## CS675: Convex and Combinatorial Optimization Fall 2023 Convex Functions

Instructor: Shaddin Dughmi

## Outline

(1) Convex Functions
(2) Examples of Convex and Concave Functions
(3) Convexity-Preserving Operations

## Convex Functions

A function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is convex if the line segment between any points on the graph of $f$ lies above $f$. i.e. if $x, y \in \mathbb{R}^{n}$ and $\theta \in[0,1]$, then

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f(\theta x+(1-\theta) y) \leq \theta f(x)+(1-\theta) f(y)
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- $f$ is convex iff its restriction to any line $\{x+t v: t \in \mathbb{R}\}$ is convex
- $f$ is strictly convex if inequality strict when $x \neq y$ and $\theta \in(0,1)$.
- Analogous definition when domain of $f$ is a convex subset of $\mathbb{R}^{n}$


## Concave and Affine Functions



A function is $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is concave if $-f$ is convex. Equivalently:

- Line segment between any points on the graph of $f$ lies below $f$.
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$$

$f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is affine if it is both concave and convex. Equivalently:

- Line segment between any points on the graph of $f$ lies on the graph of $f$.
- $f(x)=a^{\top} x+b$ for some $a \in \mathbb{R}^{n}$ and $b \in \mathbb{R}$.

We will now look at some equivalent definitions of convex functions

## First Order Definition

A differentiable $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is convex if and only if the first-order approximation centered at any point $x$ underestimates $f$ everywhere.

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f(y) \geq f(x)+(\nabla f(x))^{\top}(y-x)
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- Local information $\rightarrow$ global information
- If $\nabla f(x)=0$ then $x$ is a global minimizer of $f$


## Second Order Definition

A twice differentiable $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is convex if and only if its Hessian matrix $\nabla^{2} f(x)$ is positive semi-definite for all $x$. (We write $\nabla^{2} f(x) \succeq 0$ )

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## Intepretation

- Recall definition of PSD: $z^{\top} \nabla^{2} f(x) z \geq 0$ for all $z \in \mathbb{R}^{n}$
- When $n=1$, this is $f^{\prime \prime}(x) \geq 0$.
- More generally, $\frac{z^{\top} \nabla^{2} f(x) z}{\|z\|^{2}}$ is the second derivative of $f$ along the line $\{x+t z: t \in \mathbb{R}\}$. So if $\nabla^{2} f(x) \succeq 0$ then $f$ curves upwards along any line.
- Moving from $x$ to $x+\delta \vec{z}$, infitisimal change in gradient is $\delta \nabla^{2} f(x) z$. When $\nabla^{2} f(x) \succeq 0$, this is in roughly the same direction as $\vec{z}$.



## Epigraph

The epigraph of $f$ is the set of points above the graph of $f$. Formally,

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\operatorname{epi}(f)=\{(x, t): t \geq f(x)\}
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## Epigraph Definition

$f$ is a convex function if and only if its epigraph is a convex set.

## Jensen's Inequality (General Form)

$f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is convex if and only if

- For every $x_{1}, \ldots, x_{k}$ in the domain of $f$, and $\theta_{1}, \ldots, \theta_{k} \geq 0$ such that $\sum_{i} \theta_{i}=1$, we have

$$
f\left(\sum_{i} \theta_{i} x_{i}\right) \leq \sum_{i} \theta_{i} f\left(x_{i}\right)
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- Given a probability measure $\mathcal{D}$ on the domain of $f$, and $x \sim \mathcal{D}$,

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f(\mathbf{E}[x]) \leq \mathbf{E}[f(x)]
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Adding noise to $x$ can only increase $f(x)$ in expectation.

## Local and Global Optimality

## Local minimum

$x$ is a local minimum of $f$ if there is a an open ball $B$ containing $x$ where $f(y) \geq f(x)$ for all $y \in B$.

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## Local and Global Optimality

When $f$ is convex, $x$ is a local minimum of $f$ if and only if it is a global minimum.

- This fact underlies much of the tractability of convex optimization.


## Sub-level sets



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The $\alpha$-sublevel set of $f$ is $\{x \in \operatorname{domain}(f): f(x) \leq \alpha\}$.

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## Fact

Every sub-level set of a convex function is a convex set.

- This fact also underlies tractability of convex optimization


## Sub-level sets



$$
\text { Level sets of } f(x, y)=\sqrt{x^{2}+y^{2}}
$$

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Note: converse false, but nevertheless useful check.

## Other Basic Properties

## Continuity

Real-valued convex functions are continuous on the interior of their domain.

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## Extended-value extension

If a function $f: D \rightarrow \mathbb{R}$ is convex on its domain, and $D$ is convex, then it can be extended to a convex function on $\mathbb{R}^{n}$ by setting $f(x)=\infty$ whenever $x \notin D$.

This simplifies notation. Resulting function $\tilde{f}: D \rightarrow \mathbb{R} \bigcup \infty$ is "convex" with respect to the ordering on $\mathbb{R} \bigcup \infty$

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## Functions on the reals

- Affine: $a x+b$
- Exponential: $e^{a x}$ convex for any $a \in \mathbb{R}$
- Powers: $x^{a}$ convex on $\mathbb{R}_{++}$when $a \geq 1$ or $a \leq 0$, and concave for $0 \leq a \leq 1$
- Logarithm: $\log x$ concave on $\mathbb{R}_{++}$.


## Norms

Norms are convex.

$$
\|\theta x+(1-\theta) y\| \leq\|\theta x\|+\|(1-\theta) y\|=\theta\|x\|+(1-\theta)\|y\|
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- Uses both norm axioms: triangle inequality, and homogeneity.
- Applies to matrix norms, such as the spectral norm (radius of induced ellipsoid)


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- Applies to matrix norms, such as the spectral norm (radius of induced ellipsoid)


## Max

$\max _{i} x_{i}$ is convex

$$
\begin{aligned}
\max _{i}(\theta x+(1-\theta) y)_{i} & =\max _{i}\left(\theta x_{i}+(1-\theta) y_{i}\right) \\
& \leq \max _{i} \theta x_{i}+\max _{i}(1-\theta) y_{i} \\
& =\theta \max _{i} x_{i}+(1-\theta) \max _{i} y_{i}
\end{aligned}
$$

If i'm allowed to pick the maximum entry of $\theta x$ and $\theta y$ independently, I can do only better.

- Log-sum-exp: $\log \left(e^{x_{1}}+e^{x_{2}}+\ldots+e^{x_{n}}\right)$ is convex
- Geometric mean: $\left(\prod_{i=1}^{n} x_{i}\right)^{\frac{1}{n}}$ is concave
- Log-determinant: $\log \operatorname{det} X$ is concave
- Quadratic form: $x^{\top} A x$ is convex iff $A \succeq 0$
- Other examples in book


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f(x, y)=\log \left(e^{x}+e^{y}\right)
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Proving convexity often comes down to case-by-case reasoning, involving:

- Definition: restrict to line and check Jensen's inequality
- Write down the Hessian and prove PSD
- Express as a combination of other convex functions through convexity-preserving operations (Next)


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## Nonnegative Weighted Combinations

If $f_{1}, f_{2}, \ldots, f_{k}$ are convex, and $w_{1}, w_{2}, \ldots, w_{k} \geq 0$, then $g=w_{1} f_{1}+w_{2} f_{2} \ldots+w_{k} f_{k}$ is convex.

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## proof $(k=2)$

$$
\begin{aligned}
g\left(\frac{x+y}{2}\right) & =w_{1} f_{1}\left(\frac{x+y}{2}\right)+w_{2} f_{2}\left(\frac{x+y}{2}\right) \\
& \leq w_{1} \frac{f_{1}(x)+f_{1}(y)}{2}+w_{2} \frac{f_{2}(x)+f_{2}(y)}{2} \\
& =\frac{g(x)+g(y)}{2}
\end{aligned}
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Extends to integrals $g(x)=\int_{y} w(y) f_{y}(x)$ with $w(y) \geq 0$, and therefore expectations $\mathbf{E}_{y} f_{y}(x)$.

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## Worth Noting

Minimizing the expectation of a random convex cost function is also a convex optimization problem!

- A stochastic convex optimization problem is a convex optimization problem.


## Example: Stochastic Facility Location



## Average Distance

- $k$ customers located at $y_{1}, y_{2}, \ldots, y_{k} \in \mathbb{R}^{n}$
- If I place a facility at $x \in \mathbb{R}^{n}$, average distance to a customer is $g(x)=\sum_{i} \frac{1}{k}\left\|x-y_{i}\right\|$


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- Since distance to any one customer is convex in $x$, so is the average distance.
- Extends to probability measure over customers


## Implication

Convex functions are a convex cone in the vector space of functions from $\mathbb{R}^{n}$ to $\mathbb{R}$.

The set of convex functions is the intersection of an infinite set of homogeneous linear inequalities indexed by $x, y, \theta$

$$
f(\theta x+(1-\theta) y)-\theta f(x)-(1-\theta) f(y) \leq 0
$$

## Composition with Affine Function

If $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is convex, and $A \in \mathbb{R}^{n \times m}, b \in \mathbb{R}^{n}$, then

$$
g(x)=f(A x+b)
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is a convex function from $\mathbb{R}^{m}$ to $\mathbb{R}$.

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## Proof

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& (x, t) \in \mathbf{e p i}(g) \Longleftrightarrow t \geq g(x)=f(A x+b) \Longleftrightarrow(A x+b, t) \in \mathbf{e p i}(f)
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\end{aligned}
$$

epi $(g)$ is the inverse image of epi $(f)$ under the affine mapping

$$
(x, t) \rightarrow(A x+b, t)
$$

## Examples

- $\|A x+b\|$ is convex
- $\max (A x+b)$ is convex
- $\log \left(e^{a_{1}^{\top} x+b_{1}}+e^{a_{2}^{\top} x+b_{2}}+\ldots+e^{a_{n}^{\top} x+b_{n}}\right)$ is convex


## Maximum

If $f_{1}, f_{2}$ are convex, then $g(x)=\max \left\{f_{1}(x), f_{2}(x)\right\}$ is also convex.
Generalizes to the maximum of any number of functions, $\max _{i=1}^{k} f_{i}(x)$, and also to the supremum of an infinite set of functions $\sup _{y} f_{y}(x)$.

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$$
\text { epi } g=\mathbf{e p i} f_{1} \bigcap \text { epi } f_{2}
$$

## Example: Robust Facility Location



## Maximum Distance

- $k$ customers located at $y_{1}, y_{2}, \ldots, y_{k} \in \mathbb{R}^{n}$
- If I place a facility at $x \in \mathbb{R}^{n}$, maximum distance to a customer is $g(x)=\max _{i}\left\|x-y_{i}\right\|$


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Since distance to any one customer is convex in $x$, so is the worst-case distance.

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## Worth Noting

When a convex cost function is uncertain, minimizing the worst-case cost is also a convex optimization problem!

- A robust (in the worst-case sense) convex optimization problem is a convex optimization problem.


## Other Examples

- Maximum eigenvalue of a symmetric matrix $A$ is convex in $A$

$$
\max \left\{v^{\top} A v:\|v\|=1\right\}
$$

- Sum of k largest components of a vector $x$ is convex in $x$

$$
\max \left\{\overrightarrow{\mathbf{1}}_{S} \cdot x:|S|=k\right\}
$$

## Minimization

If $f(x, y)$ is convex and $\mathcal{C}$ is convex and nonempty, then $g(x)=\inf _{y \in C} f(x, y)$ is convex.

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## Proof (for $\mathcal{C}=\mathbb{R}^{k}$ )

epi $g$ is the projection of epi $f$ onto hyperplane $y=0$.


## Example

## Distance from a convex set $\mathcal{C}$

$$
f(x)=\inf _{y \in \mathcal{C}}\|x-y\|
$$

## Composition Rules

If $g: \mathbb{R}^{n} \rightarrow \mathbb{R}^{k}$ and $h: \mathbb{R}^{k} \rightarrow \mathbb{R}$, then $f=h \circ g$ is convex if

- $g_{i}$ are convex, and $h$ is convex and nondecreasing in each argument.
- $g_{i}$ are concave, and $h$ is convex and nonincreasing in each argument.


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## Proof ( $n=k=1$, twice differentiable)

$$
f^{\prime \prime}(x)=h^{\prime \prime}(g(x)) g^{\prime}(x)^{2}+h^{\prime}(g(x)) g^{\prime \prime}(x)
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## Proof of first case

$$
\begin{array}{rlr}
g(\theta x+(1-\theta) y) & \preceq \theta g(x)+(1-\theta) g(y) & \text { (component-wise) } \\
h(g(\theta x+(1-\theta) y)) & \leq h(\theta g(x)+(1-\theta) g(y)) & (h \text { non-decreasing) } \\
& \leq \theta h(g(x))+(1-\theta) h(g(y) & \\
(h \text { convex })
\end{array}
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& \leq \theta h(g(x))+(1-\theta) h(g(y) & (h \text { convex) }
\end{array}
$$

Proof of second case is almost identical

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epi $g$ is inverse image of epi $f$ under the perspective function $(x, t, y) \rightarrow(x / t, y / t)$.

