

CSCI 699: Topics in Learning and Game Theory  
Fall 2017  
Lecture 3: Intro to Game Theory

Instructor: Shaddin Dughmi

# Outline

- 1 Introduction
- 2 Games of Complete Information
- 3 Games of Incomplete Information
  - Prior-free Games
  - Bayesian Games

# Outline

- 1 Introduction
- 2 Games of Complete Information
- 3 Games of Incomplete Information
  - Prior-free Games
  - Bayesian Games

## Game Theory

The study of mathematical models of conflict and cooperation between **rational** decision-makers .

- **Game**: situation in which multiple decision makers (a.k.a. **agents** or **players**) make choices which influence each others' welfare (a.k.a. **utility**)
- **Goal**: Make predictions on how agents behave in a game

## Game Theory

The study of mathematical models of conflict and cooperation between **rational** decision-makers .

- **Game**: situation in which multiple decision makers (a.k.a. **agents** or **players**) make choices which influence each others' welfare (a.k.a. **utility**)
- Goal: Make predictions on how agents behave in a game
- How to define **rational** decision-making: domain of **decision theory**
  - Special case of game theory for a single agent.

# Bayesian Decision Theory

- There is a set  $\Omega$  of future states of the world (e.g. times at which you might get to school )
- Set  $A$  of possible actions (e.g. which route you drive)
- For each  $a \in A$ , there is distribution  $x(a)$  over outcomes  $\Omega$ 
  - Agent believes that he will receive  $\omega \sim x(a)$  if he takes action  $a$ .

## Question

How does a “rational” agent choose an action?

# Bayesian Decision Theory

- There is a set  $\Omega$  of future states of the world (e.g. times at which you might get to school )
- Set  $A$  of possible actions (e.g. which route you drive)
- For each  $a \in A$ , there is distribution  $x(a)$  over outcomes  $\Omega$ 
  - Agent believes that he will receive  $\omega \sim x(a)$  if he takes action  $a$ .

## Question

How does a “rational” agent choose an action?

## Answer (Expected Utility Theory)

Agent has a subjective **utility function**  $u : \Omega \rightarrow \mathbb{R}$ , and chooses an action  $a^* \in A$  maximizing his expected utility.

- $a^* \in \operatorname{argmax} \mathbf{E}_{\omega \sim x(a)} [u(\omega)]$
- If there are multiple such actions, may randomize among them arbitrarily.

# Bayesian Decision Theory

- There is a set  $\Omega$  of future states of the world (e.g. times at which you might get to school )
- Set  $A$  of possible actions (e.g. which route you drive)
- For each  $a \in A$ , there is distribution  $x(a)$  over outcomes  $\Omega$ 
  - Agent believes that he will receive  $\omega \sim x(a)$  if he takes action  $a$ .

## Question

How does a “rational” agent choose an action?

## Answer (Expected Utility Theory)

Agent has a subjective **utility function**  $u : \Omega \rightarrow \mathbb{R}$ , and chooses an action  $a^* \in A$  maximizing his expected utility.

- $a^* \in \operatorname{argmax} \mathbf{E}_{\omega \sim x(a)} [u(\omega)]$
- If there are multiple such actions, may randomize among them arbitrarily.

In addition to being simple/natural model, follows from VNM axioms.



# Outline

- 1 Introduction
- 2 Games of Complete Information
- 3 Games of Incomplete Information
  - Prior-free Games
  - Bayesian Games

# Example: Rock, Paper, Scissors

	Rock	Paper	Scissors
Rock	0 0	+1 -1	-1 +1
Paper	-1 +1	0 0	+1 -1
Scissors	+1 -1	-1 +1	0 0

Rock, Paper, Scissors is an example of the most basic type of game.

## Simultaneous move, complete information games

- Players act simultaneously
- Each player incurs a **utility**, determined by his action as well as the actions of others.
  - Players' actions determine “state of the world” or “outcome of the game”.
- The payoff structure of the game, i.e. the map from **action profiles** to utility vectors, is **common knowledge**

Standard mathematical representation of such games:

## Normal Form

An  $n$ -player **game** in **normal form** is given by

- A set of players  $N = \{1, \dots, n\}$ .
- For each player  $i$ , a set of **actions**  $A_i$ .
  - Let  $A = A_1 \times A_2 \times \dots \times A_n$  denote the set of **action profiles**.
- For each player  $i$ , a **utility function**  $u_i : A \rightarrow \mathbb{R}$ .
  - If players play  $a_1, \dots, a_n$ , then  $u_i(a_1, \dots, a_n)$  is the utility of player  $i$ .

Standard mathematical representation of such games:

## Normal Form

An  $n$ -player **game** in **normal form** is given by

- A set of players  $N = \{1, \dots, n\}$ .
  - For each player  $i$ , a set of **actions**  $A_i$ .
    - Let  $A = A_1 \times A_2 \times \dots \times A_n$  denote the set of **action profiles**.
  - For each player  $i$ , a **utility function**  $u_i : A \rightarrow \mathbb{R}$ .
    - If players play  $a_1, \dots, a_n$ , then  $u_i(a_1, \dots, a_n)$  is the utility of player  $i$ .
- 
- Typically thought of as an  $n$ -dimensional matrix, indexed by  $a = (a_1, \dots, a_n) \in A$ , with entry  $(u_1(a), \dots, u_n(a))$ .
  - Also useful for representing more general games, like sequential and incomplete information games, but is less natural there.

# Strategies in Normal Form Games

- **Pure strategy of player  $i$** : an action  $a_i \in A_i$ 
  - Example: rock
- **Mixed strategy of player  $i$** : a distribution  $s_i$  supported on  $A_i$ .
  - The player draws an action  $a_i \sim s_i$ .
  - Example: uniformly randomly choose one of rock, paper, scissors
- (pure/mixed) **strategy profile**  $(s_1, \dots, s_n)$ : strategy for each player

# Strategies in Normal Form Games

- **Pure strategy of player  $i$** : an action  $a_i \in A_i$ 
  - Example: rock
- **Mixed strategy of player  $i$** : a distribution  $s_i$  supported on  $A_i$ .
  - The player draws an action  $a_i \sim s_i$ .
  - Example: uniformly randomly choose one of rock, paper, scissors
- (pure/mixed) **strategy profile**  $(s_1, \dots, s_n)$ : strategy for each player
- When each player chooses mixed strategy, correlation matters
  - In most cases we discuss: independent. (Nash equilibrium)
  - Sometimes, they have a way of correlating (coordinating) their random choice (Correlated equilibrium)
- When we refer to mixed strategy profiles, we mean independent randomization unless stated otherwise.

# Strategies in Normal Form Games

- **Pure strategy of player  $i$** : an action  $a_i \in A_i$ 
  - Example: rock
- **Mixed strategy of player  $i$** : a distribution  $s_i$  supported on  $A_i$ .
  - The player draws an action  $a_i \sim s_i$ .
  - Example: uniformly randomly choose one of rock, paper, scissors
- (pure/mixed) **strategy profile**  $(s_1, \dots, s_n)$ : strategy for each player
- When each player chooses mixed strategy, correlation matters
  - In most cases we discuss: independent. (Nash equilibrium)
  - Sometimes, they have a way of correlating (coordinating) their random choice (Correlated equilibrium)
- When we refer to mixed strategy profiles, we mean independent randomization unless stated otherwise.
- We can extend utility functions to mixed strategy profiles. Using  $s(a)$  as shorthand for the probability of action  $a$  in strategy  $s$ ,

$$u_i(s_1, \dots, s_n) = \sum_{a \in A} u_i(a) \prod_{j=1}^n s_j(a_j)$$



# Best Responses

A mixed strategy  $s_i$  of player  $i$  is a **best response** to a strategy profile  $s_{-i}$  of the other players if  $u_i(s) \geq u_i(s'_i, s_{-i})$  for every other mixed strategy  $s'_i$ .

- Note: There is always a pure best response
- The set of mixed best responses is the randomizations over pure best responses.

# Example: Prisoner's Dilemma

	Coop	Defect
Coop	-1 -1	0 -3
Defect	-3 0	-2 -2

# Example: Battle of the Sexes

		W	
	M	Football	Movie
M	Football	1 2	0 0
	Movie	0 0	2 1

# Example: First Price Auction

Two players, with values  $v_1 = 1$  and  $v_2 = 2$ , both common knowledge.

- $A_1 = A_2 = \mathbb{R}$  (note: infinite!)
- $u_i(a_1, a_2) = v_i - a_i$  if  $a_i > a_{-i}$ , and 0 otherwise.

### But ...

what about “sequential” games which unfold over time, like chess, english auction, multiplayer video games, life, etc?

- More naturally modeled using the **extensive form** tree representation
  - Each non-leaf node is a step in the game, associated with a player
  - Outgoing edges = actions available at that step
  - leaf nodes labelled with utility of each player
  - Pure strategy: choice of action for each contingency (i.e. each non-leaf node)

### But ...

what about “sequential” games which unfold over time, like chess, english auction, multiplayer video games, life, etc?

- More naturally modeled using the **extensive form** tree representation
  - Each non-leaf node is a step in the game, associated with a player
  - Outgoing edges = actions available at that step
  - leaf nodes labelled with utility of each player
  - Pure strategy: choice of action for each contingency (i.e. each non-leaf node)
- Can be represented as a normal form game by collapsing pure strategies to actions of a large normal form game
  - Not as useful as extensive form.

### But ...

what about “sequential” games which unfold over time, like chess, english auction, multiplayer video games, life, etc?

- More naturally modeled using the **extensive form** tree representation
  - Each non-leaf node is a step in the game, associated with a player
  - Outgoing edges = actions available at that step
  - leaf nodes labelled with utility of each player
  - Pure strategy: choice of action for each contingency (i.e. each non-leaf node)
- Can be represented as a normal form game by collapsing pure strategies to actions of a large normal form game
  - Not as useful as extensive form.
- Won't need these games much in this class, though it's a good idea to know they exist, and maybe skim the chapter.

# Equilibrium Concepts

An **equilibrium concept** identifies, for every game, one or more distributions over action profiles (the **equilibria**). Predicts that the outcome of the game is distributed as one of the equilibria.

For complete information games, here are the most notable in order of generality

- Dominant strategy equilibrium
- Nash equilibrium
- Correlated equilibrium
- Coarse-correlated equilibrium



# Equilibrium Concepts

An **equilibrium concept** identifies, for every game, one or more distributions over action profiles (the **equilibria**). Predicts that the outcome of the game is distributed as one of the equilibria.

For complete information games, here are the most notable in order of generality

- Dominant strategy equilibrium
- Nash equilibrium
- Correlated equilibrium
- Coarse-correlated equilibrium

For sequential games, subgame-perfect equilibrium is the most pertinent. Sits between DSE and Nash.

# Dominant-strategy Equilibrium

A strategy  $s_i$  of player  $i$  is a **dominant strategy** if it is a best response to **every** strategy profile  $s_{-i}$  of the other players. Formally, for all profiles  $s_{-i}$  of players other than  $i$ , we should have that  $u_i(s_i, s_{-i}) \geq u_i(s'_i, s_{-i})$  for any other strategy  $s'_i$  of player  $i$ .

- If exists,  $i$  doesn't need to know what others are doing to respond.

# Dominant-strategy Equilibrium

A strategy  $s_i$  of player  $i$  is a **dominant strategy** if it is a best response to **every** strategy profile  $s_{-i}$  of the other players. Formally, for all profiles  $s_{-i}$  of players other than  $i$ , we should have that  $u_i(s_i, s_{-i}) \geq u_i(s'_i, s_{-i})$  for any other strategy  $s'_i$  of player  $i$ .

- If exists,  $i$  doesn't need to know what others are doing to respond.
- If there is a mixed dominant strategy, there is also a pure one.
  - Mixed DS is randomization over pure DS

# Dominant-strategy Equilibrium

A strategy  $s_i$  of player  $i$  is a **dominant strategy** if it is a best response to **every** strategy profile  $s_{-i}$  of the other players. Formally, for all profiles  $s_{-i}$  of players other than  $i$ , we should have that  $u_i(s_i, s_{-i}) \geq u_i(s'_i, s_{-i})$  for any other strategy  $s'_i$  of player  $i$ .

- If exists,  $i$  doesn't need to know what others are doing to respond.
- If there is a mixed dominant strategy, there is also a pure one.
  - Mixed DS is randomization over pure DS

A **dominant-strategy equilibrium** is a strategy profile where each player plays a dominant strategy.

- Exists precisely when each player has a dominant strategy
- Best kind of equilibrium (minimal knowledge assumptions)
- May be pure or mixed (independent randomization). Though mixed DSE are not of much interest.

# Dominant-strategy Equilibrium

A strategy  $s_i$  of player  $i$  is a **dominant strategy** if it is a best response to **every** strategy profile  $s_{-i}$  of the other players. Formally, for all profiles  $s_{-i}$  of players other than  $i$ , we should have that  $u_i(s_i, s_{-i}) \geq u_i(s'_i, s_{-i})$  for any other strategy  $s'_i$  of player  $i$ .

- If exists,  $i$  doesn't need to know what others are doing to respond.
- If there is a mixed dominant strategy, there is also a pure one.
  - Mixed DS is randomization over pure DS

A **dominant-strategy equilibrium** is a strategy profile where each player plays a dominant strategy.

- Exists precisely when each player has a dominant strategy
- Best kind of equilibrium (minimal knowledge assumptions)
- May be pure or mixed (independent randomization). Though mixed DSE are not of much interest.
- Every DSE is also a Nash Equilibrium

# Example: Prisoner's Dilemma

	Coop	Defect
Coop	-1 -1	0 -3
Defect	-3 0	-2 -2

# Example: Prisoner's Dilemma

	Coop	Defect
Coop	-1 -1	0 -3
Defect	-3 0	-2 -2

Dominant strategy: both players defect

# Nash Equilibrium

A **Nash equilibrium** is a strategy profile  $(s_1, \dots, s_n)$  such that, for each player  $i$ ,  $s_i$  is a best response to  $s_{-i}$ .

- If each  $s_i$  is pure we call it a **pure Nash equilibrium**, otherwise we call it a **mixed Nash equilibrium**.
- All players are optimally responding to each other, simultaneously.



# Nash Equilibrium

A **Nash equilibrium** is a strategy profile  $(s_1, \dots, s_n)$  such that, for each player  $i$ ,  $s_i$  is a best response to  $s_{-i}$ .

- If each  $s_i$  is pure we call it a **pure Nash equilibrium**, otherwise we call it a **mixed Nash equilibrium**.
- All players are optimally responding to each other, simultaneously.
- There might be a mixed Nash but no pure Nash (e.g. rock paper scissors)
- Every Nash equilibrium is a correlated equilibrium

# Example: Battle of the Sexes

		W	
	M	Football	Movie
M	Football	1 2	0 0
	Movie	0 0	2 1

# Example: Battle of the Sexes

		W	
	M	Football	Movie
Football		1	0
		2	0
Movie		0	2
		0	1

- Pure Nash: (Football, Football) and (Movie, Movie)

# Example: Battle of the Sexes

		W	
	M	Football	Movie
Football		1	0
		2	0
Movie		0	2
		0	1

- Pure Nash: (Football, Football) and (Movie, Movie)
- Mixed Nash: M goes to Football w.p.  $2/3$  and Movie w.p.  $1/3$ , and W goes to Movie w.p.  $2/3$  and Football w.p.  $1/3$

# Correlated Equilibrium

- Now we look at an equilibrium in which players choose correlated mixed strategies.
- Way to think about it: A mediator (e.g. traffic light) makes correlated action recommendations

A **Correlated equilibrium** is distribution  $x$  over action profiles such that, for each player  $i$  and action  $a_i^* \in A_i$ , we have

$$\mathbf{E}_{a \sim x} [u_i(a) | a_i = a_i^*] \geq \mathbf{E}_{a \sim x} [u_i(a'_i, a_{-i}) | a_i = a_i^*]$$

for all  $a'_i \in A_i$ .

- In other words: If all players other than  $i$  follow their recommendations, then when  $i$  is recommended  $a_i^*$ , his posterior payoff is maximized by following his recommendation as well.

# Example: Battle of the Sexes

		W	
	M	Football	Movie
Football		1	0
		2	0
Movie		0	2
		0	1

# Example: Battle of the Sexes

		W		
	M		Football	Movie
	Football		1	0
			2	0
	Movie		0	2
			0	1

Correlated Equilibrium: Uniformly randomize between (Football, Football) and (Movie, Movie)

# Example: Chicken Game

	STOP	GO
STOP	0, 0	1, -2
GO	-2, 1	-10, -10

- No DSE



# Example: Chicken Game

	STOP	GO
STOP	0, 0	1, -2
GO	-2, 1	-10, -10

- No DSE
- Pure Nash: (STOP, GO) and (GO, STOP)

# Example: Chicken Game

	STOP	GO
STOP	0, 0	1, -2
GO	-2, 1	-10, -10

- No DSE
- Pure Nash: (STOP, GO) and (GO, STOP)
- Mixed Nash: Each player goes w.p.  $1/9$

# Example: Chicken Game

	STOP	GO
STOP	0, 0	1, -2
GO	-2, 1	-10, -10

- No DSE
- Pure Nash: (STOP, GO) and (GO, STOP)
- Mixed Nash: Each player goes w.p.  $1/9$
- Correlated eq:
  - Any randomization over Nash equilibria

# Example: Chicken Game

	STOP	GO
STOP	0, 0	1, -2
GO	-2, 1	-10, -10

- No DSE
- Pure Nash: (STOP, GO) and (GO, STOP)
- Mixed Nash: Each player goes w.p.  $1/9$
- Correlated eq:
  - Any randomization over Nash equilibria
  - Uniformly randomize between (STOP,GO), (GO,STOP), and (STOP,STOP)

# Example: Chicken Game

	STOP	GO
STOP	0, 0	1, -2
GO	-2, 1	-10, -10

- No DSE
- Pure Nash: (STOP, GO) and (GO, STOP)
- Mixed Nash: Each player goes w.p.  $1/9$
- Correlated eq:
  - Any randomization over Nash equilibria
  - Uniformly randomize between (STOP,GO), (GO,STOP), and (STOP,STOP)
  - What else?

# Existence of Equilibria

- Pure Nash equilibria and dominant strategy equilibria do not always exist (e.g. rock paper scissors)
- However, mixed Nash equilibrium always exists when there is a finite number of players and actions!

## Theorem (Nash 1951)

Every *finite game* admits a mixed Nash equilibrium.

# Existence of Equilibria

- Pure Nash equilibria and dominant strategy equilibria do not always exist (e.g. rock paper scissors)
- However, mixed Nash equilibrium always exists when there is a finite number of players and actions!

## Theorem (Nash 1951)

Every *finite game* admits a mixed Nash equilibrium.

- Generalizes to some infinite games (continuous, compact)
- Implies existence for correlated equilibria as well.

# Existence of Equilibria

- Pure Nash equilibria and dominant strategy equilibria do not always exist (e.g. rock paper scissors)
- However, mixed Nash equilibrium always exists when there is a finite number of players and actions!

## Theorem (Nash 1951)

Every *finite game* admits a mixed Nash equilibrium.

- Generalizes to some infinite games (continuous, compact)
- Implies existence for correlated equilibria as well.
- Proof is difficult. Much easier in the special case of zero-sum games (LP duality)



# Arguments for/against Nash Equilibrium

Mixed Nash is most widely accepted / used equilibrium concept.

# Arguments for/against Nash Equilibrium

Mixed Nash is most widely accepted / used equilibrium concept.

In favor:

- Always exists
- Requires no correlation device
- After players find a Nash equilibrium, it is a self-enforcing agreement or stable social convention
  - MWG has a nice discussion

# Arguments for/against Nash Equilibrium

Mixed Nash is most widely accepted / used equilibrium concept.

In favor:

- Always exists
- Requires no correlation device
- After players find a Nash equilibrium, it is a self-enforcing agreement or stable social convention
  - MWG has a nice discussion

Against:

- There might be many Nash equilibria. How do players choose one collectively?
- Sometimes, no natural behavioral dynamics which converge to a Nash eq
- Sometimes hard to compute (PPAD complete in general)
  - “If your laptop can’t find it then neither can the market” – Kamal Jain

# Outline

- 1 Introduction
- 2 Games of Complete Information
- 3 Games of Incomplete Information
  - Prior-free Games
  - Bayesian Games

- In settings of complete information, Nash equilibria are a defensible prediction of the outcome of the game.
- In many settings, as in auctions, the payoff structure of the game itself is private to the players.
- How can a player possibly play his part of the Nash equilibrium if he's not sure what the game is, and therefore where the equilibrium is?
  - i.e. the set of Nash equilibria depends on opponents' private information.

- In settings of complete information, Nash equilibria are a defensible prediction of the outcome of the game.
- In many settings, as in auctions, the payoff structure of the game itself is private to the players.
- How can a player possibly play his part of the Nash equilibrium if he's not sure what the game is, and therefore where the equilibrium is?
  - i.e. the set of Nash equilibria depends on opponents' private information.

### Example: First price auction

$v_1 = 3$ ,  $v_2$  is either 1 or 2, and a bid must be multiple of  $\epsilon > 0$ . The following is a Nash equilibrium:  $b_1 = v_2 + \epsilon$  and  $b_2 = v_2$ .

- Player 1's equilibrium bid depends on player 2's private information!

- In settings of complete information, Nash equilibria are a defensible prediction of the outcome of the game.
- In many settings, as in auctions, the payoff structure of the game itself is private to the players.
- How can a player possibly play his part of the Nash equilibrium if he's not sure what the game is, and therefore where the equilibrium is?
  - i.e. the set of Nash equilibria depends on opponents' private information.

### Example: First price auction

$v_1 = 3$ ,  $v_2$  is either 1 or 2, and a bid must be multiple of  $\epsilon > 0$ . The following is a Nash equilibrium:  $b_1 = v_2 + \epsilon$  and  $b_2 = v_2$ .

- Player 1's equilibrium bid depends on player 2's private information!

To explicitly model uncertainty, and devise credible solution concepts that take it into account, **games of incomplete information** were defined.

Two main approaches are used to model uncertainty:

① Prior-free:

- A player doesn't have any beliefs about the private data of others (other than possible values it may take), and therefore about their strategies.
- Only consider a strategy to be a “credible” prediction for a player if it is a best response in every possible situation.

② Bayesian Common Prior:

- Players' private data is drawn from a distribution, which is common knowledge
- Player only knows his private data, but knows the distribution of others'
- Bayes-Nash equilibrium generalizes Nash to take into account the distribution.

Though there are other approaches. . .



# Prior-free Games

An  $n$ -player **game of strict incomplete information** is given by

- A set of players  $N = \{1, \dots, n\}$ .
- For each player  $i$ , a set of **actions**  $A_i$ .
  - Let  $A = A_1 \times A_2 \times \dots \times A_n$  denote the set of **action profiles**.
- For each player  $i$ , a set of **types**  $T_i$ 
  - Let  $T = T_1 \times T_2 \times \dots \times T_n$  denote the set of **type profiles**.
- For each player  $i$ , a utility function  $u_i : T \times A \rightarrow \mathbb{R}$ 
  - We focus on **independent private values**:  $u_i : T_i \times A \rightarrow \mathbb{R}$
  - $u_i(t_i, \vec{a})$  is utility of  $i$  when he has type  $t_i$  and players play  $\vec{a}$

# Prior-free Games

An  $n$ -player **game of strict incomplete information** is given by

- A set of players  $N = \{1, \dots, n\}$ .
- For each player  $i$ , a set of **actions**  $A_i$ .
  - Let  $A = A_1 \times A_2 \times \dots \times A_n$  denote the set of **action profiles**.
- For each player  $i$ , a set of **types**  $T_i$ 
  - Let  $T = T_1 \times T_2 \times \dots \times T_n$  denote the set of **type profiles**.
- For each player  $i$ , a utility function  $u_i : T \times A \rightarrow \mathbb{R}$ 
  - We focus on **independent private values**:  $u_i : T_i \times A \rightarrow \mathbb{R}$
  - $u_i(t_i, \vec{a})$  is utility of  $i$  when he has type  $t_i$  and players play  $\vec{a}$

When each player has just one type, what is this?

# Prior-free Games

An  $n$ -player **game of strict incomplete information** is given by

- A set of players  $N = \{1, \dots, n\}$ .
- For each player  $i$ , a set of **actions**  $A_i$ .
  - Let  $A = A_1 \times A_2 \times \dots \times A_n$  denote the set of **action profiles**.
- For each player  $i$ , a set of **types**  $T_i$ 
  - Let  $T = T_1 \times T_2 \times \dots \times T_n$  denote the set of **type profiles**.
- For each player  $i$ , a utility function  $u_i : T \times A \rightarrow \mathbb{R}$ 
  - We focus on **independent private values**:  $u_i : T_i \times A \rightarrow \mathbb{R}$
  - $u_i(t_i, \vec{a})$  is utility of  $i$  when he has type  $t_i$  and players play  $\vec{a}$

When each player has just one type, what is this?

## Example: Vickrey (Second-price) Auction

- $A_i = \mathbb{R}$  is the set of possible bids of player  $i$ .
- $T_i = \mathbb{R}$  is the set of possible values for the item.
- For  $v_i \in T_i$  and  $b \in A$ , we have  $u_i(v_i, b) = v_i - b_{-i}$  if  $b_i > b_{-i}$ , otherwise 0.

# Strategies in Incomplete Information Games

- Strategies of player  $i$ 
  - **Pure strategy**  $s_i : T_i \rightarrow A_i$ : a choice of action  $a_i \in A_i$  for every type  $t_i \in T_i$ .
    - Example: Truthful bidding (i.e., bidding your value)
    - Another example: Bidding half your value
  - **Mixed strategy**: a distribution  $s_i(t_i)$  over actions  $A_i$  for each type  $t_i \in T_i$ 
    - Example: Bidding  $b_i$  uniform in  $[0, v_i]$

# Strategies in Incomplete Information Games

- Strategies of player  $i$ 
  - **Pure strategy**  $s_i : T_i \rightarrow A_i$ : a choice of action  $a_i \in A_i$  for every type  $t_i \in T_i$ .
    - Example: Truthful bidding (i.e., bidding your value)
    - Another example: Bidding half your value
  - **Mixed strategy**: a distribution  $s_i(t_i)$  over actions  $A_i$  for each type  $t_i \in T_i$ 
    - Example: Bidding  $b_i$  uniform in  $[0, v_i]$

## Note

- In a strategy, player decides how to act based only on his private info (his type), and NOT on others' private info nor their actions (neither of which he knows).
- A strategy profile  $(s_1, \dots, s_n)$  describes what would happen in each "state of the world" (i.e., type profile)  $(t_1, \dots, t_n)$ , regardless of the relative frequency of various states.
  - In state  $(t_1, \dots, t_n)$ , players play  $(s_1(t_1), \dots, s_n(t_n))$ .

# Dominant Strategy Equilibrium

DS and DSE generalize naturally to incomplete information games

$s_i : T_i \rightarrow \Delta(A_i)$  is a **dominant strategy** for player  $i$  if, for all  $t_i \in T_i$  and  $a_{-i} \in A_{-i}$  and  $a'_i \in A_i$ ,

$$u_i(t_i, (s_i(t_i), a_{-i})) \geq u_i(t_i, (a'_i, a_{-i}))$$

- Equivalently:  $s_i(t_i)$  is a best response to  $a_{-i} \sim s_{-i}(t_{-i})$ , for all  $t_i$ ,  $t_{-i}$ ,  $s_{-i}$ , and realization  $a_{-i}$ .
- In order to choose his best response, player  $i$  only needs to know his own type  $t_i$ , but not the types  $t_{-i}$  of other players, nor their strategies  $s_{-i}$ .
- As in complete info case, if there is DS, then there is a pure DS (i.e.,  $s_i : T_i \rightarrow A_i$ )

# Dominant Strategy Equilibrium

A **dominant-strategy equilibrium** is a strategy profile where each player plays a dominant strategy.

# Dominant Strategy Equilibrium

A **dominant-strategy equilibrium** is a strategy profile where each player plays a dominant strategy.

In the absence of any information (e.g. prior probabilities) about the relative frequency of various type profiles, this is the only “credible” equilibrium concept for incomplete information games.



# Dominant Strategy Equilibrium

A **dominant-strategy equilibrium** is a strategy profile where each player plays a dominant strategy.

In the absence of any information (e.g. prior probabilities) about the relative frequency of various type profiles, this is the only “credible” equilibrium concept for incomplete information games.

Essentially same properties, pros/cons, as in complete info

- Exists precisely when each player has a dominant strategy
- If there is DSE, then there is a pure DSE (i.e.,  $s_i : T_i \rightarrow A_i$  for each  $i$ )
- Best kind of equilibrium (minimal knowledge assumptions)
- May be pure or mixed. Though mixed DSE are not of much interest.
- Every DSE is also a Bayes-Nash Equilibrium

## Vickrey (second-price) Auction

Consider a Vickrey Auction with incomplete information.

## Vickrey (second-price) Auction

Consider a Vickrey Auction with incomplete information.

### Claim

The truth-telling strategy is dominant for each player.

Prove as an exercise

# Bayesian Games

An  $n$ -player **Bayesian game of Incomplete information** is given by

- A set of players  $N = \{1, \dots, n\}$ .
- For each player  $i$ , a set of **actions**  $A_i$ .
  - Let  $A = A_1 \times A_2 \times \dots \times A_n$  denote the set of **action profiles**.
- For each player  $i$ , a set of **types**  $T_i$ 
  - Let  $T = T_1 \times T_2 \times \dots \times T_n$  denote the set of **type profiles**.
- For each player  $i$ , a utility function  $u_i : T \times A \rightarrow \mathbb{R}$ 
  - We focus on **independent private values**:  $u_i : T_i \times A \rightarrow \mathbb{R}$
  - $u_i(t_i, \vec{a})$  is utility of  $i$  when he has type  $t_i$  and players play  $\vec{a}$
- **Common prior**: distribution  $\mathcal{D}$  of  $T$ .

# Bayesian Games

An  $n$ -player **Bayesian game of Incomplete information** is given by

- A set of players  $N = \{1, \dots, n\}$ .
- For each player  $i$ , a set of **actions**  $A_i$ .
  - Let  $A = A_1 \times A_2 \times \dots \times A_n$  denote the set of **action profiles**.
- For each player  $i$ , a set of **types**  $T_i$ 
  - Let  $T = T_1 \times T_2 \times \dots \times T_n$  denote the set of **type profiles**.
- For each player  $i$ , a utility function  $u_i : T \times A \rightarrow \mathbb{R}$ 
  - We focus on **independent private values**:  $u_i : T_i \times A \rightarrow \mathbb{R}$
  - $u_i(t_i, \vec{a})$  is utility of  $i$  when he has type  $t_i$  and players play  $\vec{a}$
- **Common prior**: distribution  $\mathcal{D}$  of  $T$ .

## Example: First Price Auction

- $A_i = T_i = [0, 1]$
- $\mathcal{D}$  draws each  $v_i \in T_i$  uniformly and independently from  $[0, 1]$ .
- $u_i(v_i, b) = v_i - b_i$  if  $b_i > b_{-i}$ , or 0 if  $b_i < b_{-i}$  (ignoring ties for now).

# Bayes-Nash Equilibrium

As before, a pure strategy  $s_i$  for player  $i$  is a map from  $T_i$  to  $A_i$ . Now, we define the extension of pure Nash equilibrium to this setting.

A pure **Bayes-Nash Equilibrium** of a Bayesian Game of incomplete information is a set of strategies  $s_1, \dots, s_n$ , where  $s_i : T_i \rightarrow A_i$ , such that for all  $i$ ,  $t_i \in T_i$ ,  $a'_i \in A_i$  we have

$$\mathbf{E}_{t_{-i} \sim \mathcal{D} | t_i} u_i(t_i, s(t)) \geq \mathbf{E}_{t_{-i} \sim \mathcal{D} | t_i} u_i(t_i, (a'_i, s_{-i}(t_{-i})))$$

where the expectation is over  $t_{-i}$  drawn from  $\mathcal{D}$  after conditioning on  $t_i$ .

- Mixed BNE defined analogously: allow  $s_i : T_i \rightarrow \Delta(A_i)$ , and take expectations accordingly in the definition.
- Note: Every dominant strategy equilibrium is also a Bayes-Nash Equilibrium
- But, unlike DSE, (mixed) BNE is guaranteed to exist.

# Example: First Price Auction

## Example: First Price Auction

- Two players
- $A_i = T_i = [0, 1]$
- $\mathcal{D}$  draws each  $v_i \in T_i$  uniformly and independently from  $[0, 1]$ .
- $u_i(v_i, b) = v_i - b_i$  if  $b_i > b_{-i}$  (winner),  $= \frac{1}{2}(v_i - b_i)$  if  $b_1 = b_2$  (tied), and  $= 0$  otherwise (loser).

Exercise: Show that the strategies  $b_i(v_i) = v_i/2$  form a pure Bayes-Nash equilibrium.

## Theorem

*Every finite Bayesian game of incomplete information admits a mixed Bayes-Nash equilibrium.*

- Can prove it using Nash's theorem.
- It so happens that, in most natural Bayesian games we look at, there will be a pure BNE.



# Bayes Correlated Equilibrium

- There is also a natural generalization of Correlated equilibrium to Bayesian games, called the **Bayes correlated equilibrium**
- Every BNE is a BCE, therefore BCE always guaranteed to exist for finite Bayesian games.
- There are also interesting BCE which are not BNE
- Conceptually, gets harder to wrap your head around the BCE definition. But, we won't need it in this class (I think) so won't get into it.