Due Tuesday 10/25/22 (9am; on DEN Webpage)

1. Compute  $A^t$  and  $e^{At}$  for the matrices

$$A_1 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, A_2 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}, A_3 = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 2 & 2 & 0 & 0 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 3 \end{bmatrix}.$$

2. For the system

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} u$$
$$y = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + u$$

- a) Determine stability properties.
- b) Determine the transfer function.
- 3. For the nonlinear system

$$\dot{x}_1 = -x_1^2 + x_1 x_2 
\dot{x}_2 = -2x_2^2 + x_2 - x_1 x_2 + 2$$

- (a) Show that  $\bar{x} = \begin{bmatrix} 1 & 1 \end{bmatrix}^T$  is an equilibrium point.
- (b) Is  $\bar{x}$  the only equilibrium point?
- (c) Linearize this system around  $\bar{x} = \begin{bmatrix} 1 & 1 \end{bmatrix}^T$  and find the resolvent and the state-transition matrix of the resulting linearized system.
- (d) What can you say about the stability properties of  $\bar{x} = \begin{bmatrix} 1 & 1 \end{bmatrix}^T$  for the original nonlinear system based on linearization?
- 4. Consider the following nonlinear system

$$\dot{x}_1 = -\frac{x_2}{1+x_1^2} - 2x_1 
\dot{x}_2 = \frac{x_1}{1+x_1^2}.$$

- (a) Show that the origin is an equilibrium point.
- (b) Linearize the nonlinear system around the equilibrium point.
- (c) Obtain a suitable Lyapunov function for the linearized system by solving the Lyapunov equation

$$A^T P + P A = -Q,$$

where

$$Q = \left[ \begin{array}{cc} 2 & 0 \\ 0 & 2 \end{array} \right].$$