Due Th 10/03/24 (10am; on DEN Webpage)

1. (a) Suppose that A and B are constant square matrices. Show that the state transition matrix for the time-varying system described by

$$\dot{x}(t) = e^{-At} B e^{At} x(t)$$

is

$$\Phi(t,s) = e^{-At}e^{(A+B)(t-s)}e^{As}$$

(b) If A is an  $n \times n$  matrix of full rank, show using the definition of the matrix exponential that

$$\int_0^t e^{A\sigma} d\sigma = [e^{At} - I]A^{-1}.$$

Using this result, obtain the solution to the linear time-invariant equation

$$\dot{x} = Ax + B\bar{u} \;, \quad x(0) = x_0$$

where  $\bar{u}$  is a constant r-dimensional vector and B is an  $(n \times r)$ -dimensional matrix.

2. Consider the discrete-time system

$$x_{k+1} = A x_k + B u_k$$

$$y_k = C x_k + D u_k$$

$$x(k_0) = x_0$$

with constant matrices A, B, C, and D.

- (a) Prove that this system is linear and time-invariant.
- (b) Using the definition of the  $\mathbb{Z}$ -transform prove that  $\mathbb{Z}(A^k) = z R(z)$ , where  $R(z) := (z I A)^{-1}$  is the resolvent of the matrix A.
- (c) For

$$A = \left[ \begin{array}{cc} 0 & 1 \\ -0.5 & 0.3 \end{array} \right]$$

determine R(z). From the resulting expression for the resolvent compute the state transition matrix of the above system at k = 9.

3. Use the (matrix) exponential series to evaluate  $e^{At}$  for:

(a) 
$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$
;

(b) 
$$A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$
.

Also, determine the eigenvalue decomposition (i.e., the eigenvalues and eigenvectors) of these two matrices.

Note: You are not allowed to use Matlab in this exercise.

4. Suppose A(t) is an  $n \times n$  time-varying matrix with continuous entries that satisfies

$$A(t) \left( \int_{t_0}^t A(\sigma) d\sigma \right) = \left( \int_{t_0}^t A(\sigma) d\sigma \right) A(t).$$

Show that the state-transition matrix  $\Phi(t_1, t_0)$  can be computed as

$$\Phi(t, t_0) = \exp\left(\int_{t_0}^t A(\sigma) \, d\sigma\right).$$

5. For the Mathieu equation,

$$\ddot{y}(t) + (\omega - \alpha \cos(2t)) y(t) = 0$$

use Matlab to compute the state-transition matrix with  $x_1 = y$ ,  $x_2 = \dot{y}$ ,  $\omega = 2$ ,  $\alpha = 1$ . You should do your computations on the time interval of length equal to three periods of oscillations for  $t_0 = 0$  and  $t_0 = 1$ .

6. Consider the following system

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} A_{11} & 0 \\ \alpha A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$y = \begin{bmatrix} 0 & I \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
(S)

where  $x_1 \in \mathbb{R}^{n_1}$  and  $x_2 \in \mathbb{R}^{n_2}$  are the states,  $y \in \mathbb{R}^{n_2}$  is the output, and  $\alpha$  is the positive parameter.

- (a) Determine if the matrix A is normal.
- (b) Find the expression for the state-transition matrix and the resolvent of the above system. The resulting state transition matrix should be partitioned conformably with the partition of the matrix A and its components should be expressed in terms of  $A_{11}$ ,  $A_{21}$ ,  $A_{22}$ , and  $\alpha$ .
- (c) For

$$A_{11} = \begin{bmatrix} -1 & -2 \\ -2 & -5 \end{bmatrix}, \quad A_{22} = -1, \quad A_{21} = \begin{bmatrix} 1 & 2 \end{bmatrix}$$

find the right and the left eigenvectors of the matrix A. You result should be expressed in terms of the parameter  $\alpha$  and the left eigenvectors should be normalized to satisfy bi-orthogonality condition.

- (d) For the system given in part (c), determine the expression for the system's output arising from the initial conditions in  $x_1$  and  $x_2$ . You should use the results obtained in part (c) here.
- (e) Sketch the output components determined in part (d). How do your results change if  $\alpha$  is increased? Explain your observations.