

Computer Animation Middleware Software

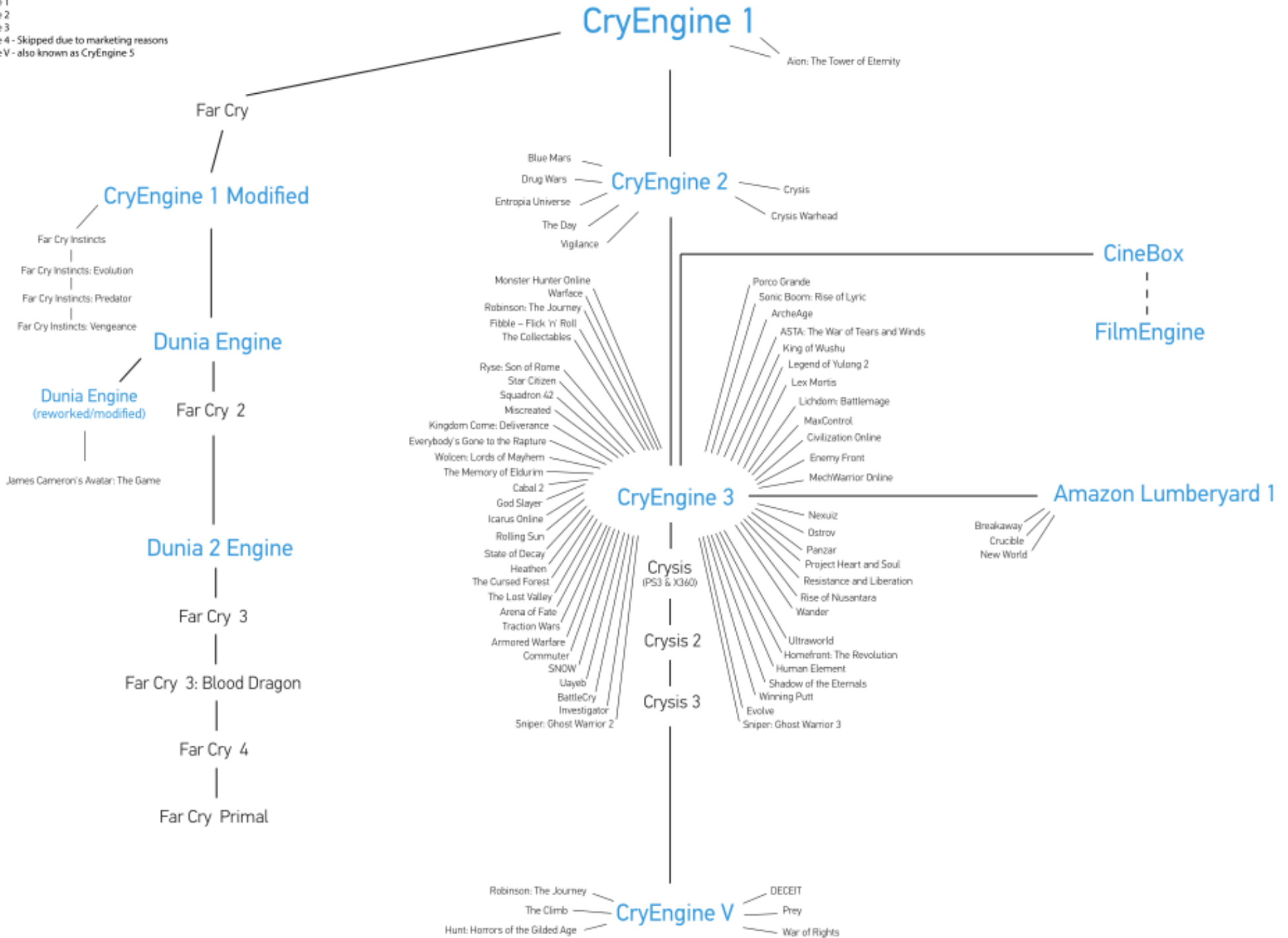
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Game Engines

- Unreal Engine (Epic Games)
- Unity (Unity Technologies)
- Source, Source2 (Valve)
- CryEngine (Crytek)
- AnvilNext (Ubisoft)
- Frostbite (Electronic Arts)
- (not an exhaustive list)

--- Rewritten version of it's predecessor

- CryEngine 1
- CryEngine 2
- CryEngine 3
- CryEngine 4 - Skipped due to marketing reasons
- CryEngine V - also known as CryEngine 5



Character Animation Middleware

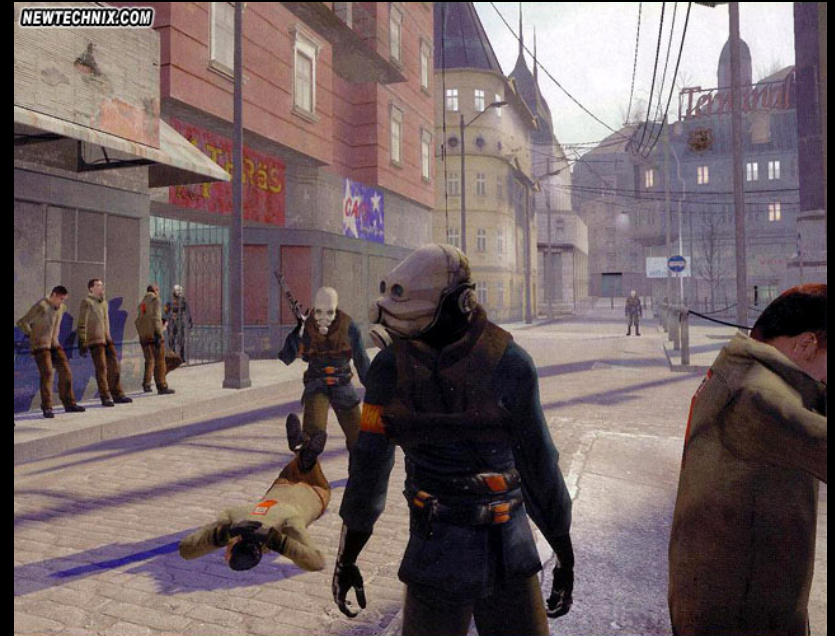
- NaturalMotion
(real-time motion control using
biomechanics)
(acquired by Zynga for \$527M in 2014)
- IKInema (full-body IK solver)

Physics in games

- Custom, in-house software
- Off-the shelf libraries
- Physics middleware

Physics Engines

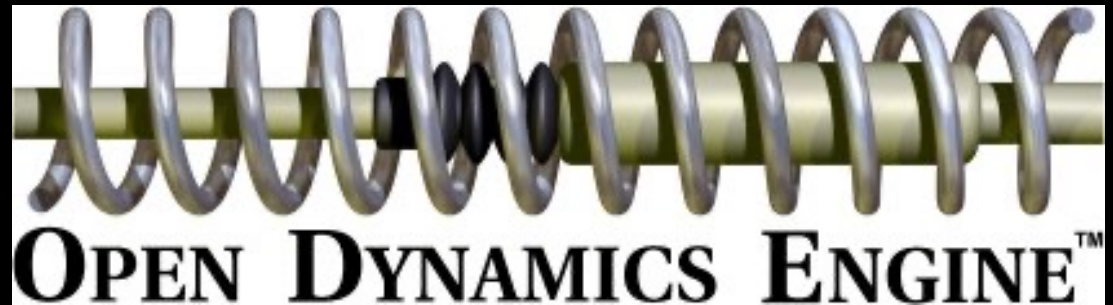
- Real-time
 - Video games
- High precision
 - Slow
 - Film
 - Scientific computing



Half-life 2

Real-time physics engines: open source

- Open Dynamics Engine (ODE)
- Bullet
- SOFA
- Vega FEM
- and several others



Real-time physics engines: commercial

- Havok (Ireland) (Intel => now Microsoft)
- Physx (formerly NovodeX, now nVidia)
- Vortex (Montreal)
- Rubikon (Valve)



Components of physics engine

- Collision detection
- Dynamics
 - rigid objects
 - cloth
 - fluids
- Fracture

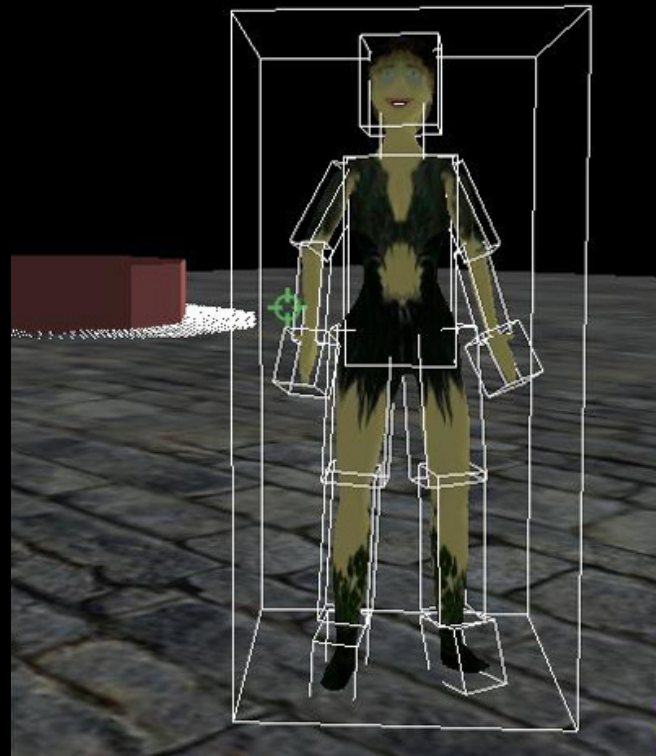


Rigid object contact

- Penalty-based
 - popular with soft/deformable objects
- Impulse-based
- Constraint-based
 - expensive, suitable for continuous contact

Real-time simulation

- Speed more important than accuracy
- Objects have two representations:
 - Complex geometry (rendering)
 - Simplified geometry (collision detection, dynamics)



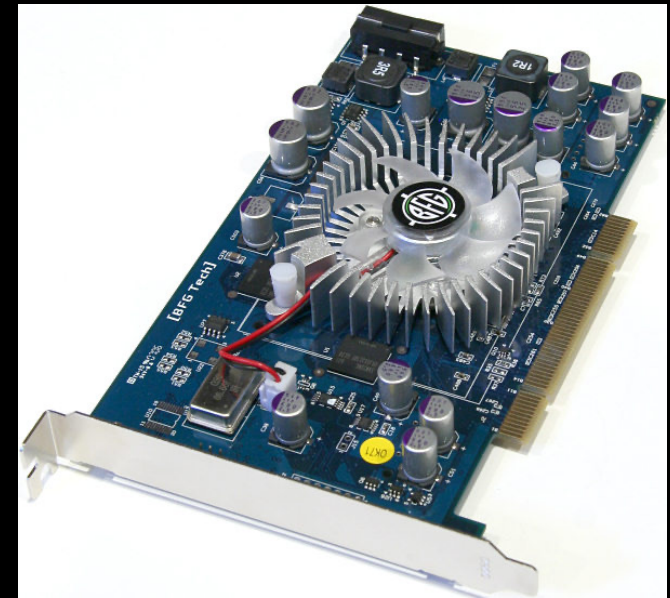
Characters

- Rag-doll physics
 - Rigid objects
- Cloth
- Controller
 - NaturalMotion
- Particles (hair)



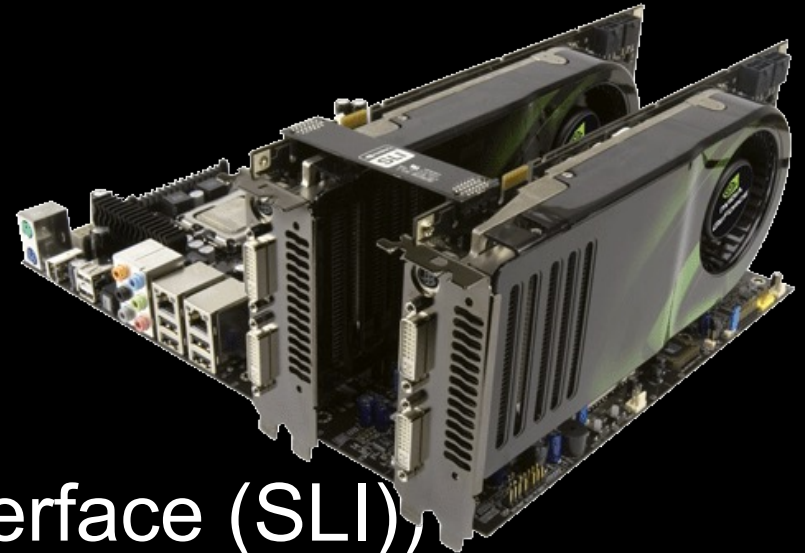
Physics processing unit (PPU)

- Dedicated physics co-processor
- SPARTA and HELLAS
 - academic
 - Penn State, Univ. of Georgia
- Ageia (Switzerland, 2006)
 - later merged into nVidia
 - use AGEIA's PhysX SDK



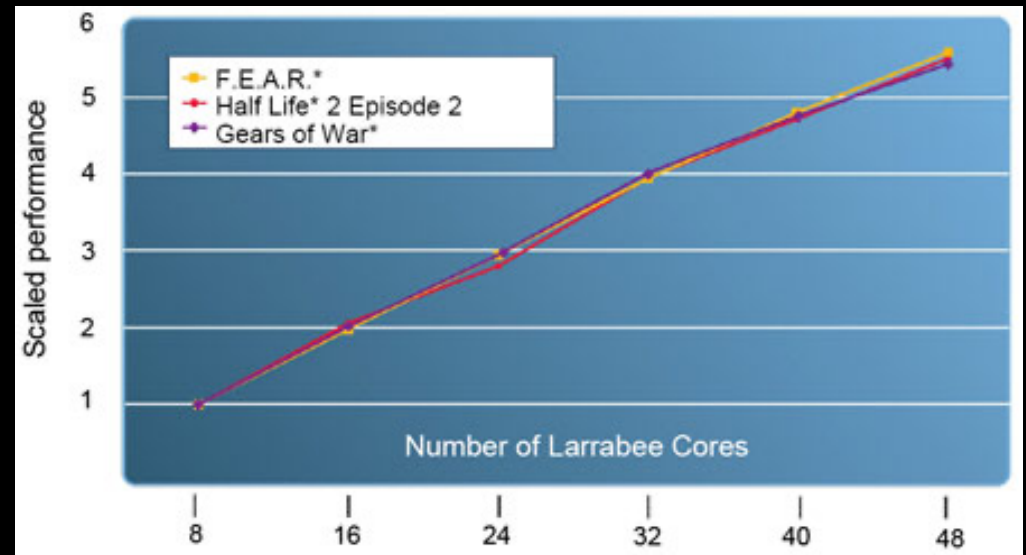
GPGPU

- Havok FX
 - was cancelled
- Multi-GPU technology
 - AMD (CrossFireX)
 - nVidia (Scalable Link Interface (SLI)),
 - SLI just parallelizes rendering, but can dedicate a specific card just to Physx (similar to AGEIA)
- Increasingly more suitable for physics



Intel Larrabee

- Many-core x86
- Fusion of CPU and GPU
- Suitable for physics



- Was scheduled for 2010, but canceled
- Combo of CPU and GPU: AMD (APU), Apple (M1, M2, M3), Intel (Falcon Shores, ~2025)

Havok

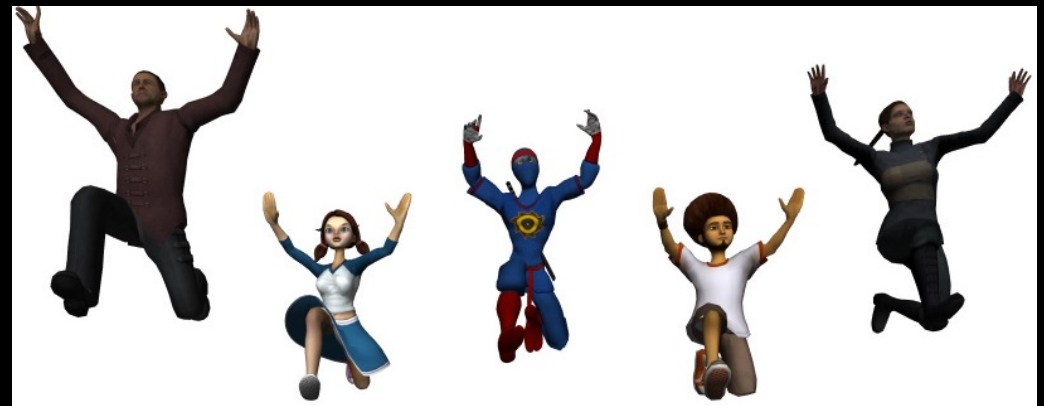
- Real-time commercial physics engine
- Company bought by Intel (2007) (\$110 million), later sold to Microsoft
- Used in over 300 games
 - Halo
 - Half Life 2



Havok Engine

- Animation
 - Fast playback
 - Real-time blending
 - Inverse kinematics
 - Retargeting

- AI
 - path-finding



Havok Engine

- Behavior
 - Character behavior development tool
- Cloth
- Destruction
- Physics



Havok Physics



FIRST PERSON SHOOTERS



DRIVING GAMES



3RD PERSON ACTION GAMES



REAL TIME STRATEGY GAMES

Havok Physics

- Collision detection
- Constraints
- Rigid bodies
- Cloth
- Continuous physics



Uncharted 2: Among thieves

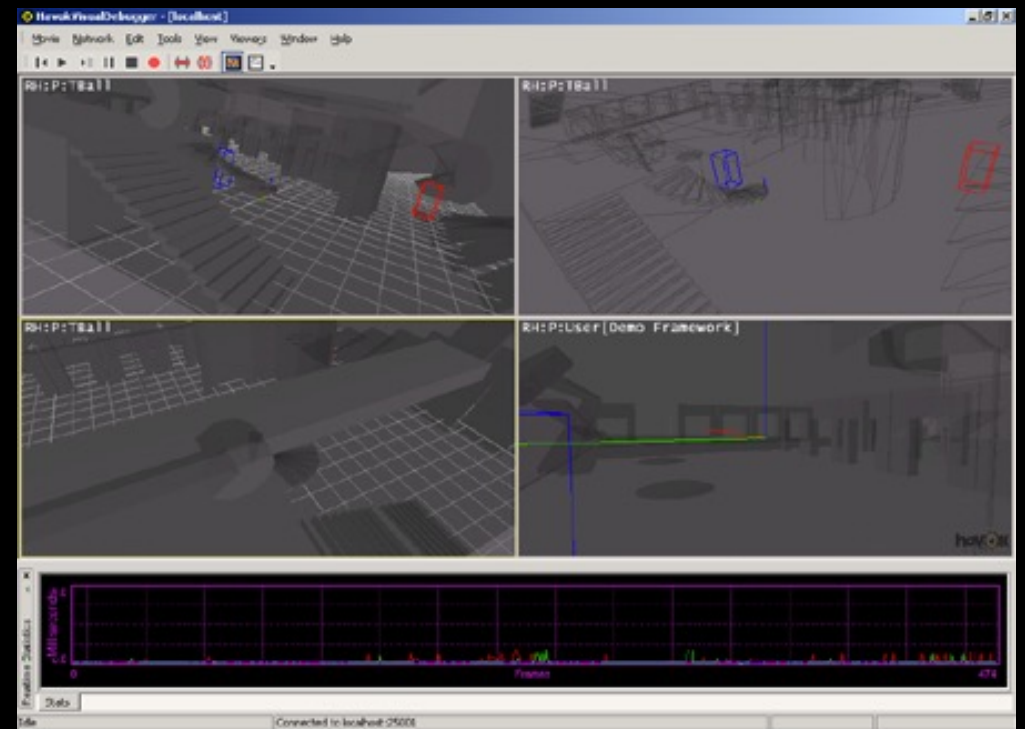
Havok Physics

- Vehicle simulation
- Human ragdolls
- Character controller
 - simulate enemy characters being hit



Havok Physics

- Visual debugger and profiler
- Content creation tools
- Integration with 3rd-party renderers
 - 3D Studio Max
 - Maya



Havok Physics

- Extensively optimized (machine code)
- Microsoft Xbox
- Sony PLAYSTATION
- Nintendo Wii
- PC

```
main:  subu   $sp, $sp, 32
       sw   $ra, 20($sp)
       sw   $fp, 16($sp)
       addiu $fp, $sp, 28
       li   $v0, 4
       la   $a0, str
       syscall
       li   $a0, 10
       jal  fact
       addu $a0, $v0, $zero
       li   $v0, 1
       syscall
       lw   $ra, 20($sp)
       lw   $fp, 16($sp)
       addiu $sp, $sp, 32
       jr   $ra
```

Havok Physics is not...

- Simple technology
 - Must invest time to use it
- Black box
 - Must understand the components and recombine them
- Commercial renderer

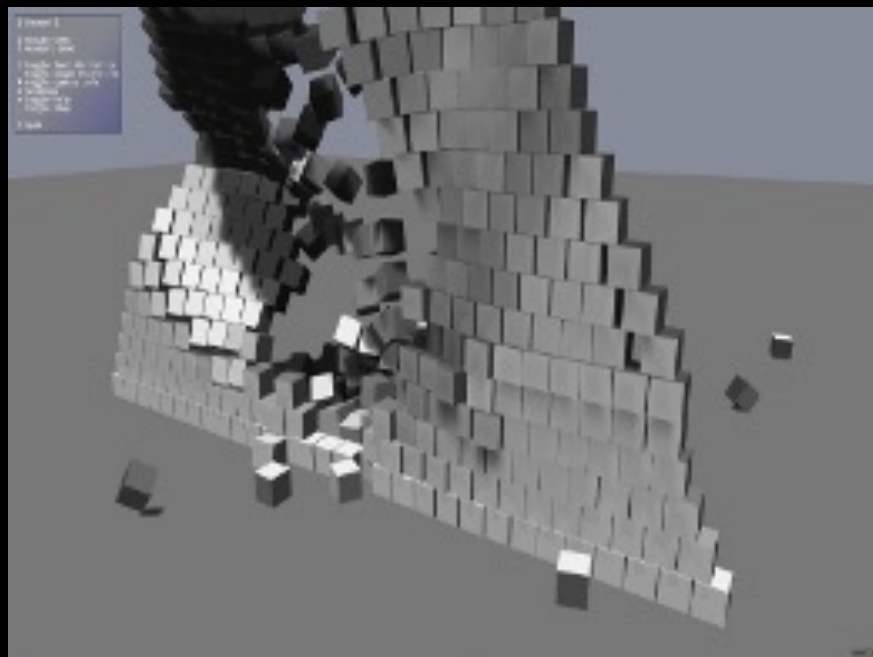
Havok Physics

- The “Havok World” (hkpWorld)
- Contains all physical objects in the simulation
- Timesteps the simulation forward in time

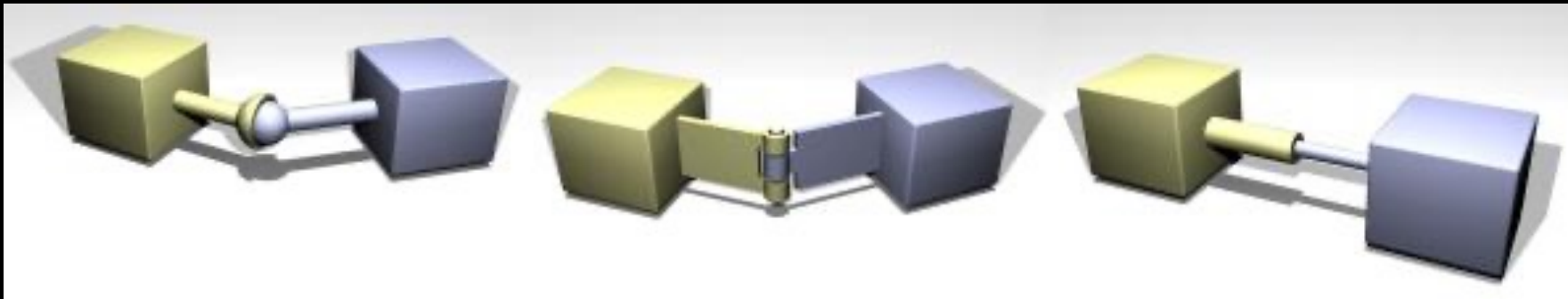


Rigid objects

- The central object in Havok
- `hkpRigidBody` class
- Add to the “world”
- Set mass, inertia tensor, etc.



Constraints

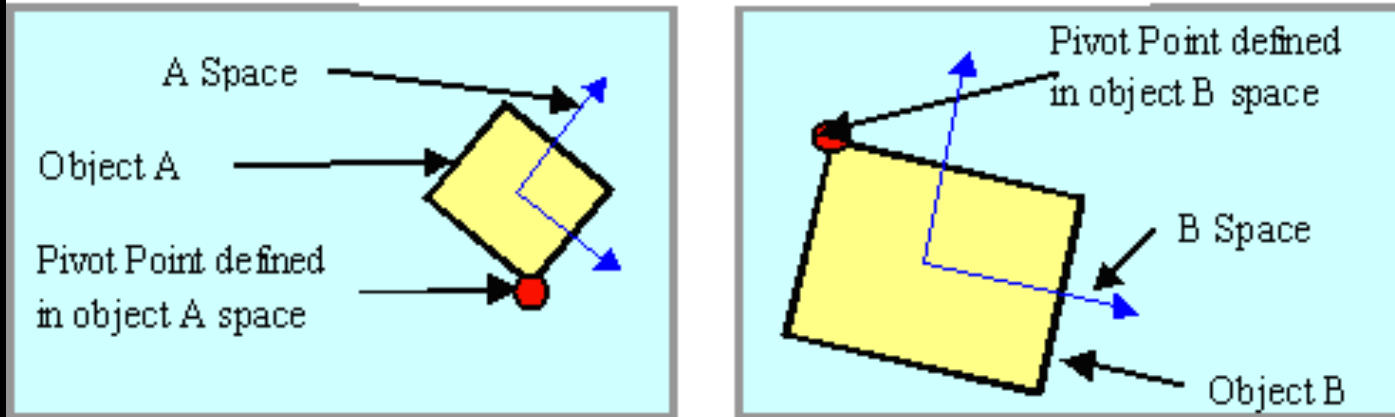


Ball and
socket

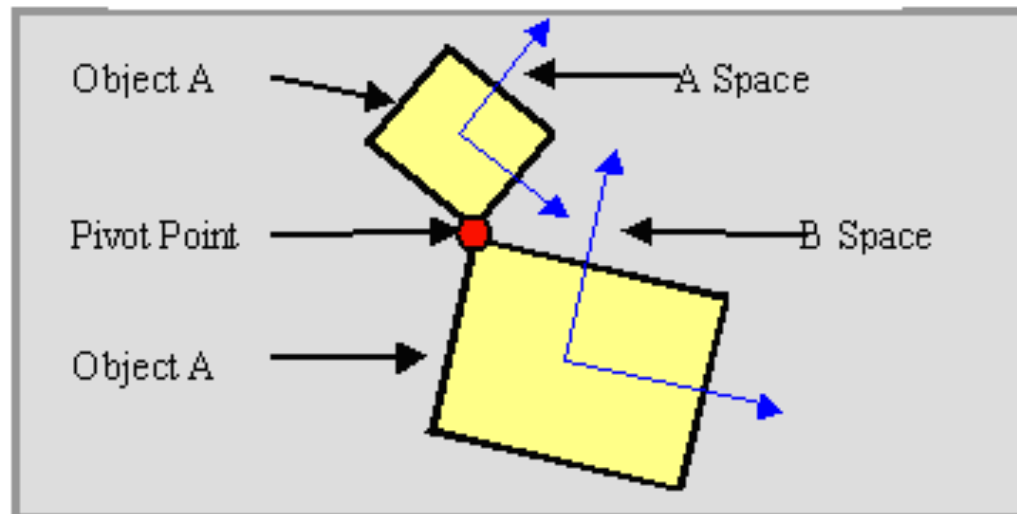
Hinge

Translational

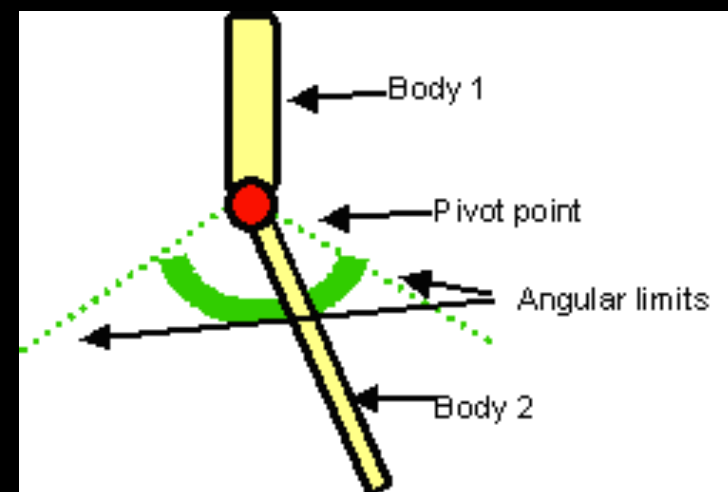
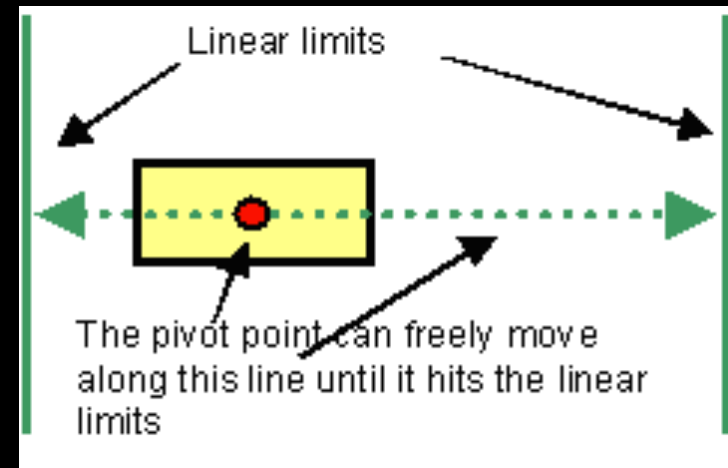
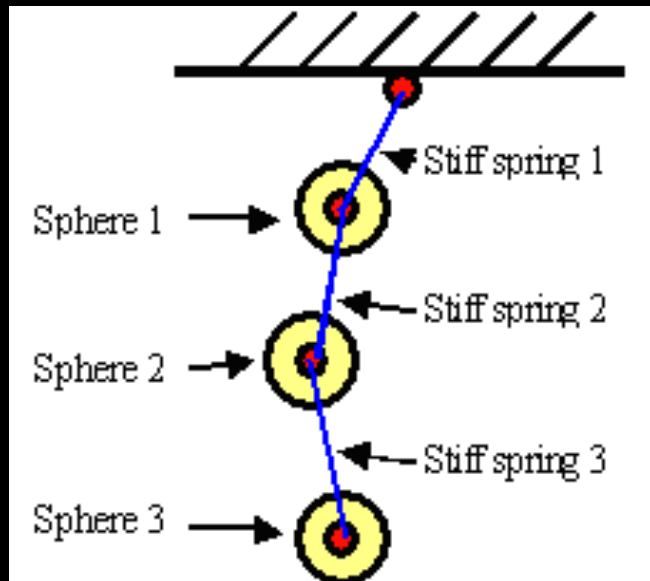
Static constraint definition



Dynamic simulation

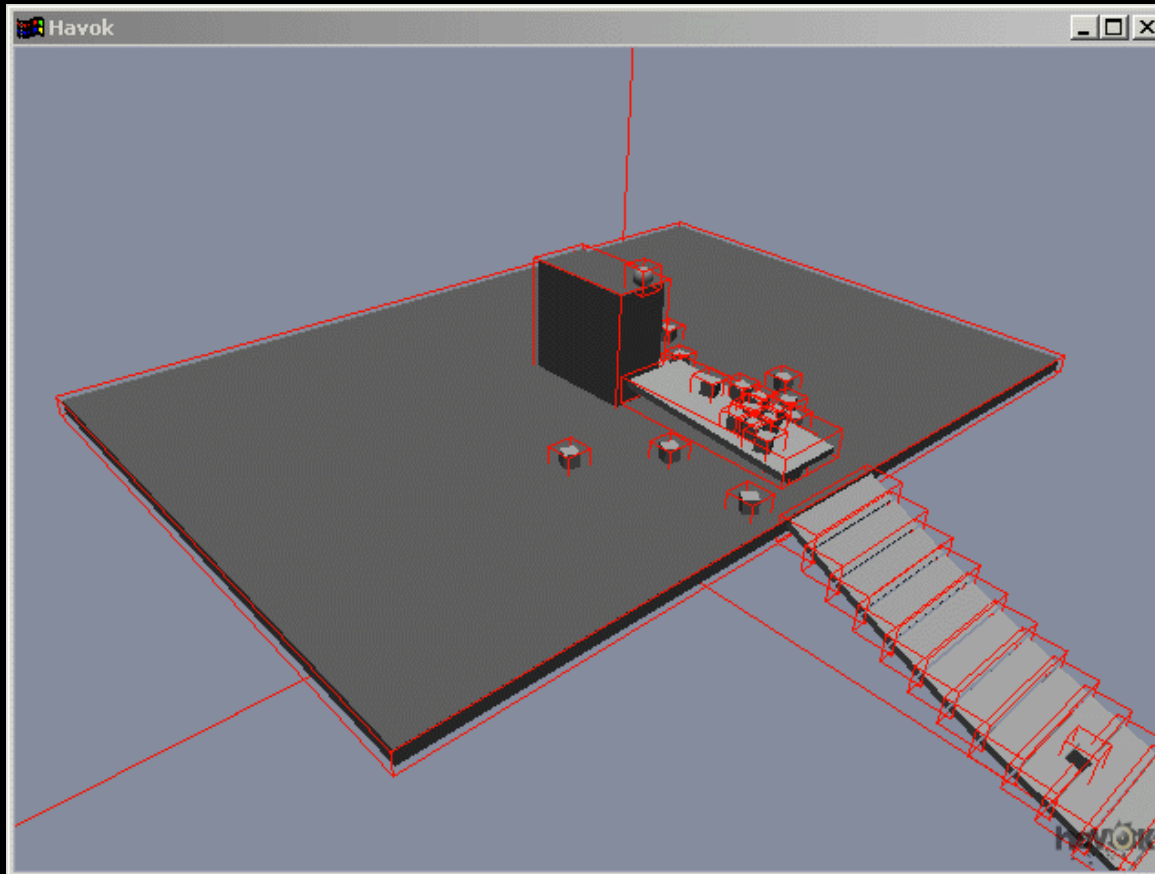


Constraints



Collision Detection

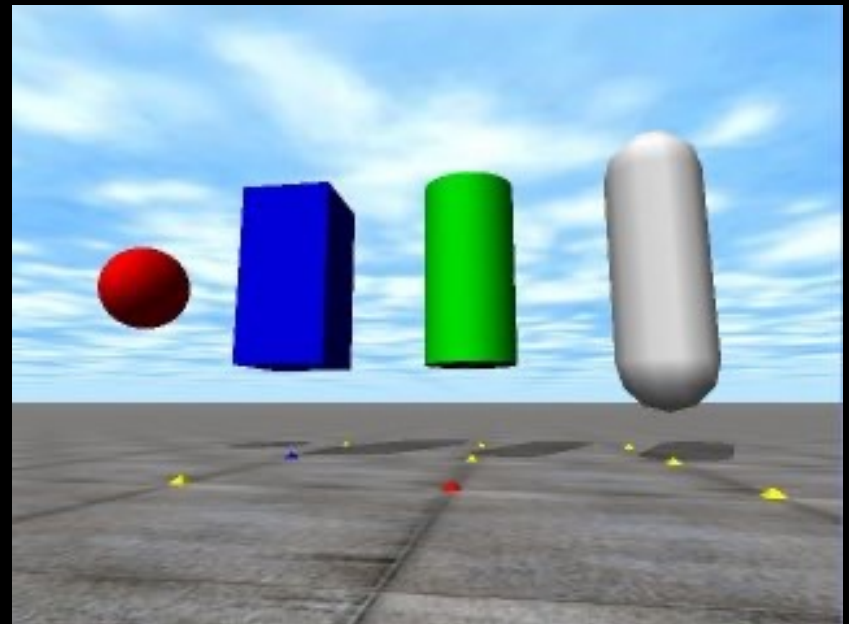
- Broad phase and narrow phase



Broad
phase

Collision Detection

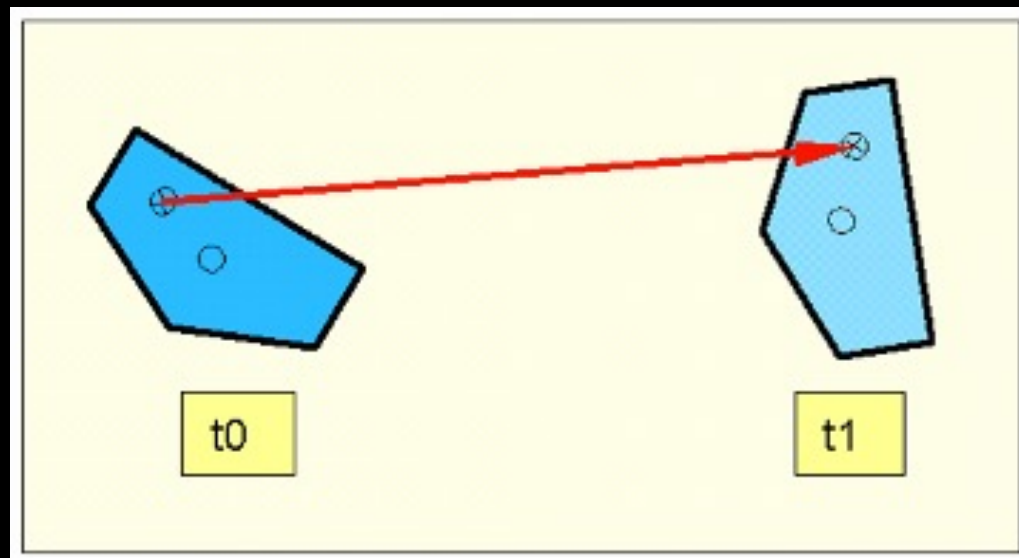
- Narrow phase
- Spheres
- AABBs
- Cylinders
- Capsules
- Compound shapes



Collision Detection: Queries

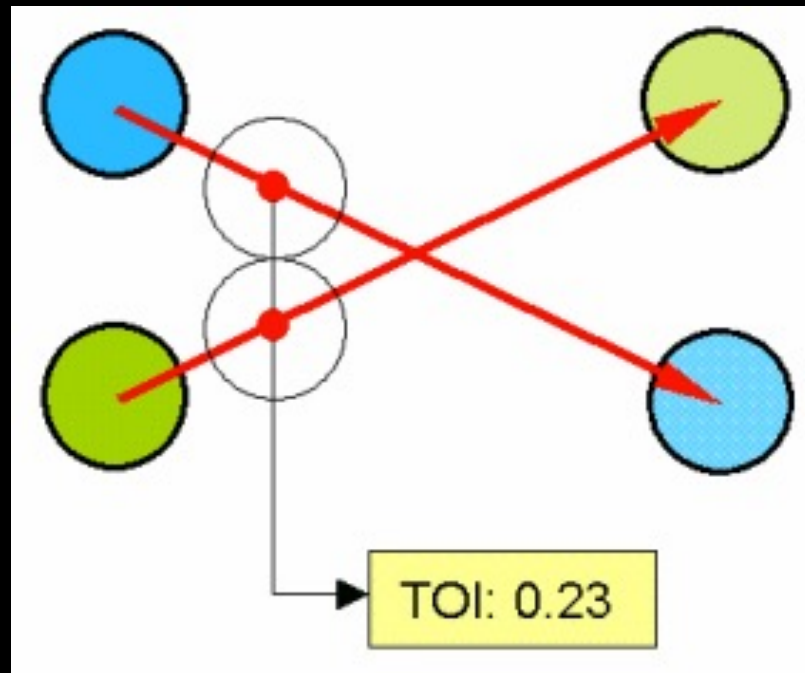
- Closest points between two bodies
- Whether two bodies penetrate
- Raycast a point through space and get colliding objects

Continuous Physics



Continuous Physics

- Time of impact:



Discrete Simulation

➤ Collision detection

- Calculate contacts

➤ Integration

- Solve constraints
- Integrate body state

REVERSED

Continuous Simulation

➤ Integration (Potential state)

- Solve contact constraints
- Integrate to a potential body state

➤ Collision detection

- Calculate potential contacts
- Generate TOI events

➤ while(TOI events present)

- Select involved objects
- Re-Calculate contact points
- Re-Integrate
- Re-Collide

➤ Client code to verify or correct:

- Allowed positions
- Interpenetration
- Tunneling