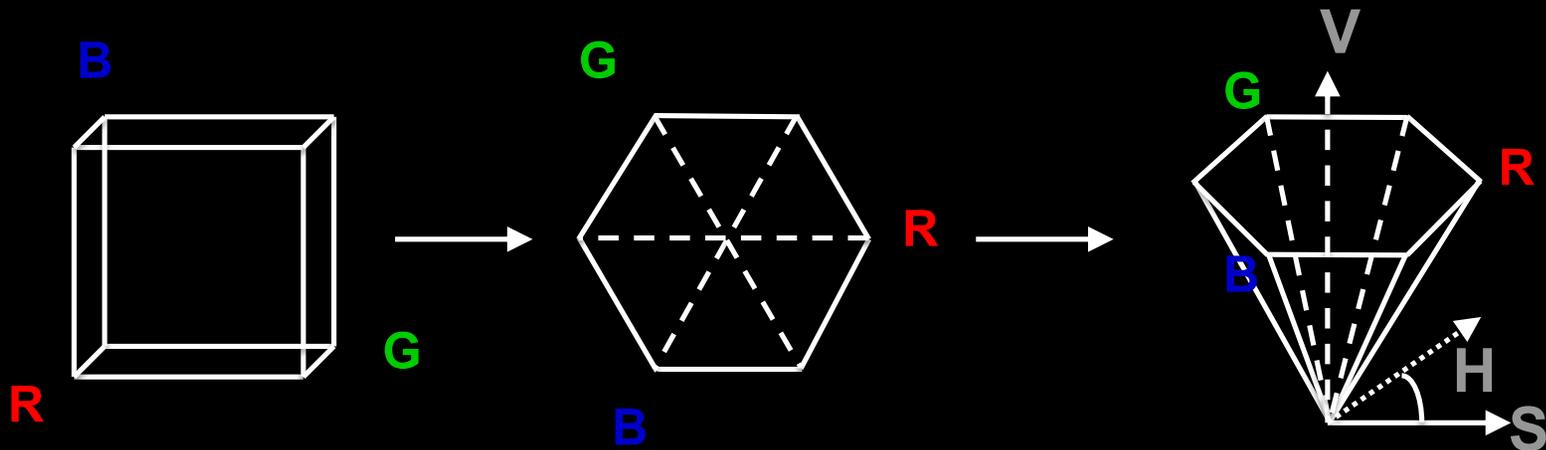
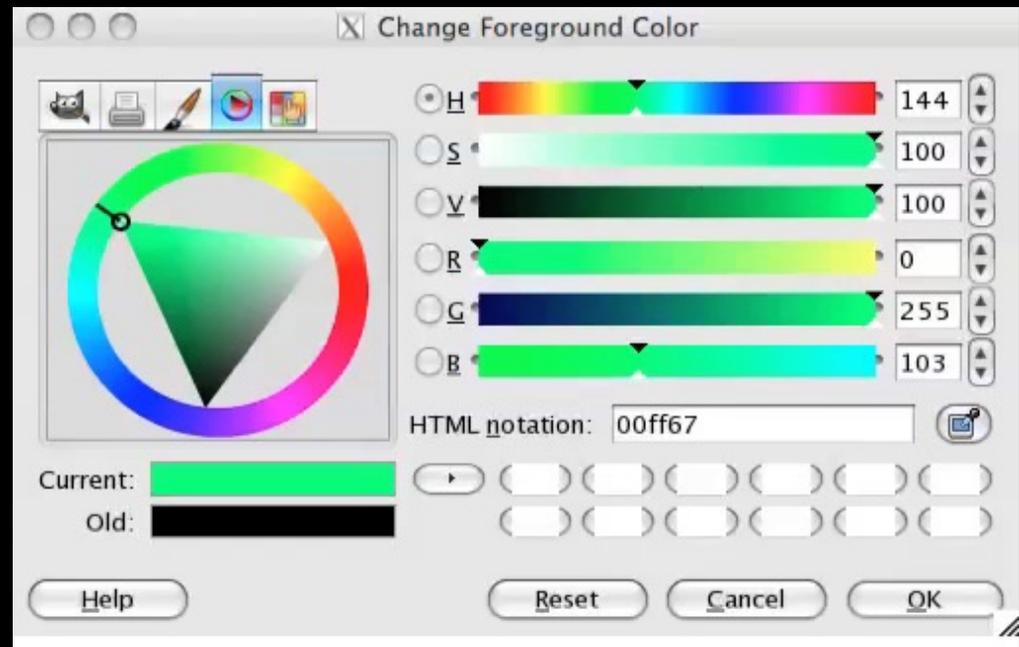
Source: Vos & Walraven

# Color Spaces

- RGB (Red, Green, Blue)
  - Convenient for display
  - Can be unintuitive (3 floats in OpenGL)
- HSV (Hue, Saturation, Value)
  - Hue: what color
  - Saturation: how far away from gray
  - Value: how bright
- Other formats for movies and printing

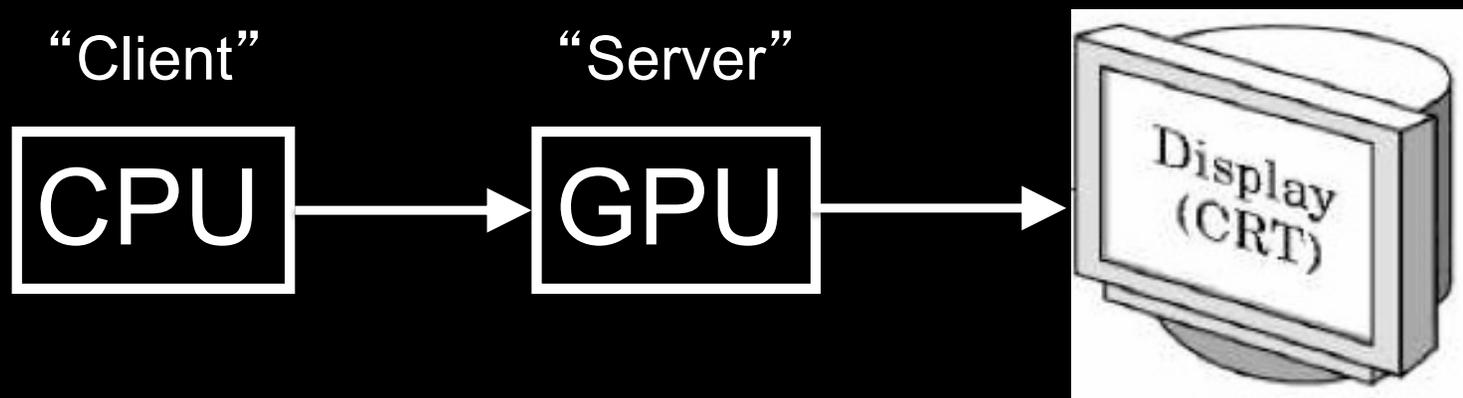
# RGB vs HSV

Gimp Color Picker



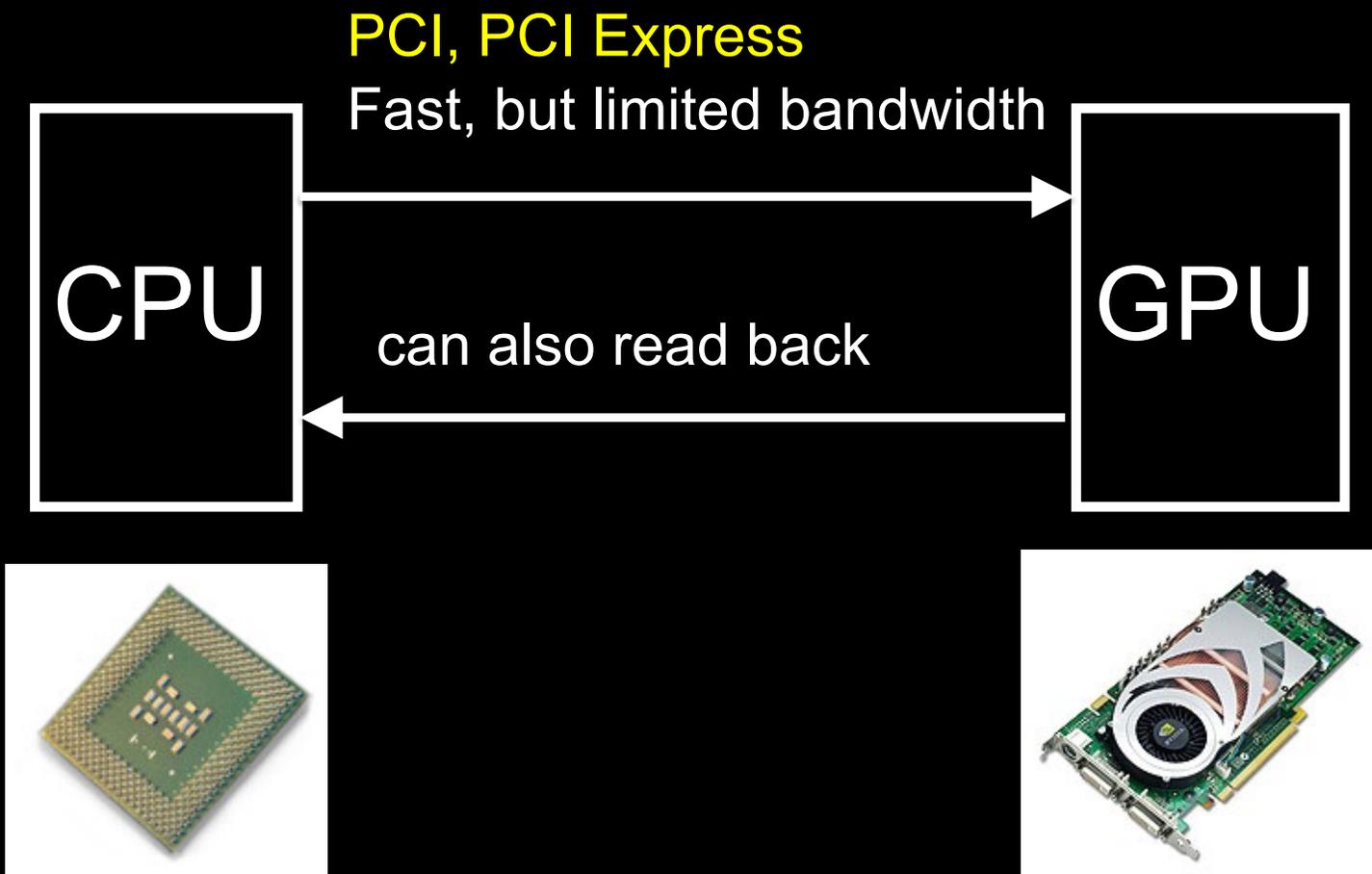
# Client/Server Model

- Graphics hardware and caching



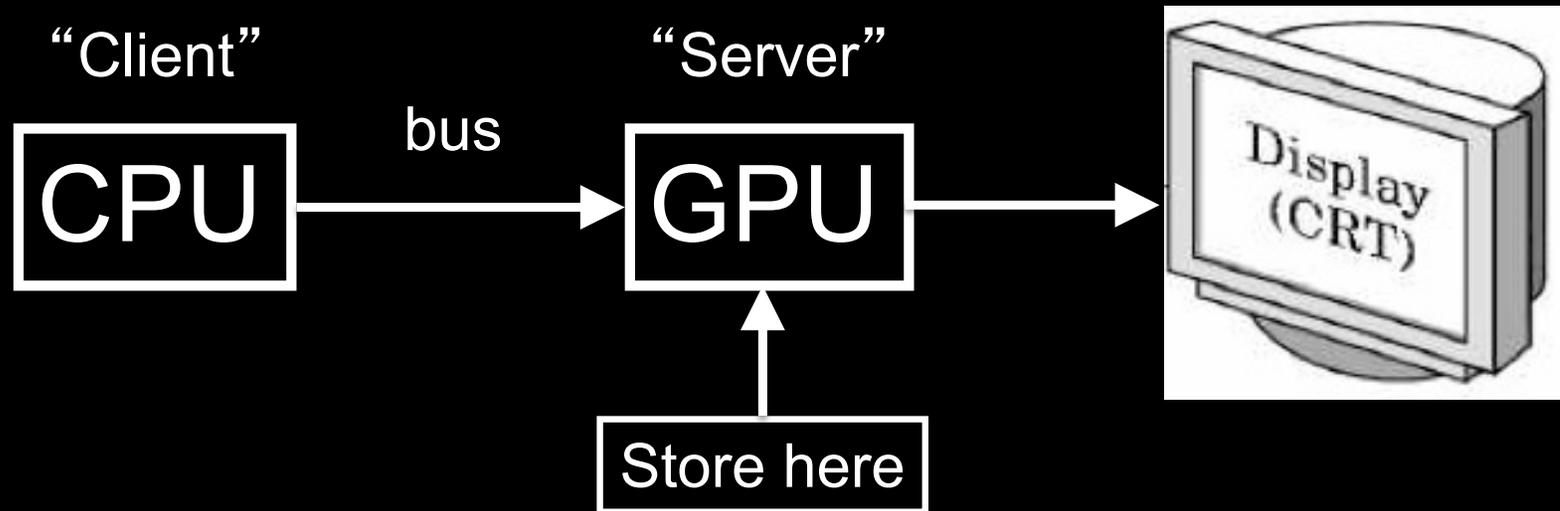
- Important for efficiency
- Need to be aware where data are stored
- Graphics driver code is on the CPU
- Rendering resources (buffers, shaders, textures, etc.) are on the GPU

# The CPU-GPU bus



# Buffer Objects

- Store rendering data: vertex positions, normals, texture coordinates, colors, vertex indices, etc.
- Optimize and store on server (GPU)



# Vertex Buffer Objects

- Caches vertex geometric data:  
positions, normals, texture coordinates, colors
- Optimize and store on server (GPU)
- Required for core OpenGL profile

```
/* vertices of the quad (will form two triangles;  
   rendered via GL_TRIANGLES) */
```

```
float positions[6][3] =
```

```
{{-1.0, -1.0, -1.0}, {1.0, -1.0, -1.0}, {1.0, 1.0, -1.0},  
 {-1.0, -1.0, -1.0}, {1.0, 1.0, -1.0}, {-1.0, 1.0, -1.0}};
```

```
/* colors to be assigned to vertices (4th value is the alpha channel) */
```

```
float colors[6][4] =
```

```
{{0.0, 0.0, 0.0, 1.0}, {1.0, 0.0, 0.0, 1.0}, {0.0, 1.0, 0.0, 1.0},  
 {0.0, 0.0, 1.0, 1.0}, {1.0, 1.0, 0.0, 1.0}, {1.0, 0.0, 1.0, 1.0}};
```

# Vertex Buffer Object: Initialization

```
int numVertices = 6;
VBO * vboVertices;
VBO * vboColors;

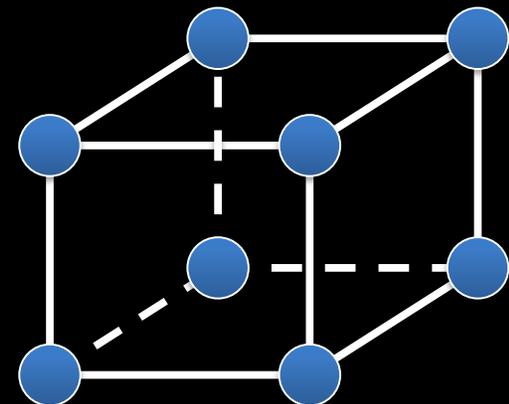
void initVBOs()
{
    // 3 values per vertex, namely x,y,z coordinates
    vboVertices = new VBO(numVertices, 3, positions, GL_STATIC_DRAW);

    // 4 values per vertex, namely r,g,b,a channels
    vboColors = new VBO(numVertices, 4, colors, GL_STATIC_DRAW);
}
```

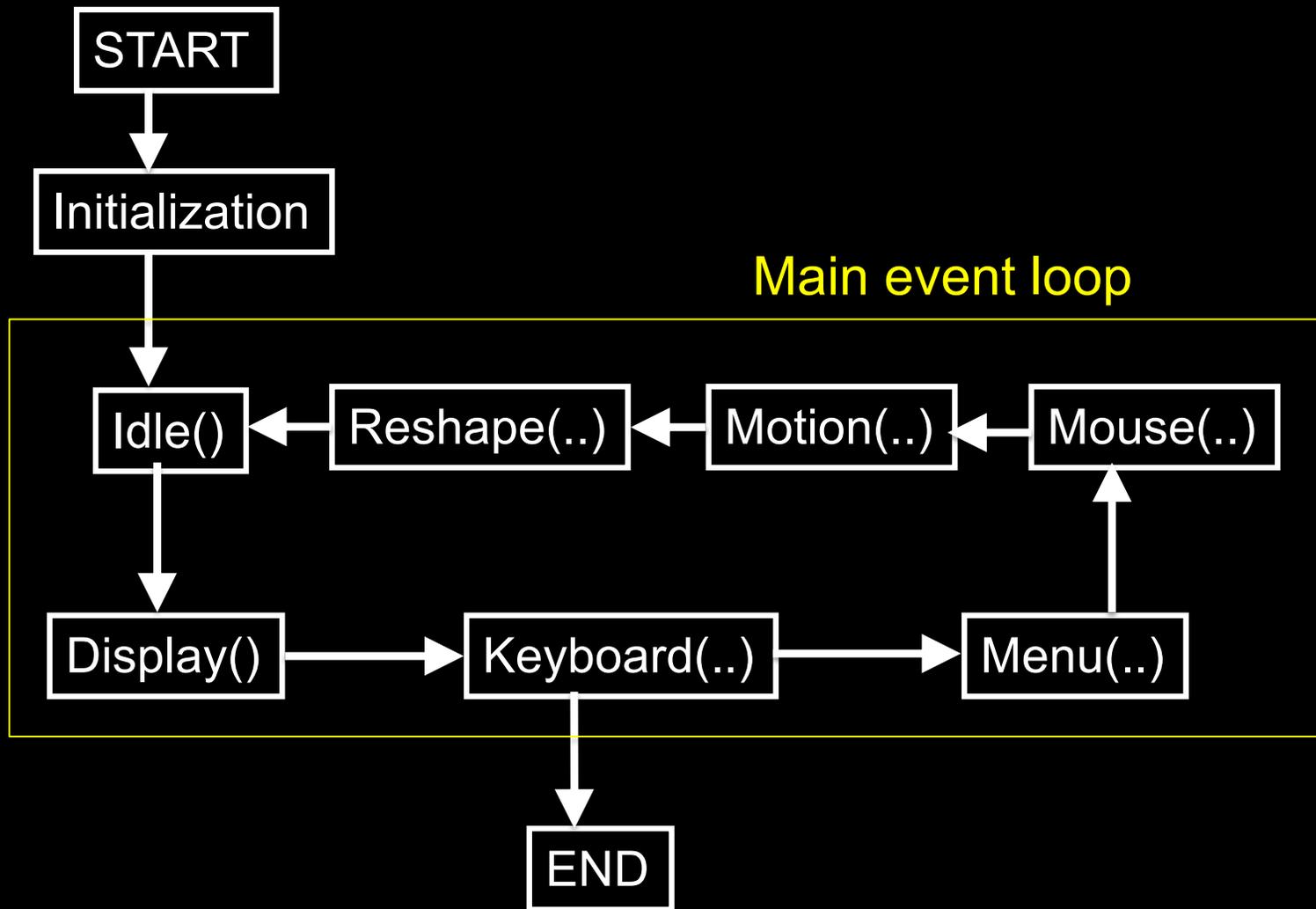
# Element Arrays

- Draw cube with  $6 \times 2 \times 3 = 36$  or with 8 vertices?
- Expense in drawing and transformation
- Triangle strips help to some extent
- Element arrays provide general solution
- Define (transmit) array of vertices, colors, normals
- Draw using index into array(s) :  

```
// (must first set up the GL_ELEMENT_ARRAY_BUFFER) ...  
glDrawElements(GL_TRIANGLES, 36, GL_UNSIGNED_INT, 0);
```
- Vertex sharing for efficient operations
- Extra credit for first assignment



# GLUT Program with Callbacks



# Main Event Loop

- Standard technique for interaction (GLUT, Qt, wxWidgets, ...)
- Main loop processes events
- Dispatch to functions specified by client
- Callbacks also common in operating systems
- “Poor man’s functional programming”

# Types of Callbacks

- Display ( ) : when window must be drawn
- Idle ( ) : when no other events to be handled
- Keyboard (unsigned char key, int x, int y) : key pressed
- Menu (...) : after selection from menu
- Mouse (int button, int state, int x, int y) : mouse button
- Motion (...) : mouse movement
- Reshape (int w, int h) : window resize
- Any callback can be NULL

# Screen Refresh

- Common: 60-100 Hz
- Flicker if drawing overlaps screen refresh
- Problem during animation
- Solution: use two separate **frame buffers**:
  - Draw into one buffer
  - Swap and display, while drawing into other buffer
- Desirable frame rate  $\geq 30$  fps (frames/second)

# Enabling Single/Double Buffering

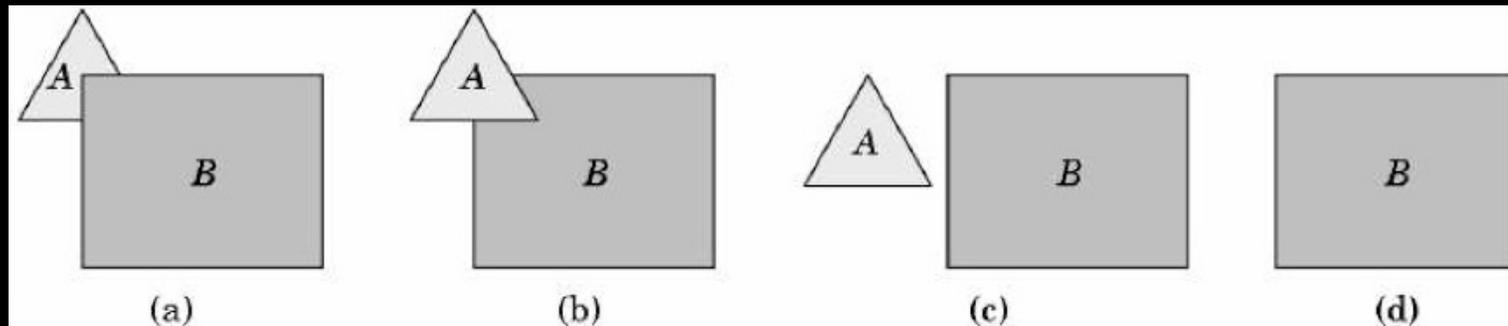
- `glutInitDisplayMode(GLUT_SINGLE);`
- `glutInitDisplayMode(GLUT_DOUBLE);`
  
- Single buffering:  
Must call `glFinish()` at the end of `Display()`
- Double buffering:  
Must call `glutSwapBuffers()` at the end of `Display()`
  
- Must call `glutPostRedisplay()` at the end of `Idle()`
  
- If something in OpenGL has no effect or does not work, check the modes in `glutInitDisplayMode`

# Hidden Surface Removal

- Classic problem of computer graphics
- What is visible after clipping and projection?
  
- Object-space vs image-space approaches
- Object space: depth sort (Painter's algorithm)
- Image space: *z-buffer* algorithm
  
- Related: back-face culling

# Object-Space Approach

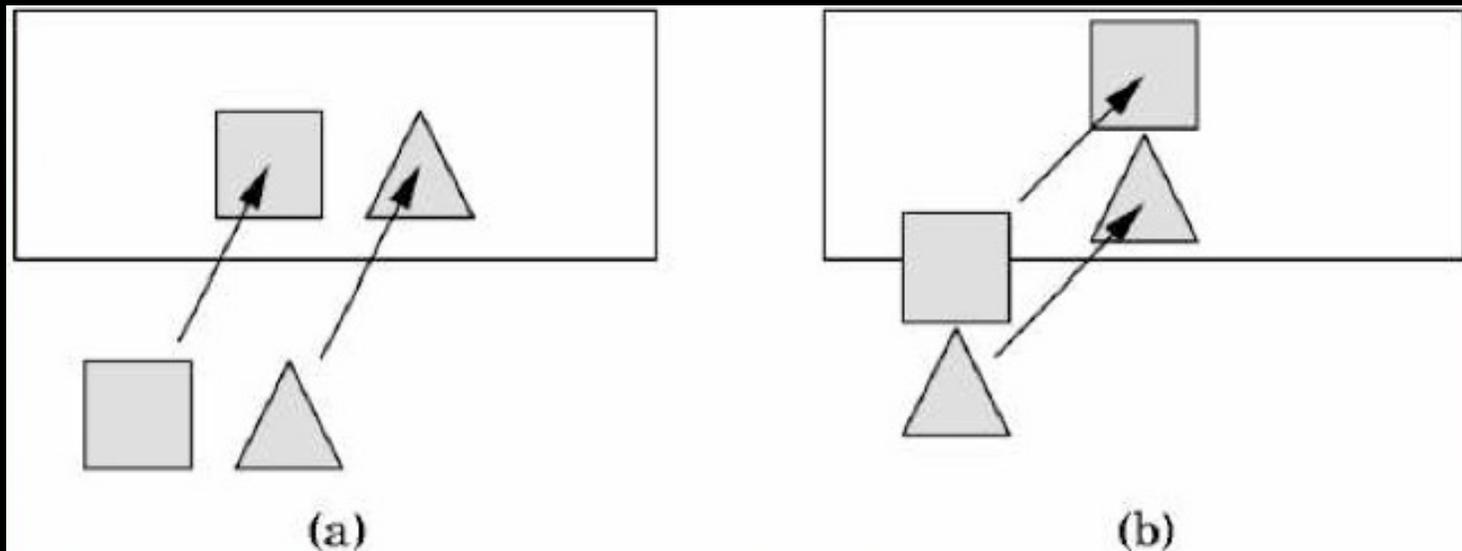
- Consider objects pairwise



- Painter's algorithm: render back-to-front
- "Paint" over invisible polygons
- How to sort and how to test overlap?

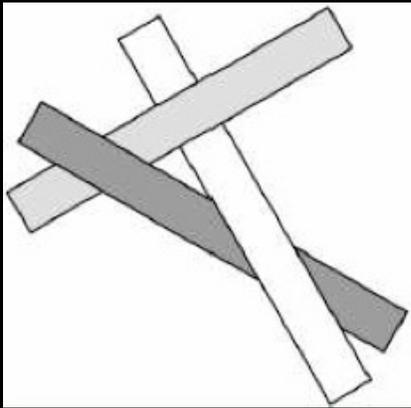
# Depth Sorting

- First, sort by furthest distance  $z$  from viewer
- If minimum depth of A is greater than maximum depth of B, A can be drawn before B
- If either  $x$  or  $y$  extents do not overlap, A and B can be drawn independently

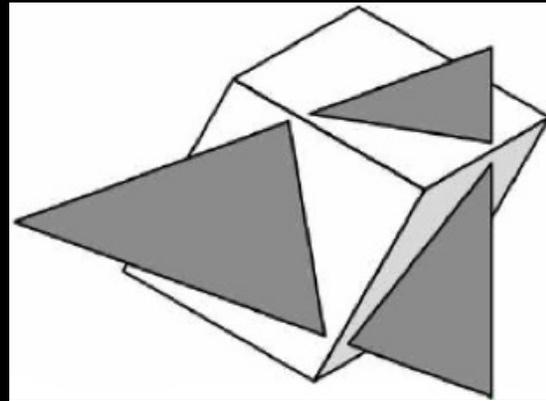


## Some Difficult Cases

- Sometimes cannot sort polygons!



Cyclic overlap



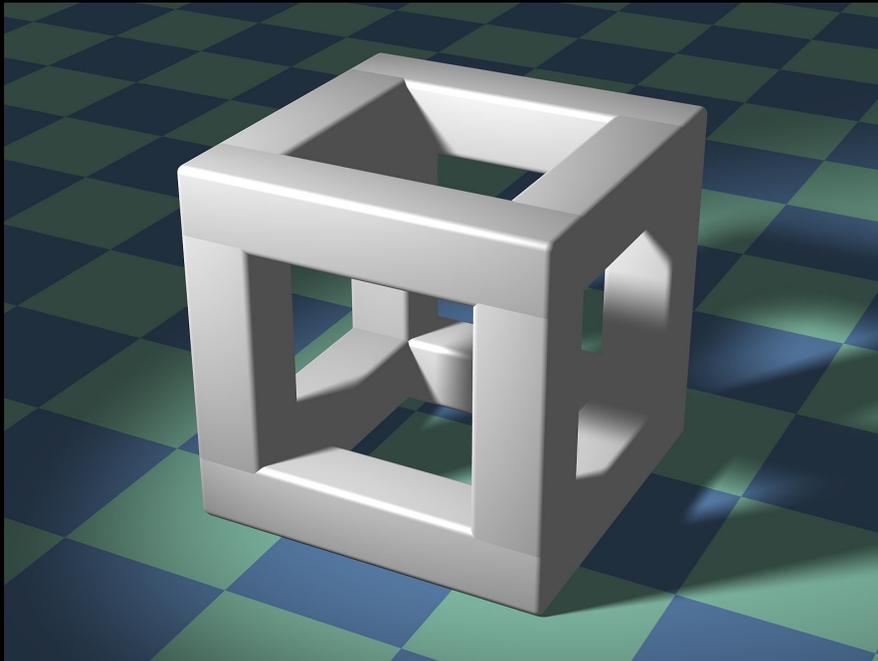
Piercing Polygons

- One solution: compute intersections & subdivide
- Do while rasterizing (difficult in object space)

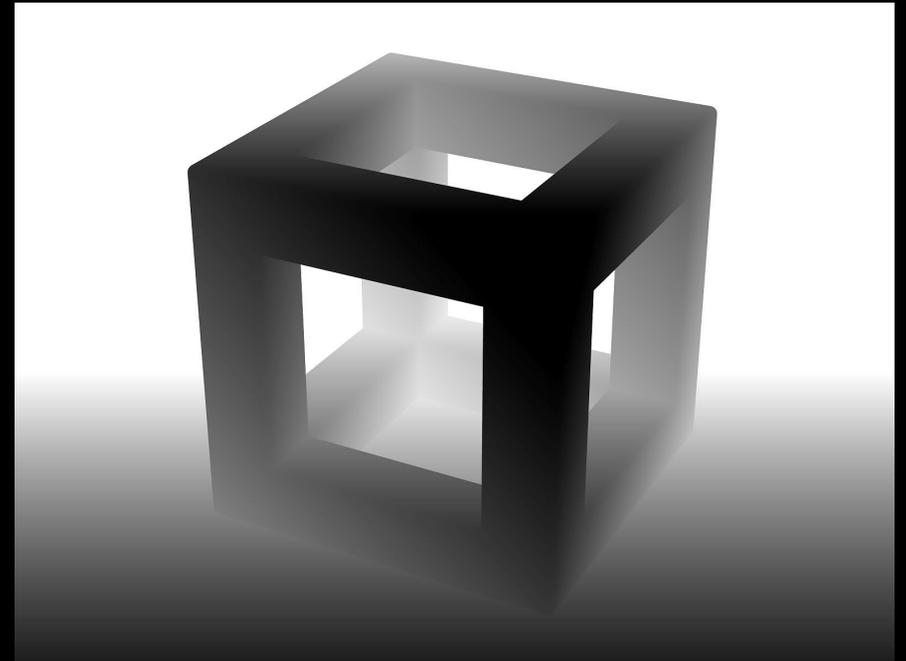
# Painter's Algorithm Assessment

- Strengths
  - Simple (most of the time)
  - Handles transparency well
  - Sometimes, no need to sort (e.g., heightfield)
- Weaknesses
  - Clumsy when geometry is complex
  - Sorting can be expensive
- Usage
  - PostScript interpreters
  - OpenGL: not supported  
(must implement Painter's Algorithm manually)

# Image-space approach



3D geometry



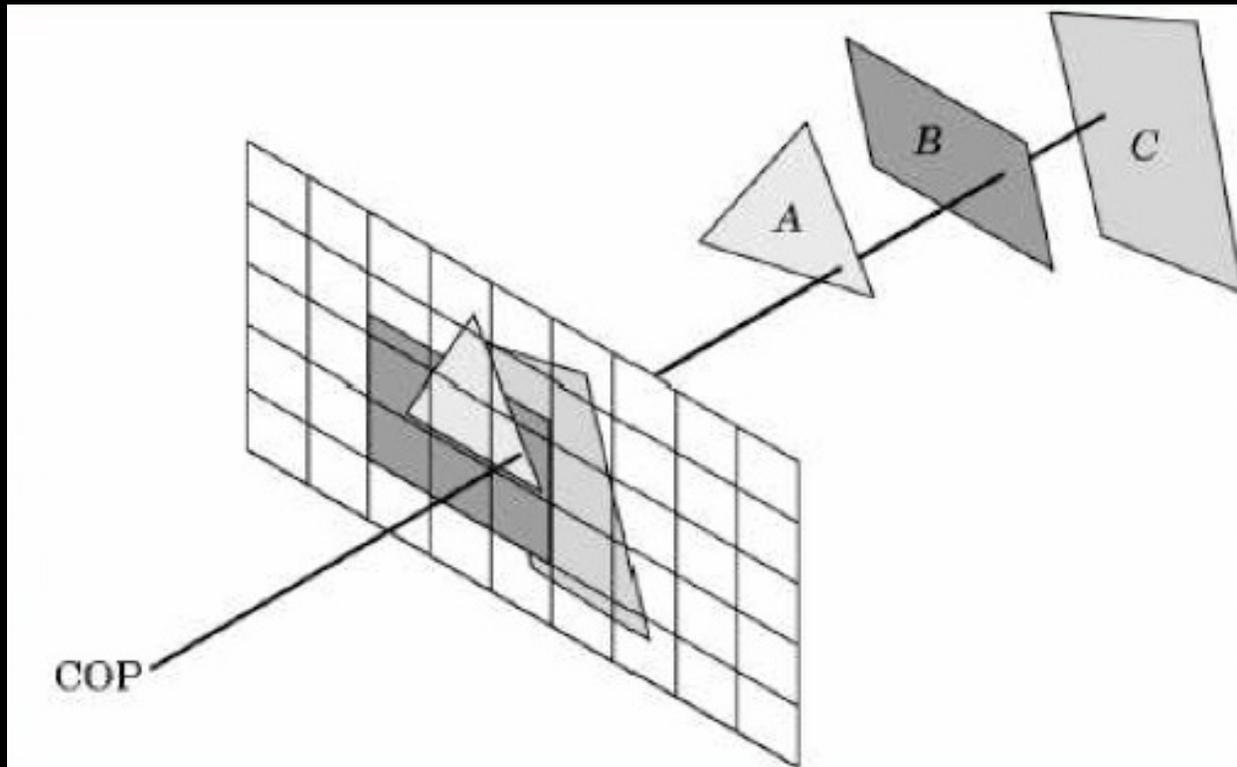
Depth image  
darker color is closer

# Depth sensor camera



# Image-Space Approach

- Raycasting: intersect ray with polygons

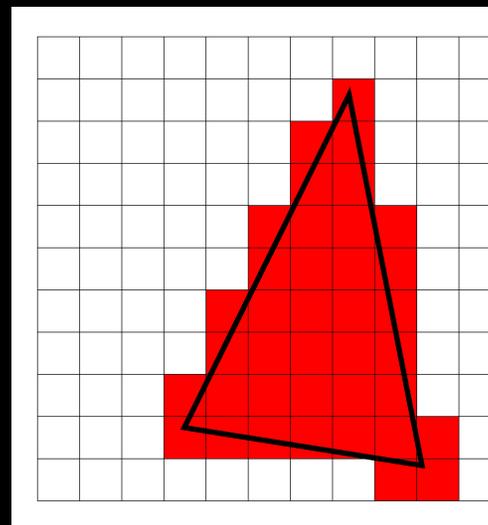
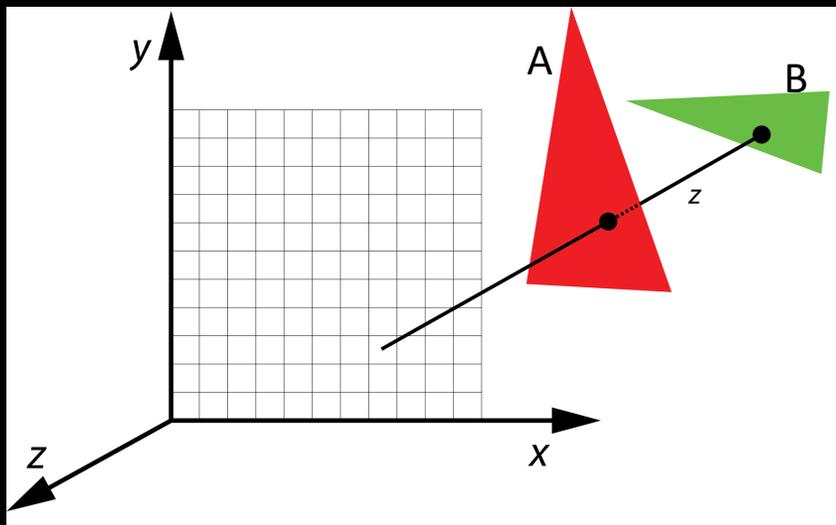


- $O(k)$  worst case (often better)
- Images can be more jagged (need anti-aliasing)

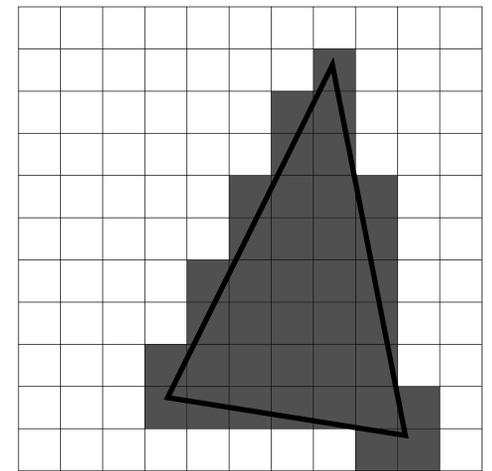
# The z-Buffer Algorithm

- z-buffer stores depth values  $z$  for each pixel
- Before writing a pixel into framebuffer:
  - Compute distance  $z$  of pixel from viewer
  - If closer, write and update z-buffer, otherwise discard

After rendering A:



color

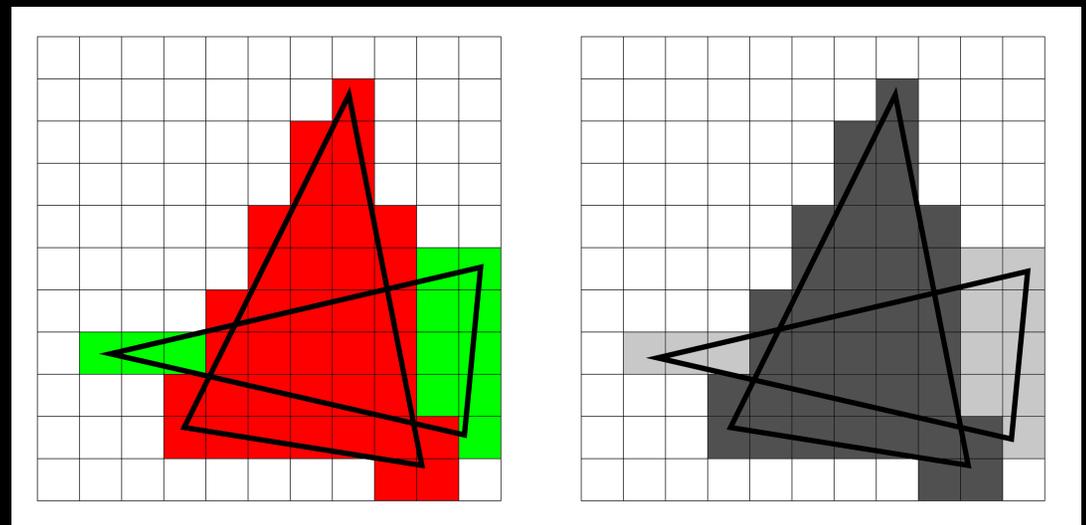
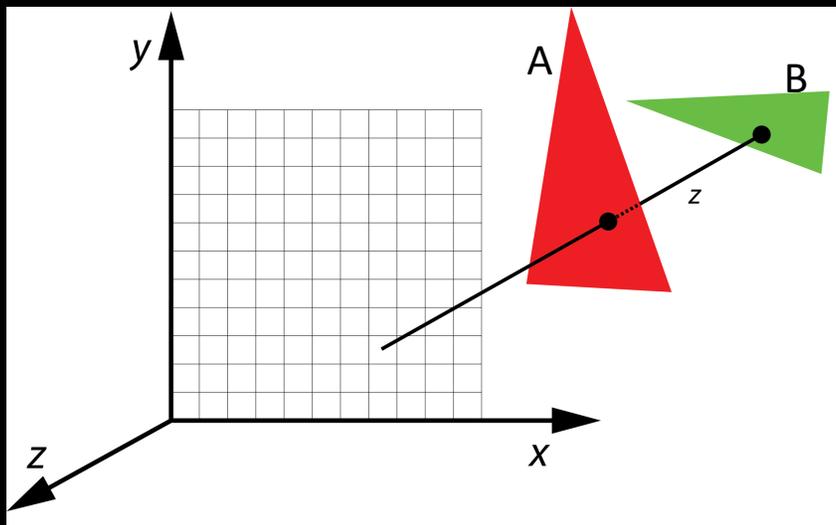


depth

# The z-Buffer Algorithm

- z-buffer stores depth values  $z$  for each pixel
- Before writing a pixel into framebuffer:
  - Compute distance  $z$  of pixel from viewer
  - If closer, write and update z-buffer, otherwise discard

After rendering A and B:



color

depth

# z-Buffer Algorithm Assessment

- Strengths
  - Simple (no sorting or splitting)
  - Independent of geometric primitives
- Weaknesses
  - Memory intensive (but memory is cheap now)
  - Tricky to handle transparency and blending
  - Depth-ordering artifacts
- Usage
  - z-Buffering comes standard with OpenGL;  
disabled by default; must be enabled

# Depth Buffer in OpenGL

- `glutInitDisplayMode(GLUT_DOUBLE | GLUT_RGBA | GLUT_DEPTH);`
- `glEnable (GL_DEPTH_TEST);`
  
- Inside `Display()`:  
`glClear (GL_DEPTH_BUFFER_BIT);`
  
- Remember all of these!
- Some “tricks” use z-buffer in read-only mode

## Note for Mac computers

Must use the GLUT\_3\_2\_CORE\_PROFILE flag to use the core profile:

```
glutInitDisplayMode(GLUT_3_2_CORE_PROFILE |  
    GLUT_DOUBLE | GLUT_RGBA | GLUT_DEPTH);
```

# Summary

- Client/Server Model
- Callbacks
- Double Buffering
- Physics of Color
- Flat vs Smooth Shading
- Hidden Surface Removal