

CS675: Convex and Combinatorial Optimization
Fall 2019
Introduction to Optimization

Instructor: Shaddin Dughmi

Outline

- 1 Course Overview
- 2 Administrivia

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1 Course Overview

2 Administrivia

Mathematical Optimization

The task of selecting the “best” configuration of a set of variables from a “feasible” set of configurations.

$$\begin{array}{ll} \text{minimize (or maximize)} & f(x) \\ \text{subject to} & x \in \mathcal{X} \end{array}$$

- Terminology: decision variable(s), objective function, feasible set, optimal solution, optimal value
- Two main classes: **continuous** and **combinatorial**

Continuous Optimization Problems

Optimization problems where feasible set \mathcal{X} is a connected subset of Euclidean space, and f is a continuous function.

- Instances typically formulated as follows.

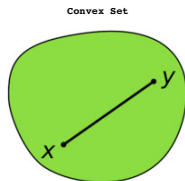
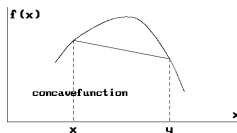
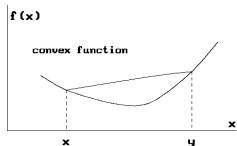
$$\begin{array}{ll} \text{minimize} & f(x) \\ \text{subject to} & g_i(x) \leq b_i, \quad \text{for } i \in \mathcal{C}. \end{array}$$

- **Objective function** $f : \mathbb{R}^n \rightarrow \mathbb{R}$.
- **Constraint functions** $g_i : \mathbb{R}^n \rightarrow \mathbb{R}$. The inequality $g_i(x) \leq b_i$ is the i 'th **constraint**.
- In general, intractable to solve efficiently (NP hard)

Convex Optimization Problem

A continuous optimization problem where f is a convex function on \mathcal{X} , and \mathcal{X} is a convex set.

- **Convex function:** $f(\alpha x + (1 - \alpha)y) \leq \alpha f(x) + (1 - \alpha)f(y)$ for all $x, y \in \mathcal{X}$ and $\alpha \in [0, 1]$
- **Convex set:** $\alpha x + (1 - \alpha)y \in \mathcal{X}$, for all $x, y \in \mathcal{X}$ and $\alpha \in [0, 1]$
- Convexity of \mathcal{X} implied by convexity of g_i 's
- For maximization problems, f should be **concave**
- Typically solvable efficiently (i.e. in polynomial time)
- Encodes optimization problems from a variety of application areas

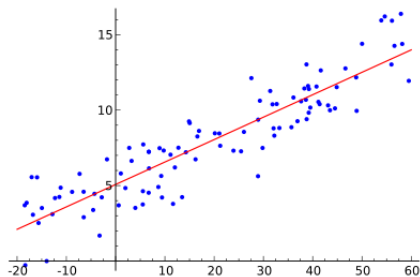


Convex Optimization Example: Least Squares Regression

Given a set of measurements $(a_1, b_1), \dots, (a_m, b_m)$, where $a_i \in \mathbb{R}^n$ is the i 'th input and $b_i \in \mathbb{R}$ is the i 'th output, find the linear function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ best explaining the relationship between inputs and outputs.

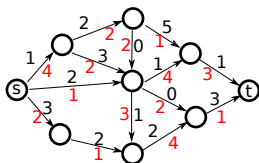
- $f(a) = x^T a$ for some $x \in \mathbb{R}^n$
- Least squares: minimize mean-square error.

$$\text{minimize } \|Ax - b\|_2^2$$



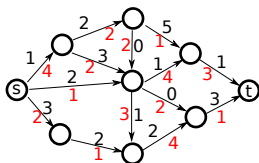
Convex Optimization Example: Minimum Cost Flow

Given a directed network $G = (V, E)$ with cost $c_e \in \mathbb{R}_+$ per unit of traffic on edge e , and capacity d_e , find the minimum cost routing of r divisible units of traffic from s to t .



Convex Optimization Example: Minimum Cost Flow

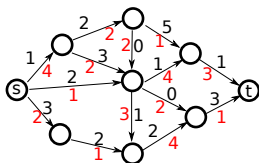
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$$\begin{aligned} &\text{minimize} && \sum_{e \in E} c_e x_e \\ &\text{subject to} && \sum_{e \leftarrow v} x_e = \sum_{e \rightarrow v} x_e, && \text{for } v \in V \setminus \{s, t\}. \\ &&& \sum_{e \leftarrow s} x_e = r \\ &&& x_e \leq d_e, && \text{for } e \in E. \\ &&& x_e \geq 0, && \text{for } e \in E. \end{aligned}$$

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Generalizes to traffic-dependent costs. For example

$$c_e(x_e) = a_e x_e^2 + b_e x_e + c_e.$$

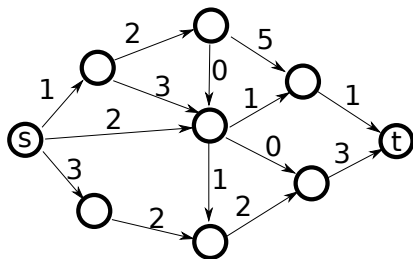
Combinatorial Optimization Problem

An optimization problem where the feasible set \mathcal{X} is finite.

- e.g. \mathcal{X} is the set of paths in a network, assignments of tasks to workers, etc...
- Again, NP-hard in general, but many are efficiently solvable (either exactly or approximately)

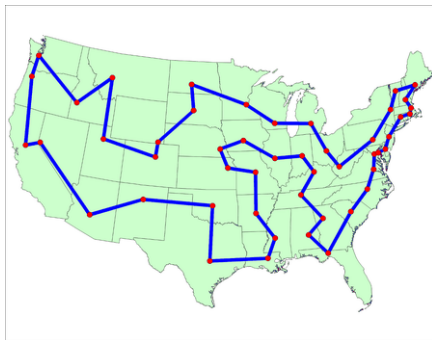
Combinatorial Optimization Example: Shortest Path

Given a directed network $G = (V, E)$ with cost $c_e \in \mathbb{R}_+$ on edge e , find the minimum cost path from s to t .



Combinatorial Optimization Example: Traveling Salesman Problem

Given a set of cities V , with $d(u, v)$ denoting the distance between cities u and v , find the minimum length tour that visits all cities.

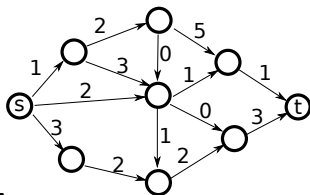


Continuous vs Combinatorial Optimization

- Some optimization problems are best formulated as one or the other
- Many problems, particularly in computer science and operations research, can be formulated as both
- This dual perspective can lead to structural insights and better algorithms

Example: Shortest Path

The shortest path problem can be encoded as a minimum cost flow problem, using distances as the edge costs, unit capacities, and desired flow rate 1



$$\begin{aligned} & \text{minimize} && \sum_{e \in E} c_e x_e \\ & \text{subject to} && \sum_{e \leftarrow v} x_e = \sum_{e \rightarrow v} x_e, && \text{for } v \in V \setminus \{s, t\}. \\ & && \sum_{e \leftarrow s} x_e = 1 \\ & && x_e \leq 1, && \text{for } e \in E. \\ & && x_e \geq 0, && \text{for } e \in E. \end{aligned}$$

The optimum solution of the (linear) convex program above will assign flow only on a single path — namely the shortest path.

Course Goals

- Recognize and model convex optimization problems, and develop a general understanding of the relevant algorithms.
- Formulate combinatorial optimization problems as convex programs
- Use both the discrete and continuous perspectives to design algorithms and gain structural insights for optimization problems

Who Should Take this Class

- Anyone planning to do research in the design and analysis of algorithms
 - Convex and combinatorial optimization have become an indispensable part of every algorithmist's toolkit
- Students interested in theoretical machine learning and AI
 - Convex optimization underlies much of machine learning
 - Submodularity has recently emerged as an important abstraction for feature selection, active learning, planning, and other applications
- Anyone else who solves or reasons about optimization problems: electrical engineers, control theorists, operations researchers, economists . . .
 - If there are applications in your field you would like to hear more about, let me know.

Who Should Not Take this Class

- You don't satisfy the prerequisites "in practice"
- You are looking for a "cookbook" of optimization algorithms, and/or want to learn how to use CPLEX, CVX, etc
 - This is a THEORY class
 - We will bias our attention towards simple yet theoretically insightful algorithms and questions
 - We will not write code

Course Outline

- Weeks 1-5: Convex optimization basics and duality theory
- Weeks 6-7: Combinatorial problems posed as linear and convex programs
- Weeks 8-9: Algorithms for convex optimization
- Weeks 10-11: Matroid theory and optimization
- Weeks 12-13: Submodular Function optimization
- Week 14: Semidefinite programming and constraint satisfaction problems
- Week 15: Additional topics

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Basic Information

- Lecture time: Mondays and Wednesdays 4:00pm - 5:50pm
- Lecture place: VHE 214
- Instructor: Shaddin Dughmi
 - Email: shaddin@usc.edu
 - Office: SAL 234
 - Office Hours: TBD
- TA: TBA
 - Email: TBA
 - Office Hours: TBA
- Course Homepage:
<http://www-bcf.usc.edu/shaddin/cs675fa19/index.html>
- References: Convex Optimization by Boyd and Vandenberghe, and Combinatorial Optimization by Korte and Vygen. (Available online through USC libraries. Will place on reserve)
- Additional References: Schrijver, Luenberger and Ye (available online through USC libraries)

Prerequisites

- Mathematical maturity: Be good at proofs, at the graduate level.
- Linear algebra at advanced undergrad / beginning grad level
- Exposure to algorithms or optimization at advanced undergrad / beginning grad level
 - CS570 or equivalent, or
 - CS270 and you did really well

Requirements and Grading

- This is an advanced elective class, so grade is not the point.
 - I assume you want to learn this stuff.
- 4-6 homeworks, 75% of grade.
 - Proof based.
 - Challenging.
 - Discussion allowed, even encouraged, but must write up solutions independently.
- Research project worth 25% of grade. Project suggestions will be posted on website.
- 5 late days allowed total (use in integer amounts)