CS675: Convex and Combinatorial Optimization Fall 2014 Introduction to Optimization

Instructor: Shaddin Dughmi

Outline

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Mathematical Optimization

The task of selecting the "best" configuration of a set of variables from a "feasible" set of configurations.

$$\begin{array}{ll} \text{minimize (or maximize)} & f(x) \\ \text{subject to} & x \in \mathcal{X} \end{array}$$

- Terminology: decision variable(s), objective function, feasible set, optimal solution, optimal value
- Two main classes: continuous and combinatorial

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Continuous Optimization Problems

Optimization problems where feasible set \mathcal{X} is a connected subset of Euclidean space, and f is a continuous function.

Instances typically formulated as follows.

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minimize f(x)
subject to g_i(x) \le b_i, for i \in \mathcal{C}.
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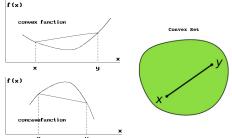
- Objective function $f: \mathbb{R}^n \to \mathbb{R}$.
- Constraint functions $g_i : \mathbb{R}^n \to \mathbb{R}$. The inequality $g_i(x) \leq b_i$ is the *i*'th constraint.
- In general, intractable to solve efficiently (NP hard)

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Convex Optimization Problem

A continuous optimization problem where f is a convex function on \mathcal{X} , and \mathcal{X} is a convex set.

- Convex function: $f(\alpha x + (1 \alpha)y) \le \alpha f(x) + (1 \alpha)f(y)$ for all $x, y \in \mathcal{X}$ and $\alpha \in [0, 1]$
- Convex set: $\alpha x + (1 \alpha)y \in \mathcal{X}$, for all $x, y \in \mathcal{X}$ and $\alpha \in [0, 1]$
- ullet Convexity of ${\mathcal X}$ implied by convexity of g_i 's
- For maximization problems, f should be concave
- Typically solvable efficiently (i.e. in polynomial time)
- Encodes optimization problems from a variety of application areas



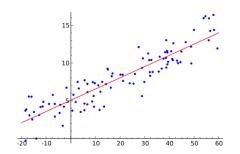
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Convex Optimization Example: Least Squares Regression

Given a set of measurements $(a_1,b_1),\ldots,(a_m,b_m)$, where $a_i\in\mathbb{R}^n$ is the i'th input and $b_i\in\mathbb{R}$ is the i'th output, find the linear function $f:\mathbb{R}^n\to\mathbb{R}$ best explaining the relationship between inputs and outputs.

- $f(a) = x^{\mathsf{T}}a$ for some $x \in \mathbb{R}^n$
- Least squares: minimize mean-square error.

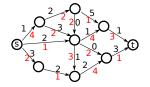
minimize
$$||Ax - b||_2^2$$



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Convex Optimization Example: Minimum Cost Flow

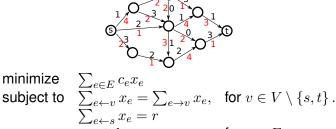
Given a directed network G = (V, E) with cost $c_e \in \mathbb{R}_+$ per unit of traffic on edge e, and capacity d_e , find the minimum cost routing of r divisible units of traffic from s to t.



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Convex Optimization Example: Minimum Cost Flow

Given a directed network G = (V, E) with cost $c_e \in \mathbb{R}_+$ per unit of traffic on edge e, and capacity d_e , find the minimum cost routing of rdivisible units of traffic from s to t.



minimize

```
\sum_{e \leftarrow s} x_e = r
x_e \leq d_e
                                    for e \in E.
                                    for e \in E.
x_e > 0,
```

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Convex Optimization Example: Minimum Cost Flow

Given a directed network G = (V, E) with cost $c_e \in \mathbb{R}_+$ per unit of traffic on edge e, and capacity d_e , find the minimum cost routing of r divisible units of traffic from s to t.

$$\sum_{e \in E} c_e x_e \\ \text{subject to} \qquad \sum_{e \in E} c_e x_e \\ \sum_{e \leftarrow v} x_e = \sum_{e \rightarrow v} x_e, \quad \text{for } v \in V \setminus \{s, t\} \,. \\ \sum_{e \leftarrow s} x_e = r \\ x_e \leq d_e, \qquad \qquad \text{for } e \in E. \\ x_e \geq 0, \qquad \qquad \text{for } e \in E.$$

Generalizes to traffic-dependent costs. For example

$$c_e(x_e) = a_e x_e^2 + b_e x_e + c_e.$$

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Combinatorial Optimization

Combinatorial Optimization Problem

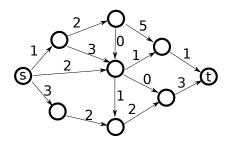
An optimization problem where the feasible set \mathcal{X} is finite.

- ullet e.g. ${\cal X}$ is the set of paths in a network, assignments of tasks to workers, etc...
- Again, NP-hard in general, but many are efficiently solvable (either exactly or approximately)

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Combinatorial Optimization Example: Shortest Path

Given a directed network G=(V,E) with cost $c_e\in\mathbb{R}_+$ on edge e, find the minimum cost path from s to t.



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Combinatorial Optimization Example: Traveling Salesman Problem

Given a set of cities V, with d(u, v) denoting the distance between cities u and v, find the minimum length tour that visits all cities.



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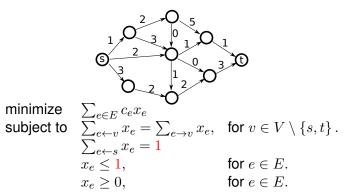
Continuous vs Combinatorial Optimization

- Some optimization problems are best formulated as one or the other
- Many problems, particularly in computer science and operations research, can be formulated as both
- This dual perspective can lead to structural insights and better algorithms

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Example: Shortest Path

The shortest path problem can be encoded as a minimum cost flow problem, using distances as the edge costs, unit capacities, and desired flow rate $1\,$



The optimum solution of the (linear) convex program above will assign flow only on a single path — namely the shortest path.

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Course Goals

- Recognize and model convex optimization problems, and develop a general understanding of the relevant algorithms.
- Formulate combinatorial optimization problems as convex programs
- Use both the discrete and continuous perspectives to design algorithms and gain structural insights for optimization problems

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Who Should Take this Class

- Anyone planning to do research in the design and analysis of algorithms
 - Convex and combinatorial optimization have become an indispensible part of every algorithmist's toolkit
- Students interested in theoretical machine learning and AI
 - Convex optimization underlies much of machine learning
 - Submodularity has recently emerged as an important abstraction for feature selection, active learning, planning, and other applications
- Anyone else who solves or reasons about optimization problems: electrical engineers, control theorists, operations researchers, economists...
 - If there are applications in your field you would like to hear more about, let me know.

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Who Should Not Take this Class

- You don't satisfy the prerequisites
- You are looking for a "cookbook" of optimization algorithms, and/or want to learn how to use CPLEX, CVX, etc
 - This is a THEORY class
 - We will bias our attention towards simple yet theoretically insightful algorithms and questions

We will not write code

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Course Outline

- Weeks 1-5: Convex optimization basics and duality theory
- Weeks 6-7: Combinatorial problems posed as linear and convex programs
- Weeks 8-9: Algorithms for convex optimization
- Weeks 10-11: Matroid theory and optimization
- Weeks 12-13: Submodular Function optimization
- Week 14: Semidefinite programming and constraint satisfaction problems

Week 15: Additional topics

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Basic Information

Lecture time: Tuesdays and Thursdays 11:00am - 12:20 pm

Lecture place: THH 121

Instructor: Shaddin Dughmi

Email: shaddin@usc.edu

Office: SAL 234Office Hours: TBD

TA: Ruixin Qiang

• Email: rqiang@usc.edu

Office Hours: TBA

Course Homepage: www.cs.usc.edu/people/shaddin/cs675fa14

 References: Convex Optimization by Boyd and Vandenberghe, and Combinatorial Optimization by Korte and Vygen. (Available online through USC libraries. Will place on reserve)

 Additional References: Schrijver, Luenberger and Ye (available online through USC libraries)

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Prerequisites

- Mathematical maturity: Be good at proofs, at the graduate level.
- Linear algebra at advanced undergrad / beginning grad level
- Exposure to algorithms or optimization at advanced undergrad / beginning grad level
 - CS570 or equivalent, or
 - CS303 and you did really well

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Requirements and Grading

- This is an advanced elective class, so grade is not the point.
 - I assume you want to learn this stuff.
- 4 homeworks, 75% of grade.
 - Proof based.
 - Challenging.
 - Discussion allowed, even encouraged, but must write up solutions independently.
- Research project or final, 25% of grade. Project suggestions will be posted on website.

3 late days allowed total (use in integer amounts)

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Survey

- Name
- Email
- Department
- Degree
- Relevant coursework/background
- Research project idea

Email Ruixin: rqiang@usc.edu

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