

# Computer Animation Middleware Software

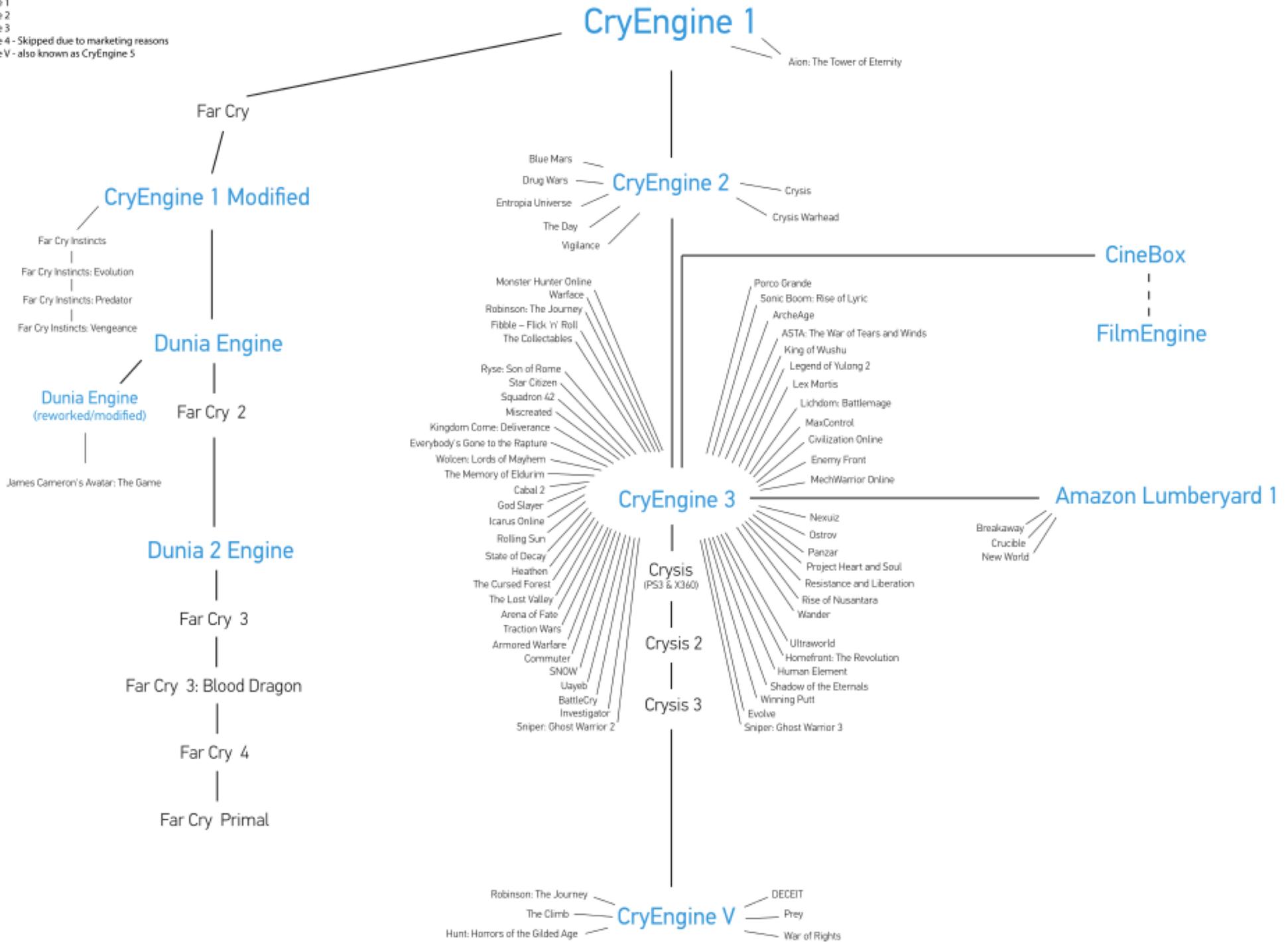
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# Game Engines

- Unity (Unity Technologies)
- Unreal Engine (Epic Games)
- Source, Source2 (Valve)
- CryEngine (Crytek)
- AnvilNext (Ubisoft)
- Frostbite (Electronic Arts)
- (not an exhaustive list)

--- Rewritten version of its predecessor

- CryEngine 1
- CryEngine 2
- CryEngine 3
- CryEngine 4 - Skipped due to marketing reasons
- CryEngine V - also known as CryEngine 5



# Character Animation Middleware

- NaturalMotion  
(real-time motion control using  
biomechanics)  
(acquired by Zynga for \$527M in 2014)
- IKInema (full-body IK solver)

# Physics in games

- Custom, in-house software
- Off-the shelf libraries
- Physics middleware

# Physics Engines

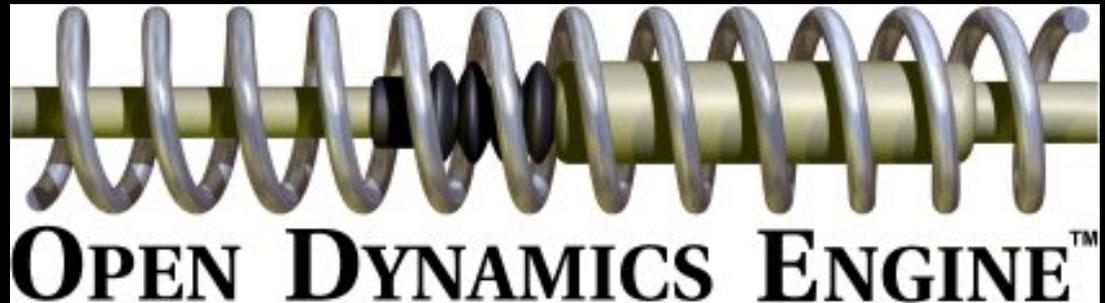
- Real-time
  - Video games
- High precision
  - Slow
  - Film
  - Scientific computing



Half-life 2

# Real-time physics engines: open source

- Open Dynamics Engine (ODE)
- Bullet
- SOFA
- Vega FEM
- and several others



# Real-time physics engines: commercial

- Havok (Ireland) (Intel => now Microsoft)
- Physx (formerly NovodeX, now nVidia)
- Vortex (Montreal)
- Rubikon (Valve)



# Components of physics engine

- Collision detection
- Dynamics
  - rigid objects
  - cloth
  - fluids
- Fracture

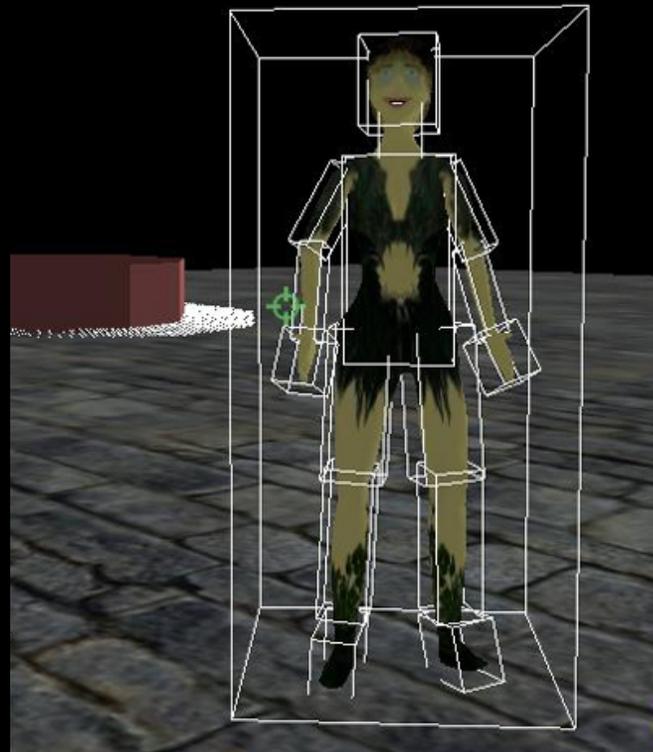


# Rigid object contact

- Penalty-based
  - popular with soft/deformable objects
- Impulse-based
- Constraint-based
  - expensive, suitable for continuous contact

# Real-time simulation

- Speed more important than accuracy
- Objects have two representations:
  - Complex geometry (rendering)
  - Simplified geometry (collision detection, dynamics)



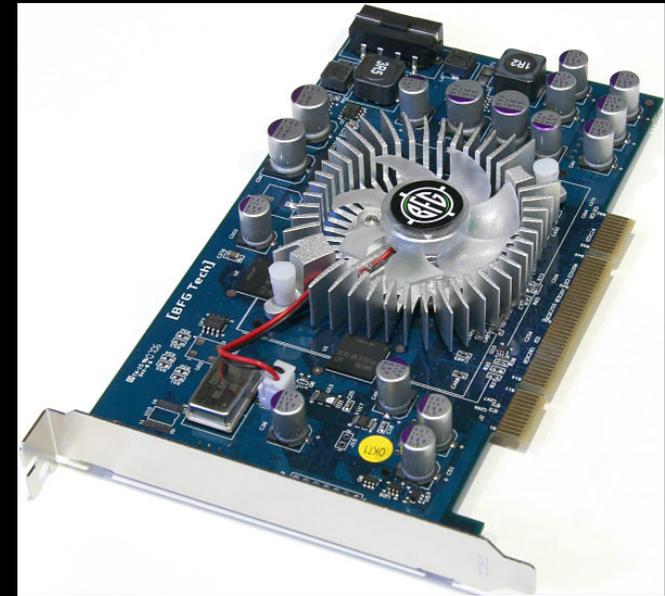
# Characters

- Rag-doll physics
  - Rigid objects
- Cloth
- Controller
  - NaturalMotion
- Particles (hair)



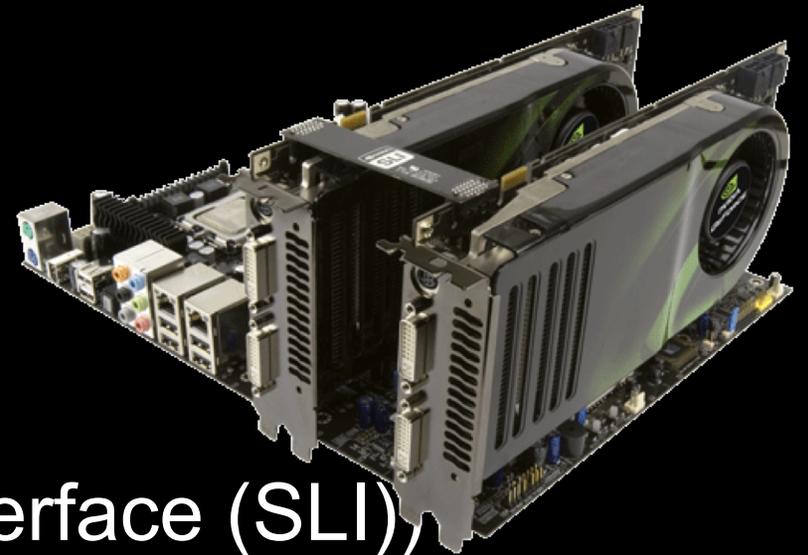
# Physics processing unit (PPU)

- Dedicated physics co-processor
- SPARTA and HELLAS
  - academic
  - Penn State, Univ. of Georgia
- Ageia (Switzerland, 2006)
  - later merged into nVidia
  - use AGEIA's PhysX SDK



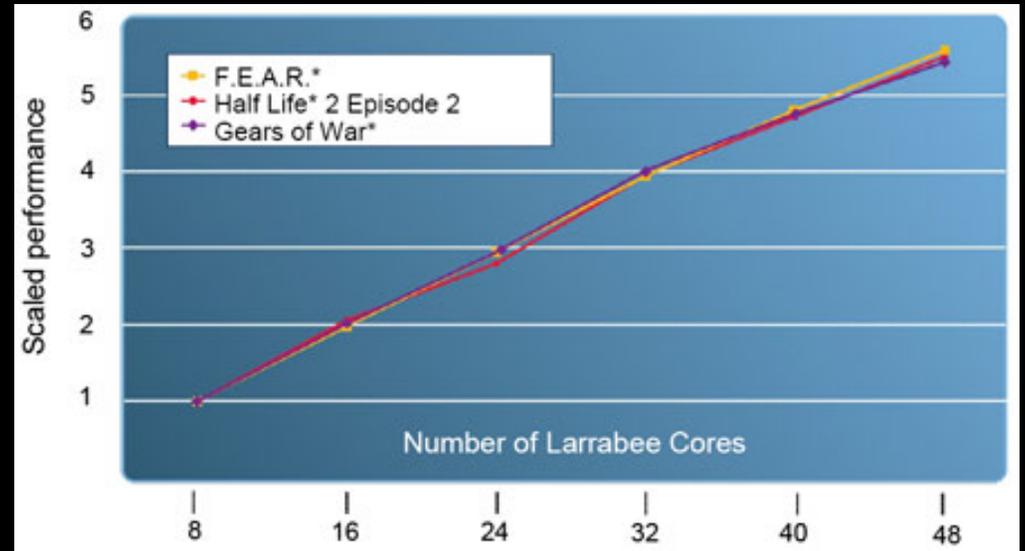
# GPGPU

- Havok FX
  - was cancelled
- Multi-GPU technology
  - AMD (CrossFireX)
  - nVidia (Scalable Link Interface (SLI)),
  - SLI just parallelizes rendering, but can dedicate a specific card just to Physx (similar to AGEIA)
- Increasingly more suitable for physics



# Intel Larrabee

- Many-core x86
- Fusion of CPU and GPU
- Suitable for physics



- Was scheduled for 2010, but canceled
- AMD: APU (combo of CPU and GPU)

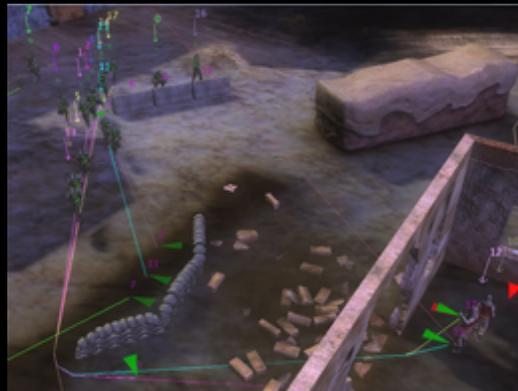
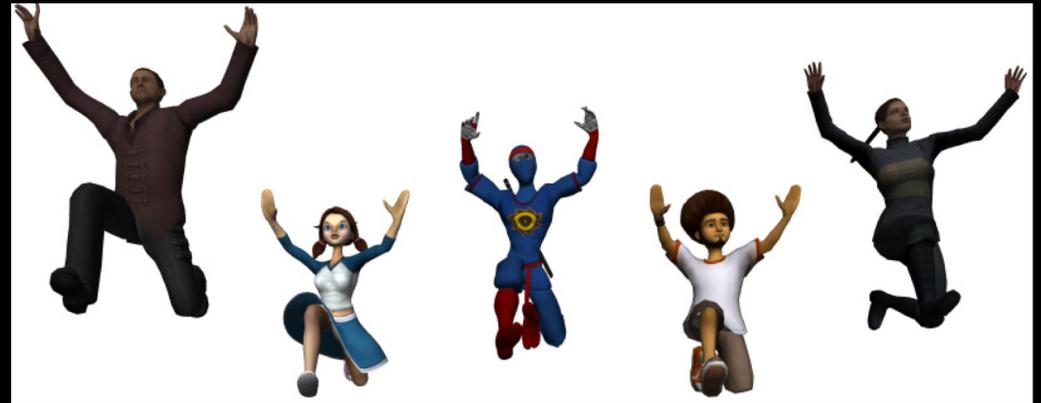
# Havok

- Real-time commercial physics engine
- Company bought by Intel (2007)  
(\$110 million)
- Used in over 300 games
  - Halo
  - Half Life 2



# Havok Engine

- Animation
  - Fast playback
  - Real-time blending
  - Inverse kinematics
  - Retargeting
  
- AI
  - path-finding



# Havok Engine

- Behavior
  - Character behavior development tool
- Cloth
- Destruction
- Physics



# Havok Physics



**FIRST PERSON SHOOTERS**



**DRIVING GAMES**



**3RD PERSON ACTION GAMES**



**REAL TIME STRATEGY GAMES**

# Havok Physics

- Collision detection
- Constraints
- Rigid bodies
- Cloth
- Continuous physics



Uncharted 2: Among thieves

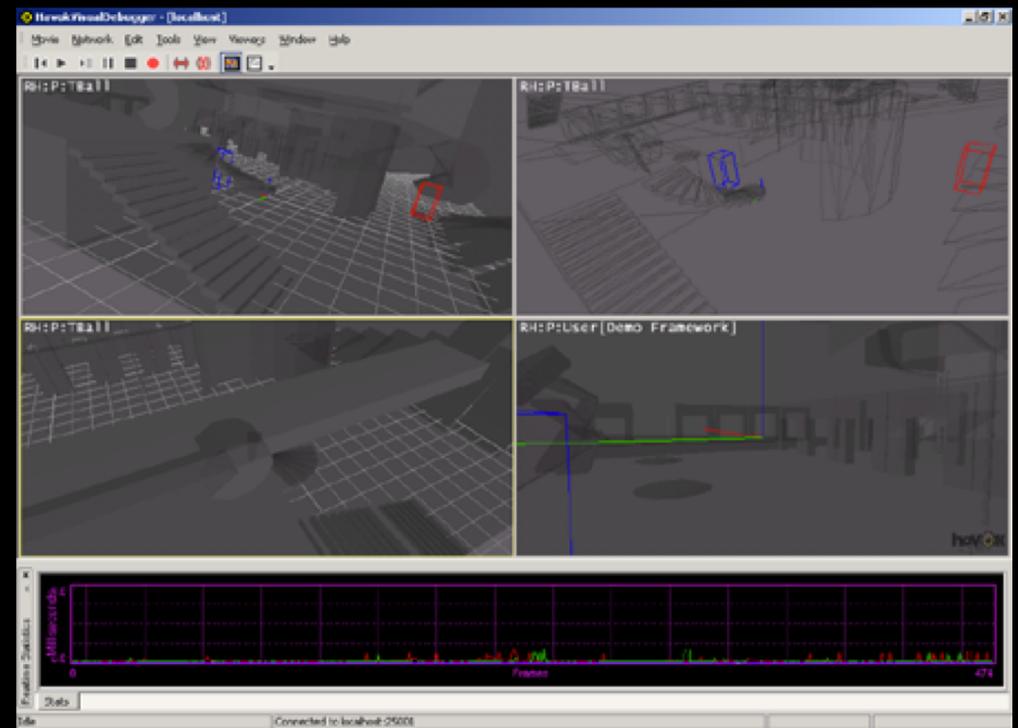
# Havok Physics

- Vehicle simulation
- Human ragdolls
- Character controller
  - simulate enemy characters being hit



# Havok Physics

- Visual debugger and profiler
- Content creation tools
- Integration with 3rd-party renderers
  - 3D Studio Max
  - Maya



# Havok Physics

- Extensively optimized (machine code)
- Microsoft Xbox
- Sony PLAYSTATION
- Nintendo Wii
- PC

```
main:  subu   $sp, $sp, 32
       sw   $ra, 20($sp)
       sw   $fp, 16($sp)
       addiu $fp, $sp, 28
       li   $v0, 4
       la   $a0, str
       syscall
       li   $a0, 10
       jal  fact
       addu $a0, $v0, $zero
       li   $v0, 1
       syscall
       lw   $ra, 20($sp)
       lw   $fp, 16($sp)
       addiu $sp, $sp, 32
       jr   $ra
```

# Havok Physics is not...

- Simple technology
  - Must invest time to use it
- Black box
  - Must understand the components and recombine them
- Commercial renderer

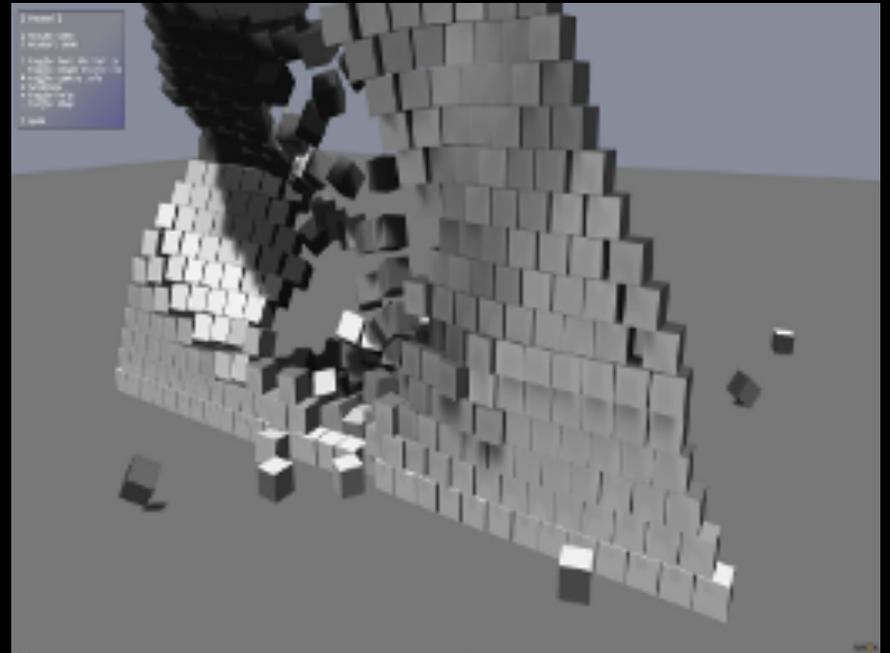
# Havok Physics

- The “Havok World” (hkpWorld)
- Contains all physical objects in the simulation
- Timesteps the simulation forward in time

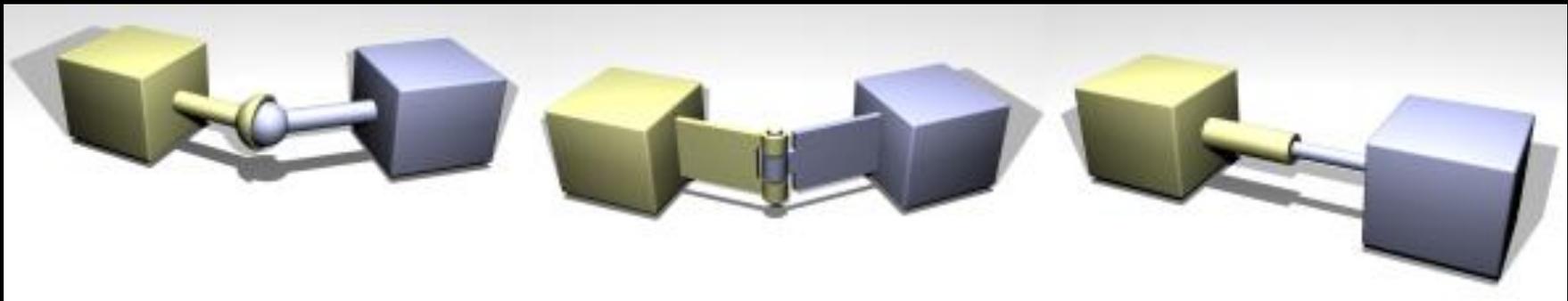


# Rigid objects

- The central object in Havok
- `hkpRigidBody` class
- Add to the “world”
- Set mass, inertia tensor, etc.



# Constraints

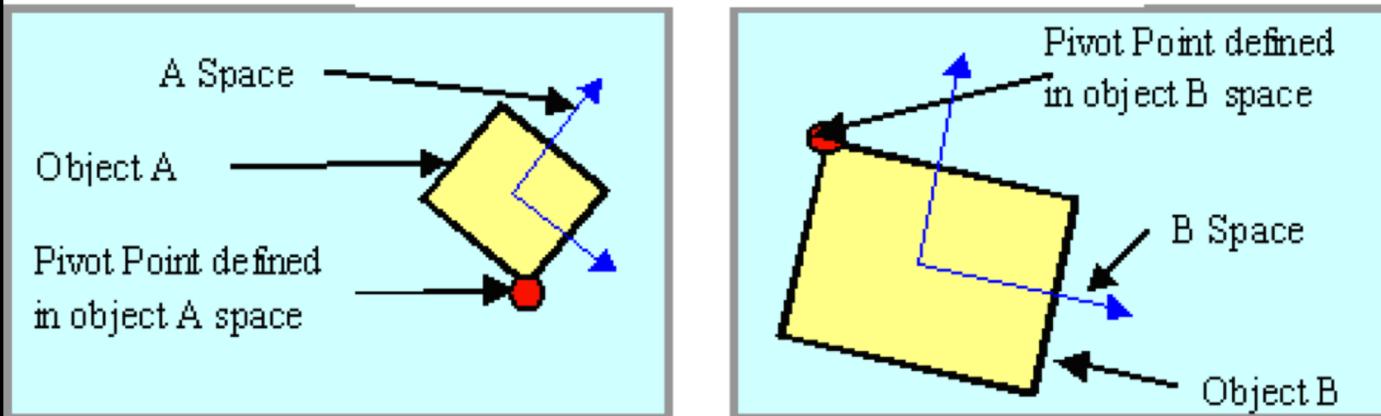


Ball and  
socket

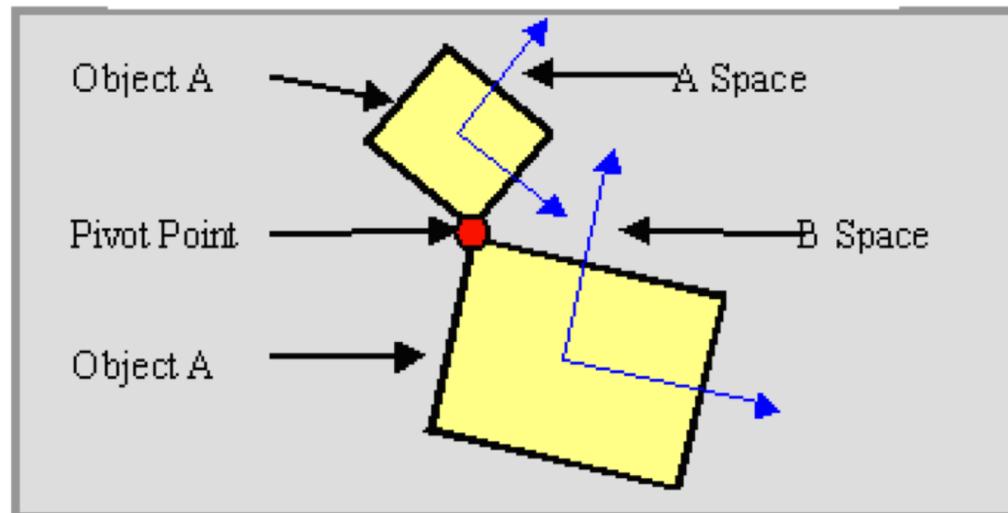
Hinge

Translational

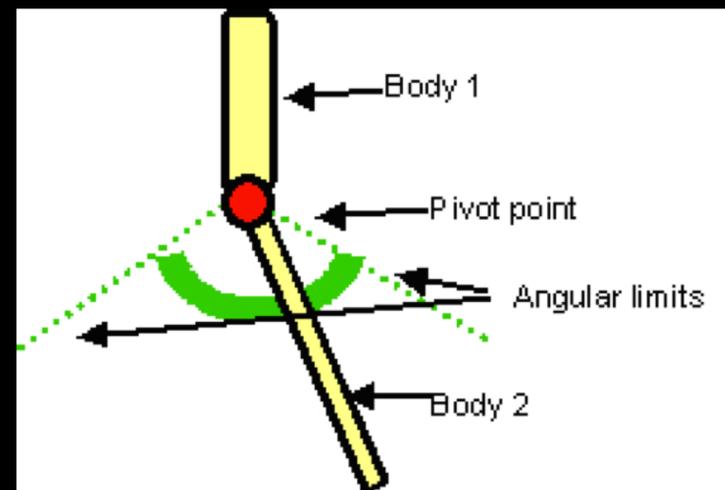
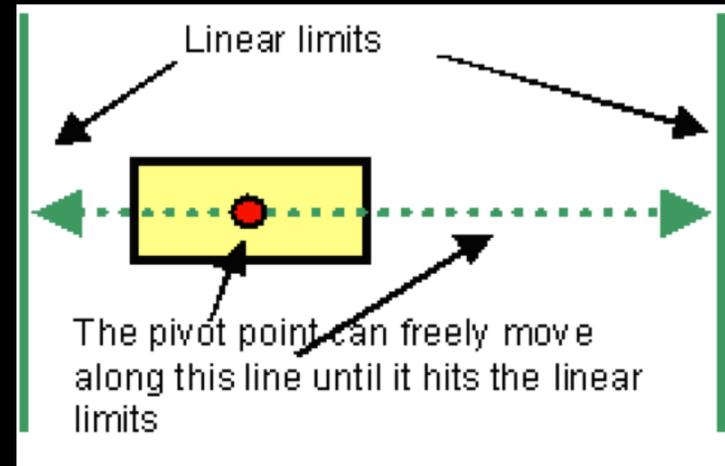
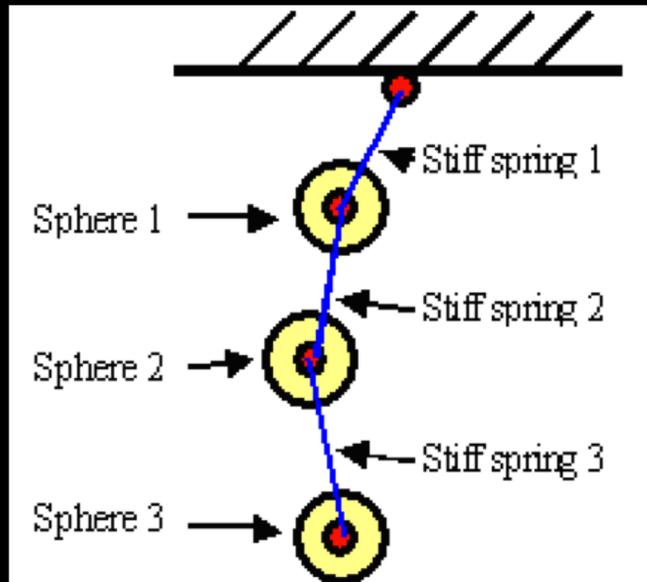
## Static constraint definition



## Dynamic simulation

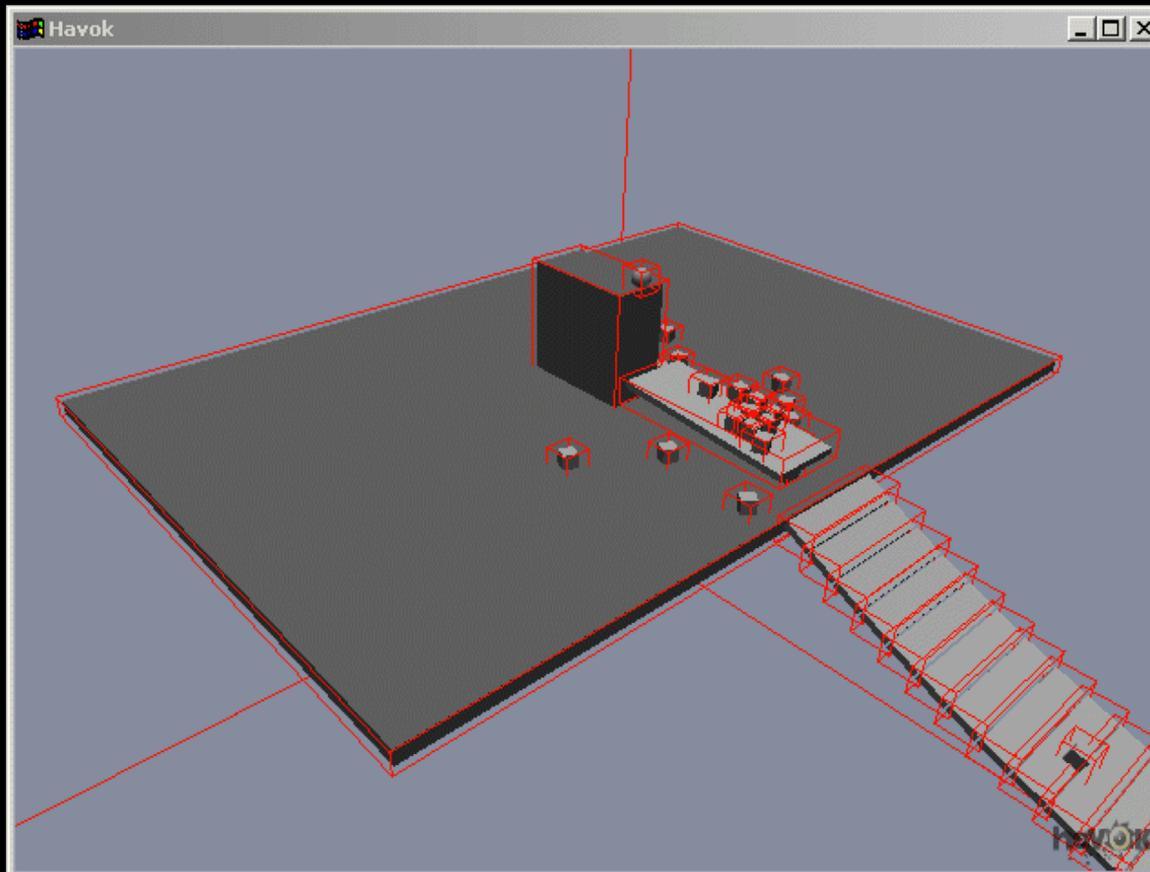


# Constraints



# Collision Detection

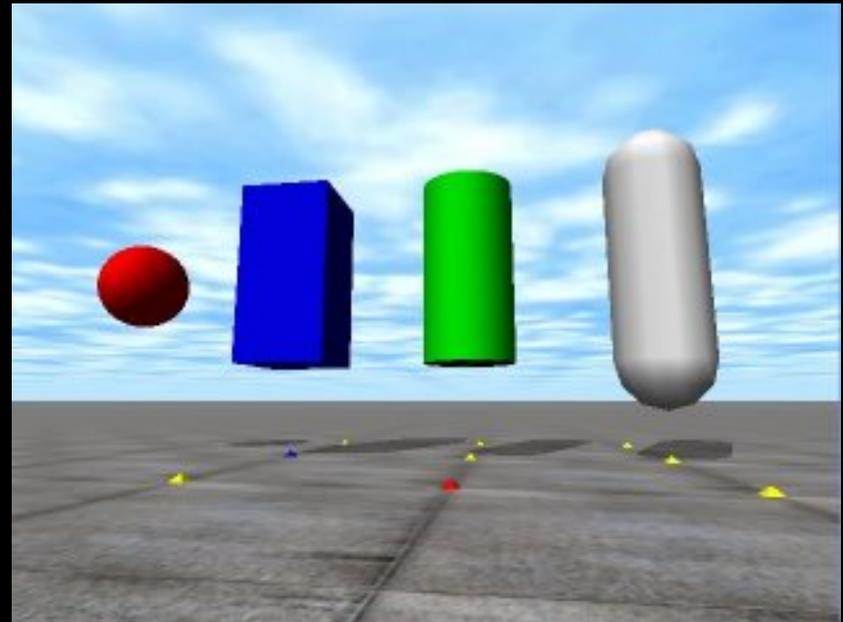
- Broad phase and narrow phase



Broad  
phase

# Collision Detection

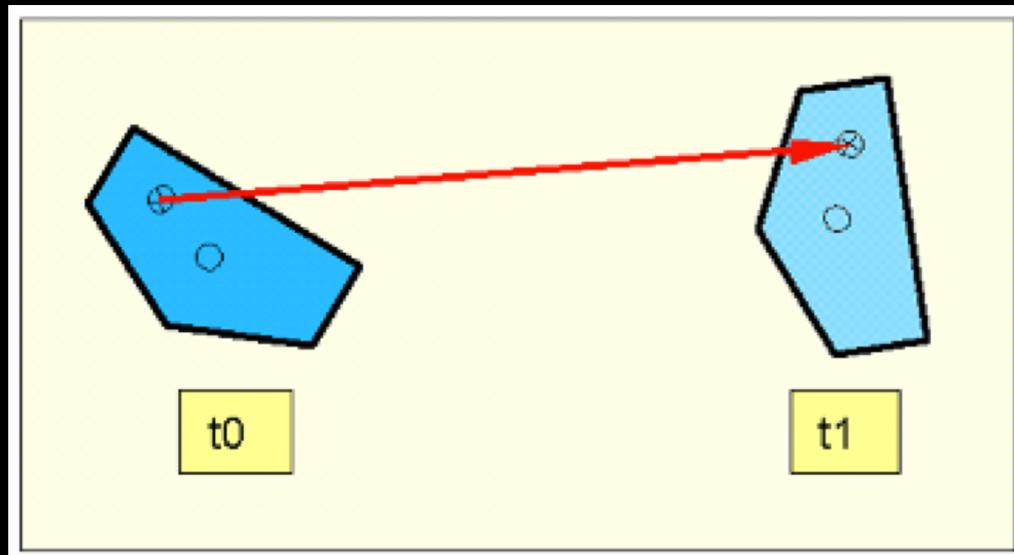
- Narrow phase
- Spheres
- AABBs
- Cylinders
- Capsules
- Compound shapes



# Collision Detection: Queries

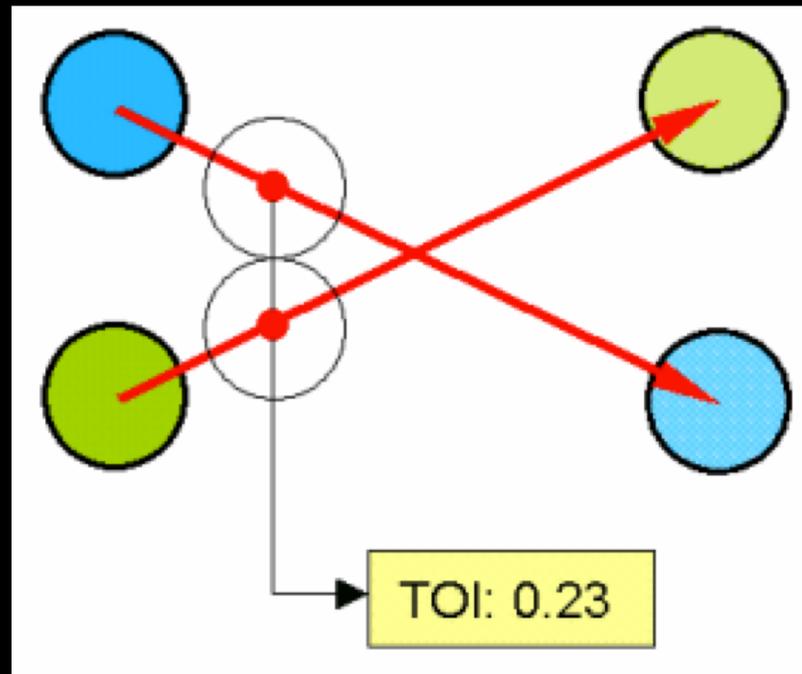
- Closest points between two bodies
- Whether two bodies penetrate
- Raycast a point through space and get colliding objects

# Continuous Physics



# Continuous Physics

- Time of impact:



## Discrete Simulation

### ➤ Collision detection

- Calculate contacts

### ➤ Integration

- Solve constraints
- Integrate body state

REVERSED

## Continuous Simulation

### ➤ Integration (Potential state)

- Solve contact constraints
- Integrate to a potential body state

### ➤ Collision detection

- Calculate potential contacts
- Generate TOI events

### ➤ while(TOI events present)

- Select involved objects
- Re-Calculate contact points
- Re-Integrate
- Re-Collide

### ➤ Client code to verify or correct:

- Allowed positions
- Interpenetration
- Tunneling