# Wei-Min Shen

Computer Science Department and/or USC/ISI	Home Residence
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Email: <u>wmshen@usc.edu</u> , shen@isi.edu, URL: http://www.isi.edu/robots	
Education	

PhD Computer Science, Carnegie Mellon University, Pittsburgh, USA	1989
Thesis: Learning from the Environment Based on Actions and Percepts	
Advisor: Professor Herbert A. Simon (Nobel Price Winner)	
MS Computer Science, Carnegie Mellon University, Pittsburgh, USA	1986
The First-Place Graduate Student selected by the Chinese government to study AI in USA	1983
MS Graduate Study, Institute of Automation, Academy of Sciences, China	1983
BS Electronics and Computer Engineering, Jiao-Tong University, Beijing, China	1982

# **Honors and Awards**

Senior Member, National Academy of Inventors, USA	2024
Honored World-Class Expert Scientific Reviewer for European Scientific Commission	2010-2015
USC Rose Hills Foundation Summer Science and Engineering Fellowship (for advisors)	2010
Best Robotics Paper Award at the 26 <sup>th</sup> Army Science Conference	2008
Championship at the first ICRA planetary contingency robotic competition	2008
Phi Kappa Phi Faculty Recognition Award, University of Southern California	2003
The Best Paper Award, International Conference on Simulation of Adaptive Behaviors	2002
The World Champion Award, the International Robotic-Soccer Competition, Nagoya, Japan	1997
(Featured on CNN, ABC, Discovery, SCIENCE, and world-wide newspapers and magazines)	
Meritorious Service Award, Information Sciences Institute, University of Southern California	1997
Second Place Award in AAAI Robotics Competition, Portland, Oregon (featured on PBS and CNN)	1996
National Scholarship Award for Education Abroad, The Chinese Ministry of Education	1983
First Place Student Award of National Graduate Examination, Academy of Sciences, China	1983
Outstanding University Graduate Award (top 2%), Jiao-Tong University, Beijing, China	1982

# **Invited Keynote Speaker**

Invited Keynote Speaker, the 7th World Conference on Structural Control and Monitoring, China	2018
Invited Keynote Speaker, Shen-Yang Institution of Automation, Science Academy, China	2013
Invited Keynote Speaker, International Conference on Swarm Intelligence, Brussels, Belgium	2010
Invited Keynote Speaker, Beijing Institution of Automation, Science Academy, China	2008
Invited Keynote Speaker, the 50th Anniversary of AI, Barcelona Science Museum, Spain	2006
Invited Keynote Speaker, the International Conference on Complex Systems, Boston, USA	2004
Invited Keynote Speaker, the TTI Vanguard Convention, Los Angeles, USA	2001

# **US Patents**

METHOD AND APPARATUS FOR CONTROL OF MULTIPLE AUTONOMOUS MOBILE NODES BASED	
ON DYNAMIC SITUATIONAL AWARENESS DATA, U.S. App. No. 15/859,495	2020
Method and Apparatus for Biologically Inspired Autonomous Infrastructure Monitoring, US #14/716,852	2017
Method and Apparatus for Control of Multiple Autonomous Nodes	
Based on Dynamic Situational Awareness DataUS #9,894,158	2015
A Multifunctional Device for Assisting Human Transfer, Mobility, and Rehabilitation, US Patent Pending	2013
A Genderless and Single-Side-Operational Connector Mechanism for Self-Reconfigurable,	
Self-Assembly and Self-Healing SystemsUS #8,234,950	2012
Extremely Flexible Thruster System for Underwater Vehicles US #8,082,870	2011

Distributed Control & Coordination of Autonomous Agents in Dynamic and Reconfigurable Systems

### **Research Experience**

University of Southern California, Los Angeles, CA

University of Southern Camornia, Los Angeles, CA		
Associate Professor of Computer Science	Computer Science Department, USC	2019—
Director	Polymorphic Robotics Laboratory, USC/ISI	1999—
Associate Director	Center for Robotics and Embedded Systems, USC	2002—
Research Team Leader	Information Sciences Institute, USC	1998—
Research Associate Professor	Computer Sciences Department, USC	2005—
Research Assistant Professor	Computer Sciences Department, USC	
Computer Scientist	Information Sciences Institute, USC	1994—
Co-Founder and Vice President	EpiSys Science Inc., San Diego, CA	2012—
Co-Founder and Vice President	AARICO Corp, Los Angeles, CA	2005—
Microelectronics and Computer Technology Corpora	ation (MCC), Austin TX	
Project Leader		1994
Senior Member of Technical Staff		1993-94
Member of Technical Staff		1989-93
Carnegie Mellon University, Pittsburgh, PA		
Graduate Research Assistant	Department of Computer Science	1983-89
Graduate Teaching Assistant	Department of Computer Science	1987-88
Chinese Academy of Sciences, Beijing, China		
Graduate Research Assistant	Institute of Automation	1982-83

# **Teaching Experience**

Foundation of Artificial Intelligence (CSCI-561), University of Southern California (USC)	2013-2023
Massive Data Mining Technology (DSCI-553), University of Southern California (USC)	2019-2023
Machine Learning for Data Science (INF552), University of Southern California (USC)	2019-2020
Foundation of Artificial Intelligence (CS360), University of Southern California (USC)	2013-2018
Advisor for PhD Students, University of Southern California, USA	1996-2018
Autonomous Robots (PTE587) USC, Department of Chemical Engineering and Material Science	2007-09
Lectures for PhD Seminar Series (CSCI 597), USC, Department of Computer Science	2007-09
Autonomous Learning and Discovery Robots (CS593) (Designer of this course), USC, CS Dept	1997-98
Autonomous Learning from the Environment (CS599), USC, Computer Science Department	1996
Deductive Databases and Data Mining (lectures for CS589), USC, Computer Science Department	1995-96
Data Mining and Knowledge Discovery in Databases, University of California at Los Angeles (UCLA)	1998-99
Data Mining Technology and Applications, NASA Jet Propulsion Laboratory, Pasadena, California	1999
Lectures on Autonomous Learning from the Environment, University of Texas at Austin, Business School	ol 1991
Lectures on Semantic Integration of Heterogeneous Databases, UT Austin, Business School	1994
Introduction to Programming Languages (TA), Carnegie Mellon University, Computer Science	1986-87

### **Grants and Contracts**

KISR-USC Research Fund (Co-PI with Masri, \$100K)	2018
US Air Force, NASA, NAV-COM, SBIR Phase I and II (Total of ~\$750K)	2014-2017
DARPA TTO, Star Cell Project (PI, \$1.0M)	2013-2017
USC/Keston Research Fund (PI, \$100K)	2017
Qatar NSF, Reconfigurable robots for infrastructure inspection (\$150K)	2015-2016
NAV-COM, SBIR Phase I (\$200K)	2014-2015
NASA, STTR with EpiSciences Inc., \$500K	2013-2014
DARPA, PHOENIX, (Co-PI with AMD-USA), \$1.0M	2012-2014
DARPA, Mind's Eye, (Co-PI for Ram Nevatia), \$1.2M	2010-2013
DARPA, CommEX, (Co-PI for Preston Marshall), \$170K	2010-2012
AFOSR, Reconfigurable robots for security, (PI), \$60K	2010-2011

US #006636781 2003

ARO, micro-reconfigurable robots, (PI), \$50K	2010-2011
DARPA, LANDroids mobile robotic networks, (PI), \$550K	2008-2009
AFOSR, Surprise-Based Learning (PI), \$600K	2006-2009
NASA, Modular, Self-Reconfigurable and Multifunctional <i>SuperBot</i> , (PI) \$4.23M	2005-2008
DARPA, Cognitive Architecture COGENT, (key contributor) \$125K	2006-2007
DURIP, Self-Healing Robotic Modules, (PI) \$200K,	2005-2007
Army Research Office, Self-reconfigurable robotics systems, (PI) \$250K	2005-2007
DARPA, Applied Learning Networks, \$400K (Co-PI for Joe Banister)	2005-2007
CiSoft, Robotics and AI for Intelligent Oil Field, Chevron-Texaco (PI), \$150K	2005-2007
NSF, Space Self-Assembly via Self-Reconfigurable Robots, (PI), \$600K	2002-2004
NSF, Meta-pattern Based Data Mining Systems, (PI), \$300K	1996-1999
AFOSR, Cooperative Control Program, (PI), \$284K	2001-2003
AFOSR, Self-Organizing and Autonomous Learning Agents, (PI), \$950K	2000-2004
AFOSR, Adaptive Agent Organizations, (PI), \$700K	1997-2000
DARPA, Self-Reconfigurable Robots, (Co-PI for Peter Will), \$3.0M	1998-2002

### **PhD Student Supervision**

Current PhD students, University of Southern California None

Former PhD students, University of Southern California

Collins, Thomas, Computer Science, 2012-present (thesis defensed in 2018) Chen, Chi-An, Computer Science, 2012-present (thesis defensed in 2018) Barrios, Luenin, Computer Science, 2010-2017 (thesis defensed in 6/2017) Jacob Everist, Computer Science, 2004-2015 (thesis defensed on 2/2/2015) Nadeesha Ranasinghe, Computer Science, 2006-2013 (thesis defensed on August 14, 2012) Feili Hou, Computer Science, 2004-2010, Thesis topic: Optimal self-reconfiguration, Current at Apple. Mike Rubenstein, 2004-2009, Computer Science, Thesis topic: Self-Assembly and Self-Healing for Robotic Collectives. Current Position: Assistant Processor, Northwestern University. Jay Modi, 1998-2003, Thesis topic: Distributed Constraint Optimization for Multi-Agent Systems. Current position: Assistant Professor in Computer Science, Drexel University. (Deceased) Kasper Stoy, 2001-2002, Thesis Topic: Control of Self-Reconfigurable Robots. Current position: Professor in Computer System Engineering, University of Copenhagen, University of Southern Denmark. Behnam Salemi, 1997-2003, Thesis topic: Distributed Control for Chain-Typed Self-Reconfigurable Robots. Current position: Computer Scientist, Hughes Research Center, Malibu, CA. Jafar Adibi, 1997-2002, Thesis topic: Self-Similarity and Extended Hidden Markov Models for Data Mining. Current position: Project Leader, Price Waterhouse.

PhD Committee Member, University of Southern California

Mohamed H. Abdelbarr, 2018, Civil Engineering, Main Advisor: Professor Sami Masri
Jens Windau, 2017, Computer Science, Main Advisor: Professor Laurent Itti
Furqan Khan, 2013, Main Advisor: Professor Ram Nevatia, Thesis title: Analyzing human activities in
videos using component based models.
Anna Li, 2008, Main Advisor: Professor Steven Lu, Thesis topic: Massive User Enabled Evolving Web

*Anna Li*, 2008, Main Advisor: Professor Steven Lu, Thesis topic: Massive User Enabled Evolving Web. *Daniel Arbuckle*, 2007, Main Advisor: Professor Arisitdes Requicha. Thesis Topic: Self-Assembly Systems. Current position: USC.

*Ayanna Howard*, 1999, Main Advisor: Professor George Bekey. Current position: Associate Professor, George Tech. Thesis topic: Manipulation of deformed objects.

*Alex Guazzelli*, 1999, Main Advisor: Professor Michael Arbib. Current position: Computer Scientist in Brazil. Thesis topic: Hippocampus and navigation.

*James Montgomery*, 1998, Main Advisor: Professor George Bekey. Current position: Robotics in JPL. Thesis topic: Fuzzy control of autonomous helicopter.

<i>Michael McHenry</i> , 1998, Main Advisor: Professor George Bekey. Current position: Senior member of technical staff in JPL.
<i>Fernando Corbacho</i> , 1997, Main Advisor: Professor Michael Arbib. Current position: Computer Scientist Madrid, Spain. Thesis topic: Integrated Learning in Rana Computatrix. <i>Bonghan Cho</i> , 1996, Main Advisor: Professor Paul Rosenbloom. Current position, Philips Electronics Thesis topic: Fast matching in AI production systems.
University of Brussels, Belgium (September 2010) Invited committee member for PhD defense by Rehan O'Grady on self-assembly of swarm robots Supervisor: Dr. Marco Dorigo
University of South Denmark (September 2008) Invited committee member for PhD defense by <i>David Christensen</i> on self-reconfigurable robots Supervisor: Dr. Henrik Hautop Lund
University of Hong Kong (2007) Invited committee member for PhD defense by <i>Scott Howe</i> on self-reconfigurable architecture/structures Supervisor: Dr. H.Y.K. Lau
Politechnical University of Catalonia, Barcelona, Spain (December 2003) Invited committee member for PhD defense by <i>Jesus Cerquides</i> on Bayesian Network Classifiers Supervisor: Dr. Ramon López de Mántaras
University of New South Wales, Sydney, Australia (1998) Invited committee member for PhD defense by <i>Rex Kwok</i> on Computational Scientific Discovery Supervisor: Dr. Norman Foo

University of Texas at Austin, USA (1992-1994)

*Rwo-Hsi Wang*, 1994, Supervisor: Dr. Al Mok. Thesis topic: Data analysis for electronic devices. *Tsing-Hwa Chi*, 1992, Supervisor: Dr. Andrew Whinston. Thesis topic: Learning for information management. Current position: Department Chairman and Professor, University of California at Long Beach.

### **Master Student Supervision**

(see the list on my website)2019-2020Shuo Cong, Zhapeng He, Niantian Zhang, and others, Computer Science2016-2018Grace Lo, Computer Science, Supervised control of SuperBot robots2013Teawon Han, Computer Science, Adaptive locomotion for self-reconfigurable rolling track2012Chi-An Chen, Computer Science, Power sharing for self-reconfigurable robots2010Yujie Hao, Computer Science, distributed control of self-reconfigurable manipulation2010Jens Windau, Computer Science, inertia-based surface identification for robot locomotion2009-2010David Yao, Computer Science, self-reconfigurable robots2008Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Grace Lo, Computer Science, Supervised control of SuperBot robots2013Teawon Han, Computer Science, Adaptive locomotion for self-reconfigurable rolling track2012Chi-An Chen, Computer Science, Power sharing for self-reconfigurable robots2013Yujie Hao, Computer Science, distributed control of self-reconfigurable manipulation2010Jens Windau, Computer Science, inertia-based surface identification for robot locomotion2009-2010David Yao, Computer Science, control of self-reconfigurable robots2009Rizwan Khan, Computer Science, self-reconfigurable robots2008Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Teawon Han, Computer Science, Adaptive locomotion for self-reconfigurable rolling track2012Chi-An Chen, Computer Science, Power sharing for self-reconfigurable robots2012Yujie Hao, Computer Science, distributed control of self-reconfigurable manipulation2010Jens Windau, Computer Science, inertia-based surface identification for robot locomotion2009-2010David Yao, Computer Science, control of self-reconfigurable robots2009Rizwan Khan, Computer Science, self-reconfigurable robots2008Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Chi-An Chen, Computer Science, Power sharing for self-reconfigurable robots2012Yujie Hao, Computer Science, distributed control of self-reconfigurable manipulation2010Jens Windau, Computer Science, inertia-based surface identification for robot locomotion2009-2010David Yao, Computer Science, control of self-reconfigurable robots2009Rizwan Khan, Computer Science, self-reconfigurable robots2008Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Yujie Hao, Computer Science, distributed control of self-reconfigurable manipulation2010Jens Windau, Computer Science, inertia-based surface identification for robot locomotion2009-2010David Yao, Computer Science, control of self-reconfigurable robots2009Rizwan Khan, Computer Science, self-reconfigurable robots2008Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Jens Windau, Computer Science, inertia-based surface identification for robot locomotion2009-2010David Yao, Computer Science, control of self-reconfigurable robots2009Rizwan Khan, Computer Science, self-reconfigurable robots2008Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
David Yao, Computer Science, control of self-reconfigurable robots2009Rizwan Khan, Computer Science, self-reconfigurable robots2008Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Rizwan Khan, Computer Science, self-reconfigurable robots2008Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Nisha Ganeriwal, Computer Science, self-reconfigurable robots2008Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Duckho Kim, Computer Science, self-reconfigurable robots2007Peter Shin, Computer Science, self-reconfigurable robots2007
Peter Shin, Computer Science, self-reconfigurable robots 2007
Nicholas Kiswanto, Underwater autonomous vehicles 2007
<i>Lim Harold</i> , Underwater autonomous vehicles 2006
Kenneth Payne, Autonomous docking for self-reconfigurable robots 2005
Harris Chiu, Self-reconfigurable robot locomotion in complex environment 2005
Jagadesh Venkendesh, Self-reconfigurable robot locomotion in complex environment 2005
James Han, Self-reconfigurable robots for climbing behaviors 2005
Harshit Suri, The design and control of self-assembly FIMER robots 2004
<i>Kasra Mogharei</i> , The design and control of self-reconfigurable robots 2004

Nadeesha Ranasinghe, Simulation of self-reconfiguration in complex environment	2003
Yusuf Ateskan, Control of self-assembly modules in space	2003
Aseem Mohanty, Autonomous learning of object models from the environment	2001
Yimin Lu, Distributed Control of Self-Reconfigurable Robots	2000
XueJun Wang, Data mining and model discovery from legacy databases	2000

# **Other Student Supervision**

University of Southern California	
Supervisor for SURE Fellowship Awardee Students 2015	-2017
Supervisor for Rose Hills Foundation Summer Science and Engineering Fellowship Grant 20	10
Undergraduate students:	
Reese Mozer, Noah Olsman, Steven Spinn, Justin Lei, Michele Kawate, James Lee. 20	10
Noah Olsman is a recipient of NSF Research Experience for Undergraduates (REU)	
High School students:	
	2013
Josh Lappen, Harvard-Westlake, (admitted to Stanford in 2013)	2012
8,	2009
PhD students under my supervision but departed before graduation	
Harry Chiu, taking an high-paid position in industry 2006	-2011
Maxim Krivokon, (USC Scholarship) departed for a personal reason 2003	-2005
Yimin Liu, departed for an attractive position in Oracle 1998	-2000
Xuejun Wang, departed for an industry position for data mining 1996	-1998

# **Consulting Experience**

AARICO Corp., Los Angelos, CA, USA.	2005-2020
Episys Sciences Inc., San Diego, CA, USA.	2012-2020
Tsinghua University, Beijing, China	2001
Shanghai Grandar Electronic & Information Co., Ltd., Shanghai, China	2001-2002
G.K. Intelligent System, Houston, TX, USA. Applying Data Mining to Enterprise Integration.	1997-1998
The company also licensed a data mining software package developed by my DataCrystal project.	

# **Special Scientific Review Committee Invitations**

NASA, Scientific Review Committee for Robotics	2016-2018
US National Science Foundation, Panel Review for Robotics	2010-2018
EU Flagship Review Committee	2012-2015
EU Cognitive Systems and Robotics Proposal Review Committee	2010-2015
EU Large Integrated Project Review Committee	2009-2012
US Army Research Office, Five-Year Strategic Planning for Robotics in Mechanical Sciences	2009
External Proposal Reviewer for AFOSR, ARL, NASA	1999-2007
JPL, External Reviewer, NASA's Deep Space Mission System Program and Mars Technology Program	2004-2006
Portuguese National Foundation for Science and Technology, Special Proposal Review Committee	2000
US National Science Foundation, Panel Review for Computation and Social Systems Program	1999
US National Science Foundation, Panel Review for Robotics and Intelligent Systems Program	1994-1995
US National Science Foundation, Panel Review for Database and Information Management Program	1991

### **Invited Demonstrations**

WIRED NextFest, LA Convention Center, http://www.wirednextfest.com/ Self-Reconfigurable Robots	09/2007
California Science Museum, Autonomous Soccer-Playing Robots	07/1999

### **Invited Presentations**

Invited Speaker for Self-Reconfigurable Robots, Cornell University, Computer Science Department	2016
IEEE Robotics and Automation Chapter at California Lutheran University, Buenaventura Section	12/03/2014
The 7 <sup>th</sup> Robotics Workshop, US Army RDECOM/TARDEC Joint Center for Robotics	12/11/2009
Robotics Institute, Carnegie Mellon University, RI Seminar	09/18/2009
iRobot Corporation, topic: Self-Reconfigurable Robots	05/20/2009
Institution of Automation, Academy of Sciences, Beijing, China	10/17/2007
University of Rome, Italy, Seminar on Self-Reconfigurable Robots	06/29/2007
Oxford University, Pembroke College, Natural and Artificial Cognition	06/23/2007
Google, Santa Monica, Self-Reconfigurable Robots	02/28/2007
Japan External Trade Organization, LA Office	02/27/2007
Monterey Bay Aquarium Research Institute, Self-reconfigurable robots for underwater applications.	9/9/2006
Universitat de Girona; Girona, Spain	10/25/2006
Universitat Rovira I Virgili, Tarragona, Spain	10/26/2006
Oxford University, Robotics Seminar on Self-reconfigurable robots	11/2006
University of California, Berkeley, EECS, Seminar on Self-Assembly	11/14/2005
University of Pennsylvanian, GRASP Robotics Seminar	4/8/2005
University of Maryland at College Park, Robotics Seminar	06/2004
NASA Workshop on Modular and self-reconfigurable systems	4/2004
Spanish Council for Scientific Research	12/2003
Spanish Artificial Intelligence Research Institute	12/2003
Institute de Robòtica i Informàtica Industrial, Barcelona, Spain	12/2003
Australian Center for Field Robotics Seminar, University of Sydney, Self-Reconfigurable Robots	7/24/2003
UC San Diego, Invited AI Seminar, Self-Reconfigurable Robots and Digital Hormones	2/22/2003
NASA Ames Research Center, Invited Presentation, Self-Assembly for RoboSphere	11/2002
Stanford Research Institute, Invited Colloquium, Self-Reconfigurable Robots	11/2002
Naval Research Laboratory, Invited AI Seminar, Self-reconfigurable Robots	06/2002
UCLA, Invited CS Seminar, Self-Reconfigurable Robots and Digital Hormones	1/31/2002
NASA Langley Research Center, Workshop on Human and Robotics Space Exploration	11/2001
NASA Ames Research Center, Invited Seminar, Self-Reconfigurable Robots	8/2001
MicroSoft Research Center, Invited Seminar, Soccer and Self-Reconfigurable Robots, Beijing, China	6/2001
Tsinghua University, Self-Reconfigurable Robots, Beijing, China	6/2001
Chinese Science Academy, SherYang Institute of Automation, Invited Seminar, On Self-Reconfiguration	
ShanHai JiaoTong University, Invited Talk, Self-Adaptive Robot Organizations, China	4/2001
American Radiology Society, Data mining techniques and their medical applications	11/1999
USC Aerospace and Mechanical Engineering Invited Seminar, On Adaptive Organizations	1999
UCLA, Invited CS Seminar, Model Construction from Databases	1999
University of British Columbia, Invited CS Seminar, Soccer Robots	1999
Simon Fraser University, Invited CS Seminar, Model Construction from Database	1998
Carnegie Mellon University, Invited CS Seminar, On Soccer Robots	1998
Brazil-US International NSF-Workshop, Porto Alegre, Intelligent Robotics Agents	1997
The First International Conference on Intelligent Data Analysis, Barden-Barden, Germany	1996
University of California at Irvine, Invited CS Seminar, Metapattern-Based Data Mining	1996
UCLA, Invited CS Seminar, Metapattern-Based Data Mining	1996
Italian International Conference on Abstract Intelligent Agents, Invited Talk, Autonomous Learning	1994
University of Texas at Austin, Invited MS Seminar, Integration of Heterogeneous Databases	1994
Eastman Chemical Company, TN, Invited Corporate Seminar, Data Mining for Chemical Databases	1994
Bellcore Inc., NJ, Invited Corporate Seminar, Data Mining for Telecommunication Databases	1993
University of Texas at Austin, Invited Seminar for Management Science, Autonomous Learning Agents	1991

# **Research Interests**

I am interested in interdisciplinary research in the following areas:

Self-Reconfigurable Robots and Systems	Surprise-Based Learning (Advanced Machine Learning)
Swarm Robotics, Systems, Applications	Self-Organization Theories and Models

Data mining and knowledge discovery Computational scientific discovery Multi-agent systems Distributed control of complex systems Life science and technology Biologically inspired systems and theories Machine learning Distributed constraint optimization Modeling of complex systems and Brain Autonomous Adaptive Systems

### **Research Projects**

Swarm UAVs for Mine Detection	2018-2020
Autonomous Robots for Underground Water Pipe Inspection (PipeFish)	2017-2018
Self-Assembly for space applications (StarCell)	2013-2018
Modular Reconfigurable Robots for Self-Assembly	2012-2013
Visual Intelligence and Activity Recognition by Learned, Structured Models	2010-2012
Surprise-Based Learning	2006-Present
SuperBot: Modular, reconfigurable and multifunctional robots	2005-Present
CATALINA: Autonomous underwater robots	2004-Present
Self-configuring, self-optimizing, self-healing, and tethering robotic network	2008-2009
SERES: Self-healing robots	2005-2007
MORPHOSE: Self-reconfigurable robots	2004-2007
SOLAR: Space self-assembly via self-reconfigurable robots	2002-2004
CiSoft: Robotics application for intelligent oil field	2005-2006
HORMCOMM: Hormone-inspired adaptive communication	2001-2003
SOALA: Self-organizing and autonomous learning robots and agents	2000-2004
CONRO: Self-reconfigurable robots	1998-2002
DYNAMITE: Dynamic and real-time distributed resource allocation in multi-agent systems	1998-2002
TEAMCORE: Robust and flexible multi-robot agent teams	1998-2001
ADAPTEAM: Adaptive and self-organizing agent teams	1997-2000
Dreamteam: Soccer-playing robot teams (1997 world champion)	1997-1999
DataCrystal: Metapattern-based, integrated data mining systems	1996-2000
YODA: Indoor navigation robots	1996
SIMS: Intelligent data mediator	1995-1998
DSQTM: Distributed semantic query/transaction manager (~50,000 lines), MCC	1992-1994
CYC: Learning in very large knowledge base, MCC	1990-1992

### **PhD Dissertation**

Shen, W.-M. *Learning from the Environment Based on Actions and Percepts* Carnegie Mellon University, under the supervision of Nobel Laureate Professor Herbert A. Simon

#### **Books**

- 1. Shen, et. al. Swarm and Self-Reconfigurable Robots (co-editor), 2011
- 2. Shen, W.-M., *Autonomous Learning from the Environment* (Foreword by Professor Herbert A. Simon), W. H. Freeman, Computer Science Press, 1994.
- 3. Shen, W.-M., (editor) Learning Action Models: A Collection of Research Papers, AAAI Press, 1993.
- 4. Gini, M., W.-M. Shen, C. Torras, H. Yuasa (editors) Intelligent Autonomous Systems, IAS7, IOS Press, 2002.
- 5. Shen, W.-M. (editors) Handbook of Data Mining and Knowledge Discovery, Oxford University Press, 2001.

### **Journal Publications**

- 1. Thomas Joseph Collins and W.-M. Shen, Surprise-Based Learning of State Representations, *Biologically Inspired Cognitive Architectures*, 24:1–20, 2018.
- 2. Thomas Joseph Collins and W.-M. Shen, A Robust Cognitive Architecture for Learning from Surprises, *Biologically Inspired Cognitive Architectures*, 21(C):1–12, 2017.
- Mohammad R. Jahanshahi, Wei-Min Shen, Tarutal Ghosh Mondal, Mohamed Abdelbarr, Sami F. Masri, and Uvais A. Qidwai. Reconfigurable Swarm Robots for Structural Health Monitoring-A Brief Review. *International Journal of Intelligent Robotics and Applications*, pp. 1–23, May 2017.
- 4. Mohamed Abdelbarr, Yulu Luke Chen, Mohammad R Jahanshahi, Sami F Masri, Wei-Min Shen and Uvais A Qidwai. 3D dynamic displacement-field measurement for structural health monitoring using inexpensive RGB-D based sensor. *Smart Materials and Structures*, 26(12):125016, 2017.

1989

- 5. Hou, Feili, and W.-M. Shen, Graph-Based Optimal Reconfiguration Planning for Self-Reconfigurable Robots, *Robotic and Autonomous Systems*, In Press, 2013.
- 6. Hou, Feili, and W.-M. Shen, MorphLine: a Distributed and Autobomous Self-Reconfiguration Planning Method for Modular Robots, *IEEE Transaction on Robotics*, Under Review, 2013.
- Rubenstein, M., W.-M. Shen, Y. Sai, and CM Chuong, Regenerative Patterning in Swarm Robots Mutual Benefits of Research in Robotics and Stem Cell Biology, *International Journal for Developmental Biology*, 53:869-881, 2009.
- 8. Mark Yim, Wei-Min Shen, Behnam Salemi, Daniela Rus, Mark Moll, Hod Lipson, Eric Klavins, and Gregory S. Chirikjian. Modular Self-Reconfigurable Robot Systems -- Challenges and Opportunities for the Future. *IEEE Robotics and Automation Magazine*, 43–53, March, 2007.
- 9. Colombano, S.P., and Wei-Min Shen. Self-Sustaining Robotic Systems, Guest Editorial, *Autonomous Robots*, 20(2):83-84, 2006.
- 10. Shen, W.-M., Maks Krivokon, Harris Chiu, Jacob Everist, Michael Rubenstein, Jagadesh Venkatesh, Multimode Locomotion for Reconfigurable Robots, *Autonomous Robots*, 20(2):165-177, 2006.
- 11. Modi, P. J., W.-M. Shen, M. Tambe, and M. Yokoo, ADOPT: Asynchronous Distributed Constraint Optimization with Quality Guarantees, *Artificial Intelligence Journal*, 161(1-2):180, January 2005.
- 12. Shen, W.-M, P. Will, A. Galstyan, C.-M. Chuong, Hormone-inspired self-organization and distributed control of robotic swarms, *Autonomous Robots*, 17:93-105, 2004.
- Jiang, T-X., Wideltz, RB., Shen, W.-M., Will, P., Wu, DY., Lin, CM., Jung, JS., Chuong, CM., 2004. Integument pattern formation involves genetic and epigenetic controls operated at different levels: Feather arrays simulated by a digital hormone model. *International Journal on Developmental Biology*, 48, 2004.
- 14. Salemi, B., P. Will, and W.-M. Shen, Distributed Task Negotiation in Modular Robots, Special Issue on "Modular Robotics", *Journal of the Robotics Society of Japan* (RSJ), 2003.
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Program Committee, IEEE International Conference on Robotics and Automation (ICRA)2006-2012Co-Chair, Workshop on self-reconfigurable robots, ICRA2010-2012Program Committee, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)2006-2011Chair, Workshop on self-reconfigurable robots, IROS2008Chair, Workshop on self-reconfigurable robots, IROS2007Co-Chair, Workshop on self-reconfigurable robots, Robotic Science-System Conference2006Scientific Committee, Workshop on self-replication machines, ALIFE X Intl Conference.2006

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Co Chair for the 2rd Conference on Debegraphics for space evaluation (NASA Amos)	2006
Co-Chair for the 3rd Conference on Robosphere for space exploration (NASA Ames)	2006
Program Committee, AAAI conference	2006
Chair for self-reconfigurable robot workshop at Robotic System Conference at MIT	2005
Co-Chair for the 2nd Conference on Robosphere for space exploration (NASA Ames)	2004
Co-Chair for the 7th International Conference on Intelligent and Autonomous Systems	2002
Organizing Chair, ICRA Workshop on Self-Reconfigurable Robots, Seoul, Korean.	2001
Organization Committee for International RoboCup Midsize Competition	1997-2001
Program Committee, Annual conference for American Association of Artificial Intelligence	1998, 2000
Organizing Chair, Robot Demonstration at International Conference of Autonomous Agents	1999
Program Committee, European Conference on Principles and Practice of Knowledge Discovery	1997-1999
Program Committee, International Conference on Agent Theories, Architectures, and Languages	1997-1998
Program Committee, International Conference on Knowledge Discovery and Data Mining	1996-1998
Program Committee, Workshop on Deductive and Object-Oriented Databases, Singapore	1995
Member of Penal, Intelligent Data Analysis, Baden-Baden Germany	1995
Member of Scientific Committee: The 2nd International Workshop on Abstract Intelligent Agent, Italy.	1994
Chair, Workshop on Learning Action Models, AAAI conference, Washington DC.	1993

### Journal Editing and Paper Reviewing

Invited Guest Editor, Special Issue of Self-Reconfigurable Modular Robots, Robotics Journal2018Co-Guest-Editor, Special Issue on Self-Reconfigurable Robots, Robotic and Autonomous Systems Journal2013Journal Reviewers: (1996-Present)2013

(1) Proceedings of National Academy of Sciences (NPAS), (2) Journal of Field Robotics,

(3) International Journal on Robotics Research, (4) IEEE Transactions on Robotics and Automation,

(5) Autonomous Robots, (6) Robotics and Autonomous Systems,

(7) IEEE Transactions on Knowledge and Data Engineering,

(8) Artificial Intelligence, (9) Machine Learning, Decision Support Systems,

(10) Distributed and Parallel Databases, (11) Journal of Artificial Intelligence Research,

(12) IEEE Transactions on Mechatronics

Conference Paper Reviewers:

International Conference on Intelligent Robotics Systems (2003-2010), International Conference on Robotics and Automation (1999-2010), International Conference on Robotics Science and Systems (2008-2010) National conference on Artificial Intelligence (1998), International Joint Conference on Artificial Intelligence (1993), Data Engineering Conference (1993), Conference of Cognitive Science (1992), IFIP World Computer Congress (1988).

*Co-Guest-Editor*, Special Issue on Self-Sustaining Robotic Systems, *Autonomous Robots Journal*, 2005-2006. *Editor*, Special Issue on Self-Reconfigurable Robots, *IEEE Transactions on Mechatronics*, 7(4), 2002. *Editorial Board Member, The Handbook of Data Mining and Knowledge Discovery*, Oxford University Press. 2001. *Editorial Board Member, Intelligent Data Analysis*. 1996-Present.

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#### **Professional References**

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