CS675: Convex and Combinatorial Optimization Fall 2014 Introduction to Linear Programming

Instructor: Shaddin Dughmi

Outline

- Linear Programming Basics
- 2 Duality and Its Interpretations
- Properties of Duals
 - Weak and Strong Duality
- 5 Formal Proof of Strong Duality of LP
- 6 Consequences of Duality
 - More Examples of Duality

Outline



- 2 Duality and Its Interpretations
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- Consequences of Duality
- 7 More Examples of Duality

- The forefather of convex optimization problems, and the most ubiquitous.
- Developed by Kantorovich during World War II (1939) for planning the Soviet army's expenditures and returns. Kept secret.
- Discovered a few years later by George Dantzig, who in 1947 developed the simplex method for solving linear programs
- John von Neumann developed LP duality in 1947, and applied it to game theory
- Polynomial-time algorithms: Ellipsoid method (Khachiyan 1979), interior point methods (Karmarkar 1984).

 $\begin{array}{ll} \text{minimize (or maximize)} & c^{\mathsf{T}}x\\ \text{subject to} & a_i^{\mathsf{T}}x \leq b_i, \quad \text{for } i \in \mathcal{C}^1.\\ & a_i^{\mathsf{T}}x \geq b_i, \quad \text{for } i \in \mathcal{C}^2.\\ & a_i^{\mathsf{T}}x = b_i, \quad \text{for } i \in \mathcal{C}^3. \end{array}$

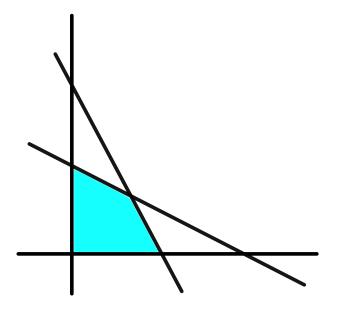
- Decision variables: $x \in \mathbb{R}^n$
- Parameters:
 - $c \in \mathbb{R}^n$ defines the linear objective function
 - $a_i \in \mathbb{R}^n$ and $b_i \in \mathbb{R}$ define the *i*'th constraint.

 $\begin{array}{ll} \text{maximize} & c^{\intercal}x\\ \text{subject to} & a_i^{\intercal}x \leq b_i, & \text{for } i=1,\ldots,m.\\ & x_j \geq 0, & \text{for } j=1,\ldots,n. \end{array}$

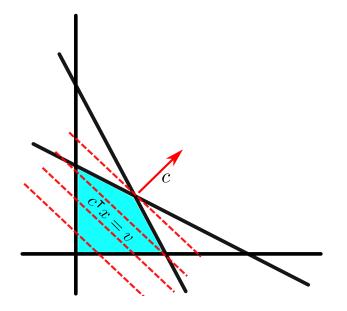
Every LP can be transformed to this form

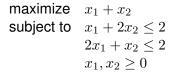
- minimizing $c^{\mathsf{T}}x$ is equivalent to maximizing $-c^{\mathsf{T}}x$
- \geq constraints can be flipped by multiplying by -1
- Each equality constraint can be replaced by two inequalities
- Uconstrained variable x_j can be replaced by $x_j^+ x_j^-$, where both x_j^+ and x_j^- are constrained to be nonnegative.

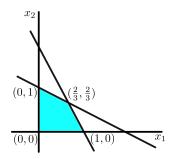
Geometric View



Geometric View





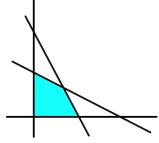


- *n* products, *m* raw materials
- Every unit of product j uses a_{ij} units of raw material i
- There are b_i units of material i available
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- Facility wants to maximize profit subject to available raw materials

$$\begin{array}{ll} \text{maximize} & c^{\mathsf{T}}x\\ \text{subject to} & a_i^{\mathsf{T}}x \leq b_i, & \text{for } i=1,\ldots,m,\\ & x_j \geq 0, & \text{for } j=1,\ldots,n. \end{array}$$

Terminology

- Hyperplane: The region defined by a linear equality
- Halfspace: The region defined by a linear inequality $a_i^{\mathsf{T}} x \leq b_i$.
- Polyhedron: The intersection of a set of linear inequalities
 - Feasible region of an LP is a polyhedron
- Polytope: Bounded polyhedron
 - Equivalently: convex hull of a finite set of points
- Vertex: A point x is a vertex of polyhedron P if $\exists y \neq 0$ with
 - $x + y \in P$ and $x y \in P$
- Face of *P*: The intersection with *P* of a hyperplane *H* disjoint from the interior of *P*



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Feasible regions of LPs (i.e. polyhedrons) are convex

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Set of optimal solutions of an LP is convex

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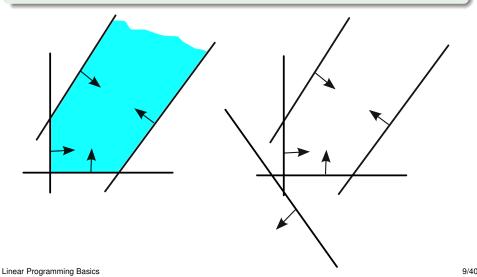
Fact

At a vertex, n linearly independent constraints are satisfied with equality (a.k.a. tight)

Basic Facts about LPs and Polyhedrons

Fact

An LP either has an optimal solution, or is unbounded or infeasible



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- Assume not, and take a non-vertex optimal solution x with the maximum number of tight constraints
- There is $y \neq 0$ s.t. $x \pm y$ are feasible
- *y* is perpendicular to the objective function and the tight constraints at *x*.
 - i.e. $c^{\mathsf{T}}y = 0$, and $a_i^{\mathsf{T}}y = 0$ whenever the *i*'th constraint is tight for x.

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- Let α be the largest constant such that $x + \alpha y$ is feasible
 - Such an α exists

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- Can choose y s.t. $y_j < 0$ for some j
- Let α be the largest constant such that $x + \alpha y$ is feasible
 - Such an α exists
- An additional constraint becomes tight at $x + \alpha y$, a contradiction.

Corollary

If an LP in standard form has an optimal solution, then there is an optimal solution with at most m non-zero variables.

maximize
$$c^{\mathsf{T}}x$$

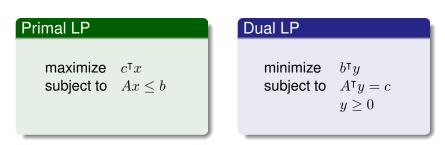
subject to $a_i^{\mathsf{T}}x \leq b_i$, for $i = 1, \dots, m$.
 $x_j \geq 0$, for $j = 1, \dots, n$.

• e.g. for optimal production with *n* products and *m* raw materials, there is an optimal plan with at most *m* products.

Outline

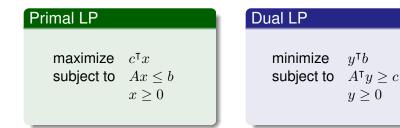
Linear Programming Basics

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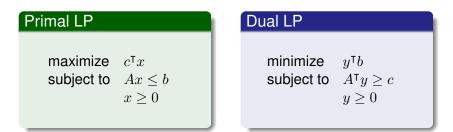
- $A \in \mathbb{R}^{m imes n}$, $c \in \mathbb{R}^n$, $b \in \mathbb{R}^m$
- y_i is the dual variable corresponding to primal constraint $A_i x \leq b_i$
- $A_j^T y \ge c_j$ is the dual constraint corresponding to primal variable x_j

Linear Programming Duality: Standard Form, and Visualization



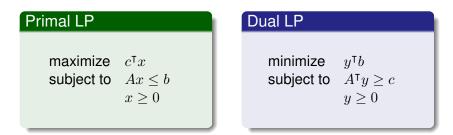
y > 0

Linear Programming Duality: Standard Form, and Visualization



	x_1	x_2	x_3	x_4	
y_1	a_{11}	a_{12}	a_{13}	a_{14}	b_1
y_2	a_{21}	a_{22}	a_{23}	a_{24}	b_2
y_3	a_{31}	a_{32}	a_{33}	a_{34}	b_3
	c_1	c_2	c_3	c_4	

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• y_i is the dual variable corresponding to primal constraint $A_i x \le b_i$ • $A_j^T y \ge c_j$ is the dual constraint corresponding to primal variable x_j Duality and Its Interpretations

Recall the Optimal Production problem from last lecture

- *n* products, *m* raw materials
- Every unit of product j uses a_{ij} units of raw material i
- There are b_i units of material i available
- Product j yields profit c_j per unit
- Facility wants to maximize profit subject to available raw materials

Primal LP

$$\begin{array}{ll} \max & \sum_{j=1}^{n} c_j x_j \\ \text{s.t.} & \sum_{j=1}^{n} a_{ij} x_j \leq b_i, & \text{for } i \in [m]. \\ & x_j \geq 0, & \text{for } j \in [n]. \end{array}$$

Primal LPDual LPmax
$$\sum_{j=1}^{n} c_j x_j$$

 $\sum_{j=1}^{n} a_{ij} x_j \leq b_i$, for $i \in [m]$.
 $x_j \geq 0$, for $j \in [n]$.min $\sum_{i=1}^{m} b_i y_i$
 $s.t. $\sum_{i=1}^{m} a_{ij} y_i \geq c_j$, for $j \in [n]$.
 $y_i \geq 0$, for $i \in [m]$.$

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- Dual variable y_i is a proposed price per unit of raw material i
- Dual price vector is feasible if facility has incentive to sell materials
- Buyer wants to spend as little as possible to buy materials

Duality and Its Interpretations

Consider the simple LP from last lecture

maximize
$$x_1 + x_2$$

subject to $x_1 + 2x_2 \le 2$
 $2x_1 + x_2 \le 2$
 $x_1, x_2 \ge 0$

• We found that the optimal solution was at $(\frac{2}{3}, \frac{2}{3})$, with an optimal value of 4/3.

Consider the simple LP from last lecture

maximize $x_1 + x_2$ subject to $x_1 + 2x_2 \le 2$ $2x_1 + x_2 \le 2$ $x_1, x_2 \ge 0$

- We found that the optimal solution was at $(\frac{2}{3}, \frac{2}{3})$, with an optimal value of 4/3.
- What if, instead of finding the optimal solution, we saught to find an upperbound on its value by combining inequalities?
 - Each inequality implies an upper bound of 2
 - Multiplying each by $\frac{1}{3}$ and summing gives $x_1 + x_2 \le 4/3$.

Interpretation 2: Finding the Best Upperbound

	x_1	x_2	x_3	x_4	
y_1	a_{11}	a_{12}	a_{13}	a_{14}	b_1
y_2	a_{21}	a_{22}	a_{23}	a_{24}	b_2
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	c_1	c_2	c_3	c_4	

• Multiplying each row i by y_i and summing gives the inequality

 $y^TAx \leq y^Tb$

Interpretation 2: Finding the Best Upperbound

	x_1	x_2	x_3	x_4	
y_1	a_{11}	$a_{12} \\ a_{22} \\ a_{32}$	a_{13}	a_{14}	b_1
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y_3	a_{31}	a_{32}	a_{33}	a_{34}	b_3
	c_1	c_2	c_3	c_4	

- Multiplying each row i by y_i and summing gives the inequality $y^T A x \leq y^T b$
- When $y^T A \ge c^T$, the right hand side of the inequality is an upper bound on $c^T x$ for every feasible x.

$$c^T x \le y^T A x \le y^T b$$

Interpretation 2: Finding the Best Upperbound

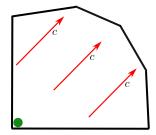
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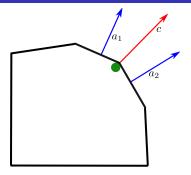
$$c^T x \le y^T A x \le y^T b$$

 The dual LP can be thought of as trying to find the best upperbound on the primal that can be achieved this way.

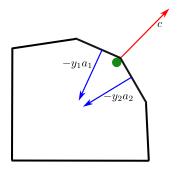
Duality and Its Interpretations



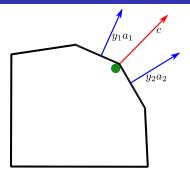
• Apply force field c to a ball inside bounded polytope $Ax \leq b$.



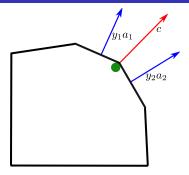
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- Eventually, ball will come to rest against the walls of the polytope.



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- Since the ball is still, $c^T = \sum_i y_i a_i = y^T A$.

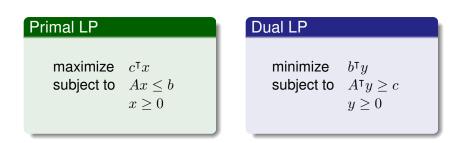


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- Wall $a_i x \leq b_i$ applies some force $-y_i a_i$ to the ball
- Since the ball is still, $c^T = \sum_i y_i a_i = y^T A$.
- Dual can be thought of as trying to minimize "work" ∑_i y_ib_i to bring ball back to origin by moving polytope
- We will see that, at optimality, only the walls adjacent to the ball push (Complementary Slackness)

Duality and Its Interpretations

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Duality is an Inversion

Given a primal LP in standard form, the dual of its dual is itself.

Primal LP		Dual	LP		
max s.t.	$\sum_{j=1}^{n} c_j x_j$ $\sum_{j=1}^{n} a_{ij} x_j \le b_i,$ $x_j \ge 0,$	for $i \in [m]$. for $j \in [n]$.	min s.t.	$\sum_{i=1}^{m} b_i y_i$ $\sum_{i=1}^{m} a_{ij} y_i \ge c_j,$ $y_i \ge 0,$	for $j \in [n]$. for $i \in [m]$.

Primal LP	Dual LP
$\begin{array}{ll} \max & \sum_{j=1}^{n} c_{j} x_{j} \\ \text{s.t.} \\ y_{i}: & \sum_{j=1}^{n} a_{ij} x_{j} \leq b_{i}, & \text{for } i \in [m]. \\ & x_{j} \geq 0, & \text{for } j \in [n]. \end{array}$	$\begin{array}{ll} \min & \sum_{i=1}^{m} b_i y_i \\ \text{s.t.} & \\ & \sum_{i=1}^{m} a_{ij} y_i \geq c_j, & \text{for } j \in [n]. \\ & y_i \geq 0, & \text{for } i \in [m]. \end{array}$

• The *i*'th primal constraint gives rise to the *i*'th dual variable y_i

Primal LP		Dual	LP		
s.t. $y_i: \sum$	$\sum_{j=1}^{n} c_j x_j$ $\sum_{j=1}^{n} a_{ij} x_j \le b_i,$ $j \ge 0,$	for $i \in [m]$. for $j \in [n]$.	s.t.	$\sum_{i=1}^{m} b_i y_i$ $\sum_{i=1}^{m} a_{ij} y_i \ge c_j,$ $y_i \ge 0,$	for $j \in [n]$. for $i \in [m]$.

- The *i*'th primal constraint gives rise to the *i*'th dual variable y_i
- The *j*'th primal variable x_j gives rise to the *j*'th dual constraint

Syntactic Rules

Primal LP	Dual LP
$\begin{array}{ll} \max & c^{\intercal}x \\ \text{s.t.} \\ y_i: & a_ix \leq b_i, \text{for } i \in \mathcal{C}_1. \\ y_i: & a_ix = b_i, \text{for } i \in \mathcal{C}_2. \\ & x_j \geq 0, \text{for } j \in \mathcal{D}_1. \\ & x_j \in \mathbb{R}, \text{for } j \in \mathcal{D}_2. \end{array}$	$\begin{array}{ll} \min & b^{T}y \\ \text{s.t.} \\ x_j: & \overline{a}_j^{T}y \geq c_j, \text{for } j \in \mathcal{D}_1. \\ x_j: & \overline{a}_j^{T}y = c_j, \text{for } j \in \mathcal{D}_2. \\ & y_i \geq 0, \text{for } i \in \mathcal{C}_1. \\ & y_i \in \mathbb{R}, \text{for } i \in \mathcal{C}_2. \end{array}$

Rules of Thumb

- Loose constraint (i.e. inequality) ⇒ tight dual variable (i.e. nonnegative)
- Tight constraint (i.e. equality) ⇒ loose dual variable (i.e. unconstrained)

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Weak Duality



Theorem (Weak Duality)

For every primal feasible x and dual feasible y, we have $c^{\intercal}x \leq b^{\intercal}y$.

Corollary

- If primal and dual both feasible and bounded, $OPT(Primal) \le OPT(Dual)$
- If primal is unbounded, dual is infeasible
- If dual is unbounded, primal is infeasible

Weak Duality



Theorem (Weak Duality)

For every primal feasible x and dual feasible y, we have $c^{\intercal}x \leq b^{\intercal}y$.

Corollary

If x is primal feasible, and y is dual feasible, and $c^{\intercal}x = b^{\intercal}y$, then both are optimal.

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Upperbound Interpretation

Self explanatory

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Upperbound Interpretation

Self explanatory

Physical Interpretation

Work required to bring ball back to origin by pulling polytope is at least potential energy difference between origin and primal optimum.

Primal LP

 $\begin{array}{ll} \text{maximize} & c^{\mathsf{T}}x\\ \text{subject to} & Ax \leq b\\ & x \geq 0 \end{array}$

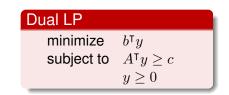
Dual LP

 $\begin{array}{ll} \mbox{minimize} & b^{\mathsf{T}}y \\ \mbox{subject to} & A^{\mathsf{T}}y \geq c \\ & y \geq 0 \end{array}$

$$c^{\mathsf{T}}x \leq y^{\mathsf{T}}Ax \leq y^{\mathsf{T}}b$$

Weak and Strong Duality

Primal LP	
maximize	
subject to	$\begin{array}{l} Ax \leq b \\ x \geq 0 \end{array}$



Theorem (Strong Duality)

If either the primal or dual is feasible and bounded, then so is the other and OPT(Primal) = OPT(Dual).

Buyer can offer prices for raw materials that would make facility indifferent between production and sale.

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Upperbound Interpretation

The method of scaling and summing inequalities yields a tight upperbound on the primal optimal value.

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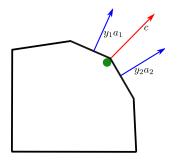
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Physical Interpretation

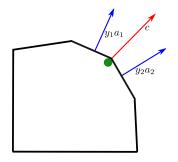
There is an assignment of forces to the walls of the polytope that brings ball back to the origin without wasting energy.

Informal Proof of Strong Duality



• Recall the physical interpretation of duality

Informal Proof of Strong Duality

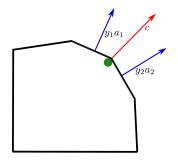


- Recall the physical interpretation of duality
- When ball is stationary at x, we expect force c to be neutralized only by constraints that are tight. i.e. force multipliers $y \ge 0$ s.t.

•
$$y^{\mathsf{T}}A = c$$

•
$$y_i(b_i - a_i x) = 0$$

Informal Proof of Strong Duality



- Recall the physical interpretation of duality
- When ball is stationary at x, we expect force c to be neutralized only by constraints that are tight. i.e. force multipliers $y \ge 0$ s.t.

•
$$y^{\mathsf{T}} A = c$$

• $y_i(b_i - a_i x) = 0$
 $y^{\mathsf{T}} b - c^{\mathsf{T}} x = y^{\mathsf{T}} b - y^T A x = \sum_i y_i(b_i - a_i x) = 0$

We found a primal and dual solution that are equal in value!

Weak and Strong Duality

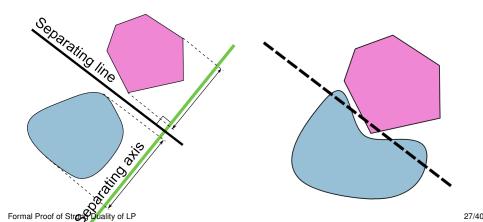
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Outline

- Linear Programming Basics
- 2 Duality and Its Interpretations
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Separating Hyperplane Theorem

If $A, B \subseteq \mathbb{R}^n$ are disjoint convex sets, then there is a hyperplane separating them. That is, there is $a \in \mathbb{R}^n$ and $b \in \mathbb{R}$ such that $a^{\mathsf{T}}x \leq b$ for every $x \in A$ and $a^{\mathsf{T}}y \geq b$ for every $y \in B$. Moreover, if one of A or Bis compact, then there is a hyperplane strictly separating them (i.e. $a^T x < b$ for $x \in A$ and $a^T y > b$ for $y \in B$).



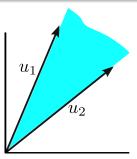
Definition

A convex cone is a convex subset of \mathbb{R}^n which is closed under nonnegative scaling and convex combinations.

Definition

The convex cone generated by vectors $u_1, \ldots, u_m \in \mathbb{R}^n$ is the set of all nonnegative-weighted sums of these vectors (also known as conic combinations).

$$Cone(u_1,\ldots,u_m) = \left\{ \sum_{i=1}^m \alpha_i u_i : \alpha_i \ge 0 \ \forall i \right\}$$

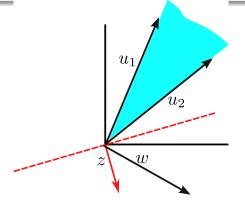


The following follows from the separating hyperplane Theorem (try to prove it).

Farkas' Lemma

Let C be the convex cone generated by vectors $u_1, \ldots, u_m \in \mathbb{R}^n$, and let $w \in \mathbb{R}^n$. Exactly one of the following is true:

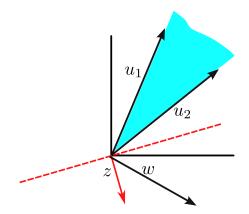
- $\bullet \ w \in \mathcal{C}$
- There is $z \in \mathbb{R}^n$ such that $z \cdot u_i \leq 0$ for all i, and $z \cdot w > 0$.



Equivalently: Theorem of the Alternative

One of the following is true, where $U = [u_1, \ldots, u_m]$

- The system Uy = w, $y \ge 0$ has a solution
- The system $U^{\intercal}z \leq 0$, $z^{\intercal}w > 0$ has a solution.



Formal Proof of Strong Duality

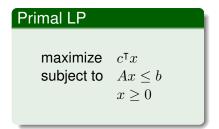
Primal LP	Dual LP
maximize $c^\intercal x$	minimize $b^{\intercal}y$
subject to $Ax \leq b$	subject to $A^{\intercal}y = c$
	$y \ge 0$

Given $v \in \mathbb{R}$, by Farkas' Lemma one of the following is true • The system $\begin{pmatrix} A^{\mathsf{T}} & 0 \\ b^{\mathsf{T}} & 1 \end{pmatrix} w = \begin{pmatrix} c \\ v \end{pmatrix}$, $w \ge 0$ has a solution. • Let $y \in \mathbb{R}^m_+$ and $\delta \in \mathbb{R}_+$ be such that $w = \begin{pmatrix} y \\ \delta \end{pmatrix}$ Implies dual is feasible and OPT(dual) < v2 The system $\begin{pmatrix} A & b \\ 0 & 1 \end{pmatrix} z \le 0, z^{\mathsf{T}} \begin{pmatrix} c \\ v \end{pmatrix} > 0$ has a solution. • Let $z = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$, where $z_1 \in \mathbb{R}^n$ and $z_2 \in \mathbb{R}$ with $z_2 \leq 0$ • When $z_2 \neq 0$, $x = -z_1/z_2$ is feasible and $c^T x \geq v$ • When $z_2 = 0$, dual is infeasible, and primal is either infeasible or unbounded (prove it)

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Complementary Slackness



Dual LP

minimize $y^{\intercal}b$ subject to $A^{\intercal}y \ge c$

 $y \ge 0$

Complementary Slackness

Primal LPDumaximize $c^{\intercal}x$ subject to $Ax \le b$ $x \ge 0$

Dual LPminimize $y^{\mathsf{T}}b$ subject to $A^{\mathsf{T}}y \ge c$ $y \ge 0$

• Let $s_i = (b - Ax)_i$ be the *i*'th primal slack variable

• Let $t_j = (A^{\mathsf{T}}y - c)_j$ be the *j*'th dual slack variable

Complementary Slackness

Primal LPmaximize $c^{\intercal}x$ subject to $Ax \le b$ $x \ge 0$

Dual LP

 $\begin{array}{ll} \mbox{minimize} & y^{\intercal}b \\ \mbox{subject to} & A^{\intercal}y \geq c \\ & y \geq 0 \end{array}$

Let s_i = (b - Ax)_i be the *i*'th primal slack variable
Let t_j = (A^Ty - c)_j be the *j*'th dual slack variable

Complementary Slackness

x and y are optimal if and only if

•
$$x_j t_j = 0$$
 for all $j = 1, \ldots, n$

• $y_i s_i = 0$ for all i = 1, ..., m

	x_1	x_2	x_3	x_4	
y_1	a_{11}	a_{12}	a_{13}	a_{14}	b_1
y_2	a_{21}		a_{23}	a_{24}	b_2
y_3	a_{31}	a_{32}	a_{33}	a_{34}	b_3
	c_1	c_2	c_3	c_4	

Interpretation of Complementary Slackness

Economic Interpretation

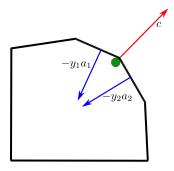
Given an optimal primal production vector x and optimal dual offer prices y,

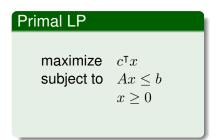
- Facility produces only products for which it is indifferent between sale and production.
- Only raw materials that are binding constraints on production are priced greater than 0

Interpretation of Complementary Slackness

Physical Interpretation

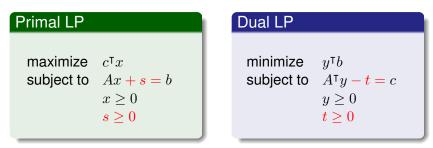
Only walls adjacent to the balls equilibrium position push back on it.



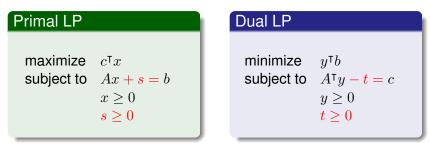


Dual LP

 $\begin{array}{ll} \mbox{minimize} & y^{\intercal}b \\ \mbox{subject to} & A^{\intercal}y \geq c \\ & y \geq 0 \end{array}$

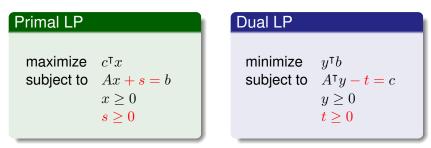


Can equivalently rewrite LP using slack variables



Can equivalently rewrite LP using slack variables

$$y^{\mathsf{T}}b - c^{\mathsf{T}}x = y^{\mathsf{T}}(Ax + s) - (y^{\mathsf{T}}A - t^{\mathsf{T}})x = y^{\mathsf{T}}s + t^{\mathsf{T}}x$$



• Can equivalently rewrite LP using slack variables

$$y^{\mathsf{T}}b - c^{\mathsf{T}}x = y^{\mathsf{T}}(Ax + s) - (y^{\mathsf{T}}A - t^{\mathsf{T}})x = y^{\mathsf{T}}s + t^{\mathsf{T}}x$$

Gap between primal and dual objectives is 0 if and only if complementary slackness holds.

- Will encounter LPs where the dual is easier to solve than primal
- Complementary slackness allows us to recover the primal optimal from the dual optimal, and vice versa.

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Primal LP (n variables, $m + n$ constraints)	Dual LP (<i>m</i> variables, $m + n$ constraints)
$\begin{array}{ll} \mbox{maximize} & c^{\intercal}x\\ \mbox{subject to} & Ax \leq b\\ & x \geq 0 \end{array}$	$\begin{array}{ll} \mbox{minimize} & y^{\intercal}b \\ \mbox{subject to} & A^{\intercal}y \geq c \\ & y \geq 0 \end{array}$

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- Let y be dual optimal. By non-degeneracy:
 - Exactly m of the m + n dual constraints are tight at y
 - Exactly n dual constraints are loose

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- Complementary slackness allows us to recover the primal optimal from the dual optimal, and vice versa.
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- Let *y* be dual optimal. By non-degeneracy:
 - Exactly m of the m + n dual constraints are tight at y
 - Exactly n dual constraints are loose
- n loose dual constraints impose n tight primal constraints

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- Let *y* be dual optimal. By non-degeneracy:
 - Exactly m of the m + n dual constraints are tight at y
 - Exactly n dual constraints are loose
- n loose dual constraints impose n tight primal constraints
 - Assuming non-degeneracy, solving the linear equation yields a unique primal optimum solution *x*.

Consequences of Duality

Sensitivity Analysis

Primal LPDual LPmaximize $c^{\intercal}x$ subject to $Ax \le b$ $x \ge 0$ $x \ge 0$

Sometimes, we want to examine how the optimal value of our LP changes with its parameters c and b

Sensitivity Analysis

Primal LP

 $\begin{array}{ll} \text{maximize} & c^{\mathsf{T}}x\\ \text{subject to} & Ax \leq b\\ & x \geq 0 \end{array}$

Dual LP

 $\begin{array}{ll} \mbox{minimize} & y^{\intercal}b \\ \mbox{subject to} & A^{\intercal}y \geq c \\ & y \geq 0 \end{array}$

Sometimes, we want to examine how the optimal value of our LP changes with its parameters $c \mbox{ and } b$

Sensitivity Analysis

Let OPT = OPT(A, c, b) be the optimal value of the above LP. Let x and y be the primal and dual optima.

•
$$\frac{\partial OPT}{\partial c_i} = x_j$$
 when x is the unique primal optimum.

• $\frac{\partial OPT}{\partial b_i} = y_i$ when y is the unique dual optimum.

Sensitivity Analysis

Primal LP

 $\begin{array}{ll} \mbox{maximize} & c^{\mathsf{T}}x\\ \mbox{subject to} & Ax \leq b\\ & x \geq 0 \end{array}$

Dual LP

 $\begin{array}{ll} \mbox{minimize} & y^{\intercal}b \\ \mbox{subject to} & A^{\intercal}y \geq c \\ & y \geq 0 \end{array}$

Sometimes, we want to examine how the optimal value of our LP changes with its parameters c and b

Economic Interpretation of Sensitivity Analysis

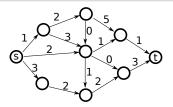
- A small increase δ in c_j increases profit by $\delta \cdot x_j$
- A small increase δ in b_i increases profit by $\delta \cdot y_i$
 - y_i measures the "marginal value" of resource i for production

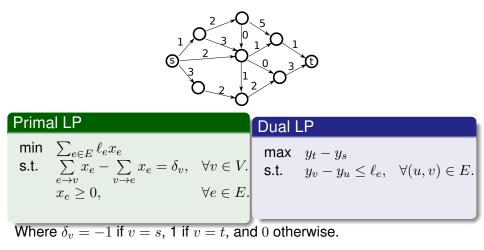
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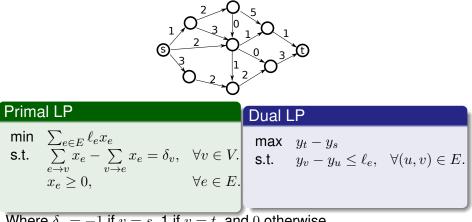
Shortest Path

Given a directed network G = (V, E) where edge e has length $\ell_e \in \mathbb{R}_+$, find the minimum cost path from s to t.





More Examples of Duality



Where $\delta_v = -1$ if v = s, 1 if v = t, and 0 otherwise.

Interpretation of Dual

Stretch s and t as far apart as possible, subject to edge lengths.

More Examples of Duality

Maximum Weighted Bipartite Matching

Set *B* of buyers, and set *G* of goods. Buyer *i* has value w_{ij} for good *j*, and interested in at most one good. Find maximum value assignment of goods to buyers.

Maximum Weighted Bipartite Matching

Prima	II LP		Dual	LP	
max	$\sum_{i,j} w_{ij} x_{ij}$		min	$\sum_{i=1}^{n} u_i + \sum_{i=1}^{n} p_j$	
	$\sum x_{ij} \leq 1,$	$\forall i \in B.$	s.t.	$ \begin{array}{ll} i \in B & j \in G \\ u_i + p_j \ge w_{ij}, \end{array} $	$\forall i \in B, j \in G$
	$\sum_{i\in B}^{j\in G} x_{ij} \le 1,$	$\forall j \in G.$		$u_i \ge 0, \\ p_j \ge 0,$	$\forall i \in B. \\ \forall j \in G.$
	$\begin{array}{l} {i \in B} \\ {x_{ij} \ge 0}, \end{array}$	$\forall i \in B, j \in$	1	$p_{j} \geq 0,$	vj c u.

Maximum Weighted Bipartite Matching

Prima	ıl LP		Dual	LP	
max	$\sum_{i,j} w_{ij} x_{ij}$		min	$\sum_{i=1}^{n} u_i + \sum_{i=1}^{n} p_j$	
s.t.	$\sum^{n} x_{ij} \leq 1,$	$\forall i \in B.$	s.t.	$i \in B \qquad j \in G \\ u_i + p_j \ge w_{ij},$	$\forall i \in B, j \in G$
	$\sum_{i=1}^{j \in G} x_{ii} < 1,$	$\forall j \in G.$		$u_i \ge 0,$	$\forall i \in B.$
	$\sum_{i \in B} x_{ij} \le 1,$ $x_{ij} \ge 0,$	$\forall i \in B, j \in$		$p_j \ge 0,$	$\forall j \in G.$
	$x_{ij} \ge 0,$	$v \in D, j \in$	t i		

Interpretation of Dual

- p_j is price of good j
- u_i is utility of buyer i
- Complementary Slackness: each buyer grabs his favorite good given prices

Rock-Paper-Scissors

	R	P	S
R	0	1	-1
P	-1	0	1
S	1	-1	0

- Two players, row and column
- Game described by matrix A
- When row player plays pure strategy *i* and column player plays pure strategy *j*, row player pays column player *A*_{*ij*}

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- Mixed Strategy: distribution over pure strategies

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- Two players, row and column
- Game described by matrix A
- When row player plays pure strategy *i* and column player plays pure strategy *j*, row player pays column player *A*_{*ij*}
- Mixed Strategy: distribution over pure strategies
- Assume players know each other's mixed strategies but not coin flips

- Assume row player moves first with distribution $y \in \Delta_m$
 - Loss as a function of column's strategy given by $y^{\intercal}A$
 - A best response by column is pure strategy *j* maximizing $(y^{\intercal}A)_j$

	x_1	x_2	x_3	x_4
y_1	a_{11}	a_{12}	a_{13}	a_{14}
y_2	a_{21}	a_{22}	a_{23}	a_{24}
y_3	a_{31}	a_{32}	a_{33}	a_{34}

- Assume row player moves first with distribution $y \in \Delta_m$
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Row Moves First		
min s.t. $\sum_{i=1}^{m} y_i = 1$ $y \ge \vec{0}$	$\max_j (y^{T} A)_j$	

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Row Moves First	
$ \begin{array}{ll} \min & u \\ \mathbf{s.t.} u \vec{1} - y^{T} A \geq \vec{0} \\ \sum_{i=1}^{m} y_i = 1 \\ y \geq \vec{0} \end{array} $	

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 - Similarly when column moves first

Row Moves First	h
$ \begin{array}{ll} \min & u \\ \mathbf{s.t.} u \vec{1} - y^{T} A \geq \vec{0} \\ \sum_{i=1}^{m} y_i = 1 \\ y \geq \vec{0} \end{array} $	

Column Moves First	
$\max_{\substack{\textbf{s.t.}v\vec{1} - Ax \leq \vec{0} \\ \sum_{j=1}^{n} x_j = 1 \\ x \geq \vec{0}}}$	v

- Assume row player moves first with distribution $y \in \Delta_m$
 - Loss as a function of column's strategy given by $y^{\intercal}A$
 - A best response by column is pure strategy j maximizing $(y^{\intercal}A)_j$
 - Similarly when column moves first

Row Moves First	Column Moves First
$ \begin{array}{ll} \min & u \\ \mathbf{s.t.} u \vec{1} - y^{T} A \geq \vec{0} \\ \sum_{i=1}^{m} y_i = 1 \\ y \geq \vec{0} \end{array} $	$\max_{\substack{\mathbf{s}.\mathbf{t}.v\vec{1}-Ax\leq\vec{0}\\\sum_{j=1}^{n}x_{j}=1\\x\geq\vec{0}}}$

These two optimization problems are LP Duals!

v

Duality and Zero Sum Games

Weak Duality

 $\bullet \ u^* \geq v^*$

Zero sum games have a second mover advantage (weakly)

Duality and Zero Sum Games

Weak Duality

• $u^* \ge v^*$

Zero sum games have a second mover advantage (weakly)

Strong Duality (Minimax Theorem)

- $u^* = v^*$
- There is no second or first mover advantage in zero sum games with mixed strategies
- Each player can guarantee $u^* = v^*$ regardless of other's strategy.
- *y**, *x** are simultaneously best responses to each other (Nash Equilibrium)

Duality and Zero Sum Games

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Zero sum games have a second mover advantage (weakly)

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Complementary Slackness

 x^* randomizes over pure best responses to y^* , and vice versa.

Saddle Point Interpretation

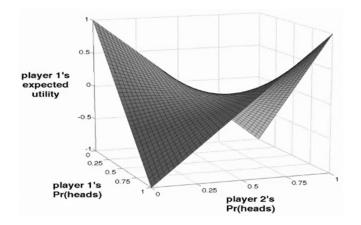
Consider the matching pennies game

	H	Т
H	-1	1
T	1	-1

- Unique equilibrium: each player randomizes uniformly
- If row player deviates, he pays out more
- If column player deviates, he gets paid less

More Examples of Duality

Saddle Point Interpretation



- Unique equilibrium: each player randomizes uniformly
- If row player deviates, he pays out more
- If column player deviates, he gets paid less