On the M^{-1} norm and Equation 2 in [Barbič et al. 2012]

Jernej Barbič Fun Shing Sin Eitan Grinspun Supplementary material to "Interactive Editing of Deformable Simulations"

Abstract

This document derives Equation 2 in [Barbič et al. 2012].

1 Derivation of Equation 2

First, let us explain why we used the M^{-1} weighted energy in Equation 1 in [Barbič et al. 2012]. Such an "energy" measures the total sum of squares of impulses (momentum; force times timestep) applied at each timestep (defined as Fh, where h is timestep). In mechanics, the proper norm for momentum is the inverse of mass. For a particle with momentum p, such a norm gives the particle's kinetic energy:

$$W_{\rm kin} = \frac{1}{2} < \frac{1}{m}p, p > = \frac{1}{2} < v, mv > . \tag{1}$$

Similarly, the proper norm for v is simply the mass, because it gives the kinetic energy: 1/2 < mv, v >.

The M^{-1} norm has the very elegant property that it works well with model reduction (which is usually a sign that the norm is the correct one). When inserting p = Uz into Equation 1 of [Barbič et al. 2012], with the M^{-1} weighting, the expression for E can be simplified as follows. Here, we omit the constant factors and the temporal discretization for brevity.

$$E = ||Mp'' + Dp' + Kp||_{M^{-1}}^2 = ||MUz'' + DUz' + KUz||_{M^{-1}}^2 = (2)$$

(Rayleigh damping)

$$= ||MUz'' + (\alpha M + \beta K)Uz' + KUz||_{M^{-1}}^{2} =$$
 (3)

(*U* are the modes: $KU = MU\Lambda$)

$$= ||MU(z'' + \alpha z') + MU\Lambda(z + \beta z')||_{M^{-1}}^{2} =$$
 (4)

(collecting MU)

$$= ||MU(z'' + \alpha z' + \Lambda(z + \beta z'))||_{M^{-1}}^{2} =$$
 (5)

(definition of M^{-1} norm)

$$< M^{-1}MU(z'' + \alpha z' + \Lambda(z + \beta z')), MU(z'' + \alpha z' + \Lambda(z + \beta z')) > =$$
(6)

(cancel M^{-1} and M)

$$\langle U(z'' + \alpha z' + \Lambda(z + \beta z')), MU(z'' + \alpha z' + \Lambda(z + \beta z')) \rangle = (7)$$

(move U in first factor to the other side (U^T))

$$\langle z'' + \alpha z' + \Lambda(z + \beta z'), U^T M U(z'' + \alpha z' + \Lambda(z + \beta z')) \rangle = (8)$$

(modes are mass-orthonormal, $U^TMU = I$)

$$\langle z'' + \alpha z' + \Lambda(z + \beta z'), z'' + \alpha z' + \Lambda(z + \beta z') \rangle =$$
 (9)

(definition of 2-norm)

$$= ||z'' + \alpha z' + \Lambda(z + \beta z')||_2^2 =$$
 (10)

(rearrange terms to collect damping terms)

$$= ||z'' + (\alpha + \beta \Lambda)z' + \Lambda z||_2^2, \tag{11}$$

which is the quantity used in Equation 2 in [Barbič et al. 2012].

References

BARBIČ, J., SIN, F., AND GRINSPUN, E. 2012. Interactive editing of deformable simulations. *ACM Trans. on Graphics (SIG-GRAPH 2012) 31*, 4.