

CS599: Convex and Combinatorial Optimization  
Fall 2013  
Lectures 5-6: Convex Functions

Instructor: Shaddin Dughmi

# Announcements

- HW1 is out, due Thursday 9/26
- Make sure you get email from me
- Today: Convex Functions
  - Read all of B&V Chapter 3.

# Outline

- 1 Convex Functions
- 2 Examples of Convex and Concave Functions
- 3 Convexity-Preserving Operations

## Convex Functions

A function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is **convex** if the line segment between any points on the graph of  $f$  lies above  $f$ . i.e. if  $x, y \in \mathbb{R}^n$  and  $\theta \in [0, 1]$ , then

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$$



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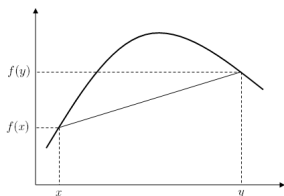
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- Analogous definition when the domain of  $f$  is a convex subset  $D$  of  $\mathbb{R}^n$



# Concave and Affine Functions

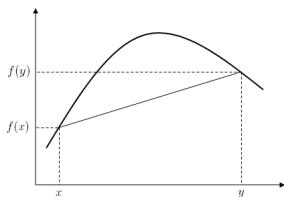


A function is  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is **concave** if  $-f$  is convex. Equivalently:

- Line segment between any points on the graph of  $f$  lies **below**  $f$ .
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$f : \mathbb{R}^n \rightarrow \mathbb{R}$  is **affine** if it is both concave and convex. Equivalently:

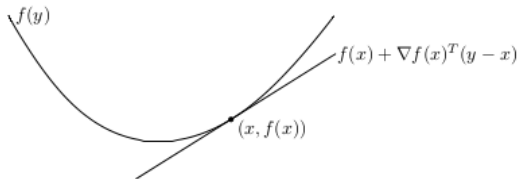
- Line segment between any points on the graph of  $f$  lies on the graph of  $f$ .
- $f(x) = a^\top x + b$  for some  $a \in \mathbb{R}^n$  and  $b \in \mathbb{R}$ .

We will now look at some equivalent definitions of convex functions

## First Order Definition

A differentiable  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is convex if and only if the first-order approximation centered at any point  $x$  underestimates  $f$  everywhere.

$$f(y) \geq f(x) + (\nabla f(x))^T(y - x)$$

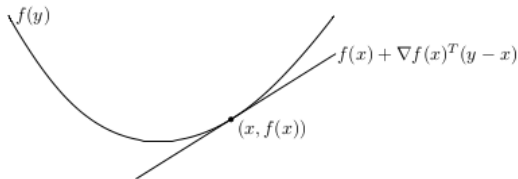


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- Local information  $\rightarrow$  global information
- If  $\nabla f(x) = 0$  then  $x$  is a global minimizer of  $f$

## Second Order Definition

A twice differentiable  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is convex if and only if its derivative is nondecreasing in all directions. Formally,

$$\nabla^2 f(x) \succeq 0$$

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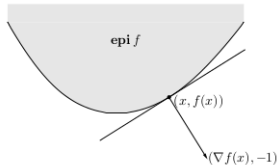
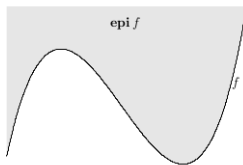
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## Interpretation

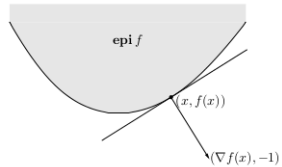
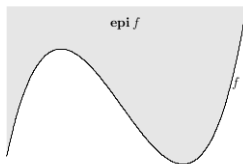
- Recall definition of PSD:  $z^\top \nabla^2 f(x) z > 0$  for all  $z \in \mathbb{R}^n$
- At  $x + \delta \vec{z}$ , infinitesimal change in gradient is in roughly in the same direction as  $\vec{z}$
- Graph of  $f$  curves upwards along any line
- When  $n = 1$ , this is  $f''(x) \geq 0$ .



## Epigraph

The epigraph of  $f$  is the set of points above the graph of  $f$ . Formally,

$$\text{epi}(f) = \{(x, t) : t \geq f(x)\}$$



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## Epigraph Definition

$f$  is a convex function if and only if its epigraph is a convex set.



# Jensen's Inequality (General Form)

$f : \mathbb{R}^n \rightarrow \mathbb{R}$  is convex if and only if

- For every  $x_1, \dots, x_k$  in the domain of  $f$ , and  $\theta_1, \dots, \theta_k \geq 0$  such that  $\sum_i \theta_i = 1$ , we have

$$f\left(\sum_i \theta_i x_i\right) \leq \sum_i \theta_i f(x_i)$$

- Given a probability measure  $\mathcal{D}$  on the domain of  $f$ , and  $x \sim \mathcal{D}$ ,

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Adding noise to  $x$  can only increase  $f(x)$  in expectation.

# Local and Global Optimality

## Local minimum

$x$  is a **local minimum** of  $f$  if there is an open ball  $B$  containing  $x$  where  $f(y) \geq f(x)$  for all  $y \in B$ .

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## Local minimum

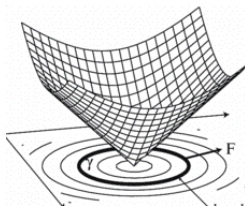
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When  $f$  is convex,  $x$  is a local minimum of  $f$  if and only if it is a global minimum.

- This fact underlies much of the tractability of convex optimization.

# Sub-level sets

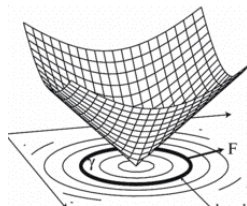


Level sets of  $f(x, y) = \sqrt{x^2 + y^2}$

## Sublevel set

The  $\alpha$ -sublevel set of  $f$  is  $\{x \in \text{domain}(f) : f(x) \leq \alpha\}$ .

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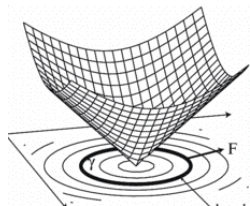
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## Fact

Every sub-level set of a convex function is a convex set.

- This fact also underlies tractability of convex optimization

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Note: converse false, but nevertheless useful check.

## Continuity

Convex functions are continuous.



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## Extended-value extension

If a function  $f : D \rightarrow \mathbb{R}$  is convex on its domain, and  $D$  is convex, then it can be extended to a convex function on  $\mathbb{R}^n$ . by setting  $f(x) = \infty$  whenever  $x \notin D$ .

This simplifies notation. Resulting function  $\tilde{f} : D \rightarrow \mathbb{R} \cup \infty$  is “convex” with respect to the ordering on  $\mathbb{R} \cup \infty$

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# Functions on the reals

- Affine:  $ax + b$
- Exponential:  $e^{ax}$  convex for any  $a \in \mathbb{R}$
- Powers:  $x^a$  convex on  $\mathbb{R}_{++}$  when  $a \geq 1$  or  $a \leq 0$ , and concave for  $0 \leq a \leq 1$
- Logarithm:  $\log x$  concave on  $\mathbb{R}_{++}$ .

# Norms

Norms are convex.

$$\|\theta x + (1 - \theta)y\| \leq \|\theta x\| + \|(1 - \theta)y\| = \theta\|x\| + (1 - \theta)\|y\|$$

- Uses both norm axioms: triangle inequality, and homogeneity.
- Applies to matrix norms, such as the spectral norm (radius of induced ellipsoid)

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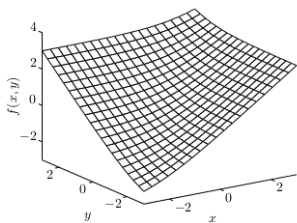
## Max

$\max_i x_i$  is convex

$$\begin{aligned}\max_i (\theta x + (1 - \theta)y)_i &= \max_i (\theta x_i + (1 - \theta)y_i) \\ &\leq \max_i \theta x_i + \max_i (1 - \theta)y_i \\ &= \theta \max_i x_i + (1 - \theta) \max_i y_i\end{aligned}$$

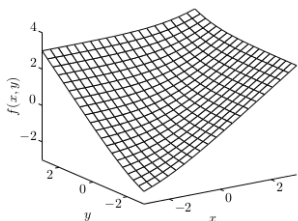
If i'm allowed to pick the maximum entry of  $\theta x$  and  $\theta y$  independently, I can do only better.

- Log-sum-exp:  $\log(e^{x_1} + e^{x_2} + \dots + e^{x_n})$  is convex
- Geometric mean:  $(\prod_{i=1}^n x_i)^{\frac{1}{n}}$  is concave
- Log-determinant:  $\log \det X$  is concave
- Quadratic form:  $x^T A x$  is convex iff  $A \succeq 0$
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Proving convexity often comes down to case-by-case reasoning, involving:

- Definition: restrict to line and check Jensen's inequality
- Write down the Hessian and prove PSD
- Express as a combination of other convex functions through convexity-preserving operations (Next)

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## Nonnegative Weighted Combinations

If  $f_1, f_2, \dots, f_k$  are convex, and  $w_1, w_2, \dots, w_k \geq 0$ , then  $g = w_1 f_1 + w_2 f_2 \dots + w_k f_k$  is convex.

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proof ( $k = 2$ )

$$\begin{aligned} g\left(\frac{x+y}{2}\right) &= w_1 f_1\left(\frac{x+y}{2}\right) + w_2 f_2\left(\frac{x+y}{2}\right) \\ &\leq w_1 \frac{f_1(x) + f_1(y)}{2} + w_2 \frac{f_2(x) + f_2(y)}{2} \\ &= \frac{g(x) + g(y)}{2} \end{aligned}$$

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Extends to integrals  $g(x) = \int_y w(y) f_y(x)$  with  $w(y) \geq 0$ , and therefore expectations  $\mathbf{E}_y f_y(x)$ .

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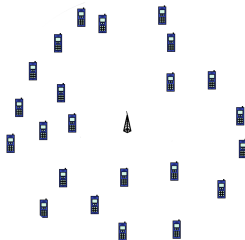
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## Worth Noting

Minimizing the expectation of a random convex cost function is also a convex optimization problem!

- A **stochastic** convex optimization problem is a convex optimization problem.

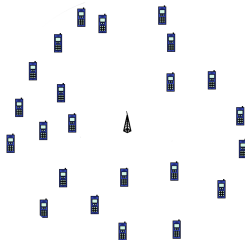
# Example: Stochastic Facility Location



## Average Distance

- $k$  customers located at  $y_1, y_2, \dots, y_k \in \mathbb{R}^n$
- If I place a facility at  $x \in \mathbb{R}^n$ , average distance to a customer is 
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- Since distance to any one customer is convex in  $x$ , so is the average distance.
- Extends to probability measure over customers

## Implication

Convex functions are a convex cone in the vector space of functions from  $\mathbb{R}^n$  to  $\mathbb{R}$ .

The set of convex functions is the intersection of an infinite set of homogeneous linear inequalities indexed by  $x, y, \theta$

$$f(\theta x + (1 - \theta)y) - \theta f(x) + (1 - \theta)f(y) \leq 0$$

## Composition with Affine Function

If  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is convex, and  $A \in \mathbb{R}^{n \times m}$ ,  $b \in \mathbb{R}^n$ , then

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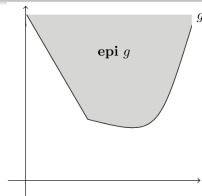
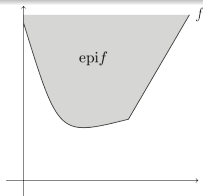


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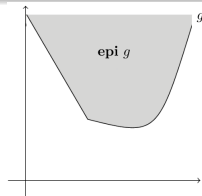
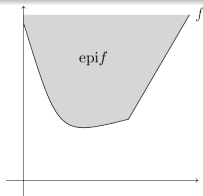
$$(x, t) \in \mathbf{graph}(g) \iff t = g(x) = f(Ax+b) \iff (Ax+b, t) \in \mathbf{graph}(f)$$

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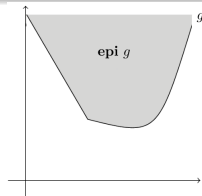
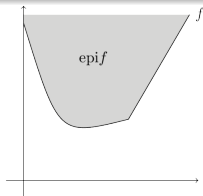
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$\mathbf{epi}(g)$  is the inverse image of  $\mathbf{epi}(f)$  under the affine mapping  
 $(x, t) \rightarrow (Ax + b, t)$

## Examples

- $\|Ax + b\|$  is convex
- $\max(Ax + b)$  is convex
- $\log(e^{a_1^\top x + b_1} + e^{a_2^\top x + b_2} + \dots + e^{a_n^\top x + b_n})$  is convex

## Maximum

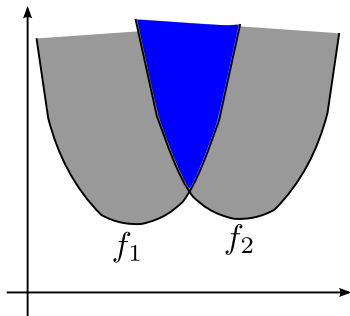
If  $f_1, f_2$  are convex, then  $g(x) = \max \{f_1(x), f_2(x)\}$  is also convex.

Generalizes to the maximum of any number of functions,  $\max_{i=1}^k f_i(x)$ , and also to the supremum of an infinite set of functions  $\sup_y f_y(x)$ .

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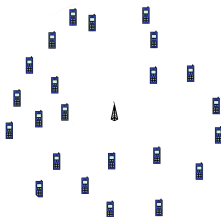
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$$\text{epi } g = \text{epi } f_1 \cap \text{epi } f_2$$

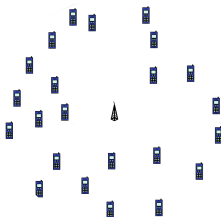
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## Maximum Distance

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- If I place a facility at  $x \in \mathbb{R}^n$ , maximum distance to a customer is  $g(x) = \max_i \|x - y_i\|$

# Example: Robust Facility Location



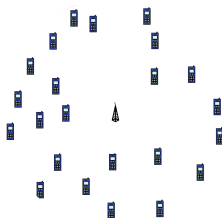
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Since distance to any one customer is convex in  $x$ , so is the worst-case distance.



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## Worth Noting

When a convex cost function is uncertain, minimizing the **worst-case** cost is also a convex optimization problem!

- A **robust** (in the worst-case sense) convex optimization problem is a convex optimization problem.

## Other Examples

- Maximum eigenvalue of a symmetric matrix  $A$  is convex in  $A$

$$\max \{v^T A v : \|v\| = 1\}$$

- Sum of  $k$  largest components of a vector  $x$  is convex in  $x$

$$\max \left\{ \vec{\mathbf{1}}_S \cdot x : |S| = k \right\}$$

## Minimization

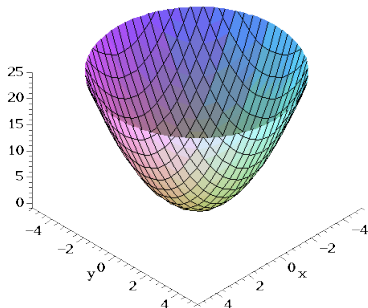
If  $f(x, y)$  is convex and  $\mathcal{C}$  is convex and nonempty, then  $g(x) = \inf_{y \in \mathcal{C}} f(x, y)$  is convex.

## Minimization

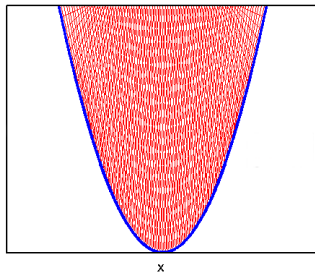
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Proof (for  $\mathcal{C} = \mathbb{R}^k$ )

$\text{epi } g$  is the projection of  $\text{epi } f$  onto hyperplane  $y = 0$ .



$$f(x, y) = x^2 + y^2$$



$$g(x) = x^2$$

## Example

Distance from a convex set  $\mathcal{C}$

$$f(x, y) = \inf_{y \in \mathcal{C}} \|x - y\|$$

## Composition Rules

If  $g : \mathbb{R}^n \rightarrow \mathbb{R}^k$  and  $h : \mathbb{R}^k \rightarrow \mathbb{R}$ , then  $f = h \circ g$  is convex if

- $g_i$  are convex, and  $h$  is convex and nondecreasing in each argument.
- $g_i$  are concave, and  $h$  is convex and nonincreasing in each argument.

## Proof ( $n = k = 1$ )

$$f''(x) = h''(g(x))g'(x)^2 + h'(g(x))g''(x)$$

## Perspective

If  $f$  is convex then  $g(x, t) = tf(x/t)$  is also convex.

## Proof

$\text{epi } g$  is inverse image of  $\text{epi } f$  under the perspective function.