# Cost Sharing Network Routing Game 

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## 1 The Game

Consider a graph $G(V, E)$ and $n$ players, where the $i^{\text {th }}$ player is interested in moving from his source node $s_{i} \in V$ to a common $\operatorname{sink} t \in V$. Each player strategically chooses a path, $p_{i}$, from his source to the sink in order to minimize his own cost $C_{i}$. The cost of a path $p_{i}$ depends on all the rest $p_{j}$ and decreases with the number of players sharing the path ${ }^{1}$.

To fix ideas, we can think of the graph as a public transportation network, where each edge represents a bus route connecting two stations. The $n$ players can be thought of as employees that want to commute from their home stations $s_{i}$ to a company located at station $t$. Assume that the operation of each route requires a fixed amount of money, say one unit of cost, which people using that route can share. Now, the natural objective of each employee is to find a path that minimizes his commuting expenses.

More specifically, the cost function of the $i^{t h}$ player can be written as

$$
\begin{equation*}
C_{i}(\mathrm{P})=\sum_{e \in p_{i}} \frac{1}{n_{p}(e)} \tag{1}
\end{equation*}
$$

where $\mathrm{P}=\left[p_{1}, \ldots, p_{i}, \ldots, p_{n}\right]^{T}$ is the strategy vector and $n_{p}(e)=\left|\left\{p_{j} \in \mathrm{P} \mid e \in p_{j}\right\}\right|$ is the number of paths in P sharing an edge $e$.
Under best-response dynamics, the $i^{\text {th }}$ player "wakes up" arbitrarily, observes the current strategic configuration $\mathrm{P}=\left[p_{1}, \ldots, p_{i}, \ldots, p_{n}\right]^{T}$, and chooses the $p_{i}{ }^{\prime}$ that minimizes (and strictly improves) his own cost $C_{i}\left(\mathrm{P}^{\prime}\right), \mathrm{P}^{\prime}=\left[p_{1}, \ldots, p_{i}^{\prime}, \ldots, p_{n}\right]^{T}$. We say that the game reaches an equilibrium if no player has incentive to deviate from his current strategy, i.e., change his path. More formally, if $\mathrm{P}^{[k]}$ denotes the strategic configuration at time $k$, then there is a time $1<t_{e q}<\infty$ such that if we wake any player $i$ at time $t_{e q}$, then we have $\mathrm{P}^{\left[t_{e q}+1\right]}=\mathrm{P}^{\left[t_{e q}\right]}$. In fact, $\mathrm{P}^{[k]}=\mathrm{P}^{\left[t_{e q}\right]}, \forall k \geq t_{e q}$.

A cost sharing network routing (CSNR) instance can be described by the following tuple:

$$
\operatorname{CSNR}=\left(\mathcal{N}, G(V, E),\left\{\mathcal{P}_{i}\right\}_{i \in \mathcal{N}},\left\{C_{i}: \times_{j \in \mathcal{N}} \mathcal{P}_{j} \rightarrow \mathbb{R}\right\}_{i \in \mathcal{N}}\right)
$$

where $\mathcal{N}=\{1,2, \ldots, n\}$ is the index set of the players, $G(V, E)$ is the network graph, $\mathcal{P}_{i}$ is the set of all simple paths from $s_{i} \in V$ to $t \in V$ in $G(V, E)$ (all the $i^{t h}$ player's strategies), and $C_{i}$ is the $i^{t h}$ player's cost function as defined in (1).

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## 2 Existence of Equilibrium

### 2.1 Best Response Graphs

The best response dynamics of a game can be modeled as a directed graph $F(P, R)$. The vertices, $v \in P$, in the graph are the configurations of the strategic choices and the edges, $e \in R$, correspond to player's best responses. In our game, the vertices are $\mathrm{P}=\left[p_{1}, \ldots, p_{i}, \ldots, p_{n}\right]^{T}, p_{j} \in \mathcal{P}_{j}$ and there is an edge from P to $\mathrm{P}^{\prime}=\left[p_{1}, \ldots, p_{i}^{\prime}, \ldots, p_{n}\right]^{T}$ if $p_{i}^{\prime}$ is the minimizer of $C_{i}\left(\mathrm{P}^{\prime}\right)$, with $C_{i}(\mathrm{P})-C_{i}\left(\mathrm{P}^{\prime}\right)>0$. Note that in CSNR game the set of all possible configurations $P$ is finite and the graph is finite.

### 2.2 Potential Games

Consider a function $\Phi$ that maps configurations in a game to a real number. In our example $\Phi$ maps $\mathrm{P}=\left[p_{1}, \ldots, p_{i}, \ldots, p_{n}\right]^{T}$ to the reals. Now consider an edge in the best response graph from P to $\mathrm{P}^{\prime}=\left[p_{1}, \ldots, p_{i}^{\prime}, \ldots, p_{n}\right]^{T}$. Call this change $A \rightarrow B_{i}$. We now define two functions.

$$
\begin{align*}
& \Delta \Phi\left(A, B_{i}\right):=\Phi\left(B_{i}\right)-\Phi(A)  \tag{2}\\
& \Delta C_{i}\left(A, B_{i}\right):=C_{i}\left(B_{i}\right)-C_{i}(A) \tag{3}
\end{align*}
$$

Recall that $C_{i}$ is the cost function of the $i^{t h}$ player. Note that the function $\Delta C_{i}\left(A, B_{i}\right)$ is defined for that $i$ that made the best response in $A \rightarrow B_{i}$. A game is a potential game if there exists a function $\Phi$ such that, for all $A$ and for all $i, \Delta \Phi\left(A, B_{i}\right)$ and $\Delta C_{i}\left(A, B_{i}\right)$ have the same sign.

### 2.3 Existence of Equilibrium for Potential Games

We now argue that potential games have an equilibrium that can be achieved through best response dynamics. Consider the best response graph of a potential game. Observe that for every edge $\left(A, B_{i}\right)$ in the graph, $\Delta C_{i}\left(A, B_{i}\right)$ is strictly negative. Which implies that $\Phi\left(B_{i}\right)<\Phi(A)$. That is for all edges $(A, B)$ in the graph, $\Phi(B)<\Phi(A)$.

Assume there exists a cycle in the graph. Then clearly there exists an edge $(A, B)$ in the cycle such that $\Phi(B) \geq \Phi(A)$. This is a contradiction. Thus, our graph is a finite directed acyclic graph. Such graphs always have a sink node. Clearly, such a sink node represents an equilibrium.

### 2.4 CSNR game is a Potential Game

Here we will prove that CSNR game is a potential game and thus has an equilibrium that can be achieved through best response dynamics.

Proof. Define a function $\Phi: \times_{j \in \mathcal{N}} \mathcal{P}_{j} \rightarrow \mathbb{R}$ as follows:

$$
\begin{equation*}
\Phi(\mathrm{P})=\sum_{e \in E}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p}(e)}\right) \tag{4}
\end{equation*}
$$

where $\mathrm{P}=\left[p_{1}, \ldots, p_{i}, \ldots, p_{n}\right]^{T}, p_{j} \in \mathcal{P}_{j}$, and $n_{p}(e)=\left|\left\{p_{j} \in \mathrm{P} \mid e \in p_{j}\right\}\right|$. We will show that $\Phi$ is a potential function for the CSNR game.

Let $\mathrm{P}^{\prime}=\left[p_{1}, \ldots, p_{i}^{\prime}, \ldots, p_{n}\right]^{T}$ be the strategic configuration after the $i^{\text {th }}$ player's best response, with $\Delta C_{i}\left(\mathrm{P}, \mathrm{P}^{\prime}\right)<0$. We want to show that $\Delta \Phi\left(\mathrm{P}, \mathrm{P}^{\prime}\right)<0$.
Let $E^{+}=\left\{e \in p_{i}^{\prime} \backslash p_{i}\right\}$ and $E^{-}=\left\{e \in p_{i} \backslash p_{i}^{\prime}\right\}$ be the set of edges included only in $p_{i}^{\prime}$ and $p_{i}$ respectively. We can partition the edges as the union of four disjoint sets:

$$
E=E^{+} \cup E^{-} \cup\left\{e \in p_{i}^{\prime} \cap p_{i}\right\} \cup\left\{e \notin p_{i}^{\prime} \cup p_{i}\right\}
$$

It is evident that $n_{p^{\prime}}(e) \neq n_{p}(e)$ only for edges $e \in E^{+} \cup E^{-}$, since the number, $n_{p^{\prime}}(e)$, of players using an edge, changes only for the edges where the paths $p_{i}$ and $p_{i}^{\prime}$ differ. More specifically,

$$
n_{p^{\prime}}(e)= \begin{cases}n_{p}(e)+1,, & \text { if } e \in E^{+} \\ n_{p}(e)-1, & \text { if } e \in E^{-}\end{cases}
$$

We can write:

$$
\begin{aligned}
\Delta \Phi\left(\mathrm{P}, \mathrm{P}^{\prime}\right)= & \Phi\left(\mathrm{P}^{\prime}\right)-\Phi(\mathrm{P})=\sum_{e \in E}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p^{\prime}}(e)}\right)-\sum_{e \in E}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p}(e)}\right) \\
= & \sum_{e \in E^{+}}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p^{\prime}}(e)}\right)+\sum_{e \in E^{-}}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p^{\prime}}(e)}\right) \\
& -\left[\sum_{e \in E^{+}}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p}(e)}\right)+\sum_{e \in E^{-}}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p}(e)}\right)\right] \\
= & \sum_{e \in E^{+}}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p}(e)+1}\right)+\sum_{e \in E^{-}}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p}(e)-1}\right) \\
& -\sum_{e \in E^{+}}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p}(e)}\right)-\sum_{e \in E^{-}}\left(1+\frac{1}{2}+\cdots+\frac{1}{n_{p}(e)}\right) \\
= & \sum_{e \in E^{+}} \frac{1}{n_{p}(e)+1}-\sum_{e \in E^{-}} \frac{1}{n_{p}(e)} \\
= & \sum_{e \in E^{+}} \frac{1}{n_{p}(e)+1}+\sum_{e \in p_{i}^{\prime} \cap p_{i}} \frac{1}{n_{p}(e)}-\sum_{e \in E^{-}} \frac{1}{n_{p}(e)}-\sum_{e \in p_{i}^{\prime} \cap p_{i}} \frac{1}{n_{p}(e)} \\
= & \sum_{e \in p_{i}^{\prime}} \frac{1}{n_{p^{\prime}}(e)}-\sum_{e \in p_{i}} \frac{1}{n_{p}(e)}=C_{i}\left(\mathrm{P}^{\prime}\right)-C_{i}(\mathrm{P})=\Delta C_{i}\left(\mathrm{P}, \mathrm{P}^{\prime}\right)<0
\end{aligned}
$$

Hence, $\Phi(\mathrm{P})$ is a potential function for the CSNR game.

## 3 Convergence to Equilibrium

In the previous sections we proved that an equilibrium point exists for the CSNR game. A natural question, now, is how fast the players can reach it under best response dynamics.

### 3.1 How long can a sequence of best responses be?

Consider the best response graph $F(P, R)$ for the CSNR game, as described in section 2.1, where vertices correspond to strategic configurations P , and edges represent best responses. We have seen that $F(P, R)$ is a finite directed acyclic graph and thus any path from a vertex P to a sink $\mathrm{P}^{*}$ is of finite length. But how does this path length scale with respect to the number of players and the size of the network?

Let $r(s)$ be a the path in $F(P, R)$, from a vertex $s \in P$ to its corresponding $\operatorname{sink} t_{s} \in P$. We are interested in bounding the number of edges in $r(s)$ for all $s \in P$. Since $r(s)$ is a best-response sequence of a potential game, there is a strictly negative number $\Delta \Phi\left(v_{k}, v_{l}\right)$ associated with every edge $\left(v_{k}, v_{l}\right) \in r(s)$, that corresponds to the reduction in the potential function after some player's response from $v_{k}$ to $v_{l}$.

For a path $r(s)$ in $F(P, R)$ we have:

$$
\begin{equation*}
\Phi\left(t_{s}\right)=\Phi(s)-\sum_{\left(v_{k}, v_{l}\right) \in r(s)}\left|\Delta \Phi\left(v_{k}, v_{l}\right)\right| \tag{5}
\end{equation*}
$$

where $\Phi\left(t_{s}\right)$ is a local minimum of the potential function that is reached by starting from $\Phi(s)$ and following the best response path $r(s)$. See Fig. 1 for an illustration of Eq.5.

To upper bound the number of edges in $r(s)$ we can write:

$$
\begin{aligned}
\Phi\left(t_{s}\right) & \leq \Phi(s)-\sum_{\left(v_{k}, v_{l}\right) \in r(s)} \min _{\left(v_{k}, v_{l}\right) \in r(s)}\left\{\left|\Delta \Phi\left(v_{k}, v_{l}\right)\right|\right\} \\
& =\Phi(s)-A(s) \min _{\left(v_{k}, v_{l}\right) \in r(s)}\left\{\left|\Delta \Phi\left(v_{k}, v_{l}\right)\right|\right\}
\end{aligned}
$$

or, equivalently:

$$
A(s) \leq \frac{\Phi(s)-\Phi\left(t_{s}\right)}{\min _{\left(v_{k}, v_{l}\right) \in r(s)}\left\{\left|\Delta \Phi\left(v_{k}, v_{l}\right)\right|\right\}}
$$

where $A(s)=\left|\left\{\left(v_{k}, v_{l}\right) \in r(s)\right\}\right|$, is the number of edges in $r(s)$.
Since $0 \leq \Phi(a) \leq|\mathrm{E}|(\ln (n)+1), \forall a \in P$, (this can be shown directly from in Eq.4, by setting $n_{p}(e)=n, \forall e \in E$ and upper bounding the harmonic number $H_{n}$ by $\ln (n)+1$ ), we can further upper bound the number of edges for all paths $r(s)$ in $F(P, R)$ by writing:

$$
\begin{equation*}
A(s) \leq \frac{|\mathrm{E}|(\ln (n)+1)}{\min _{\left(v_{k}, v_{l}\right) \in R}\left\{\left|\Delta \Phi\left(v_{k}, v_{l}\right)\right|\right\}}, \forall s \in P \tag{6}
\end{equation*}
$$

Hence, the length of all best-response sequences is upper bounded by a quantity inversely proportional to the minimum possible change $\left|\Delta \Phi\left(\mathrm{P}, \mathrm{P}^{\prime}\right)\right|$ in the potential function.


Figure 1: A best-response path to equilibrium and strictly negative reductions in the potential function

### 3.2 How small can $\left|\Delta \Phi\left(P, P^{\prime}\right)\right|$ be?

Let $\mathrm{P}=\left[p_{1}, \ldots, p_{i}, \ldots, p_{n}\right]^{T}$ be an arbitrary strategic configuration and let $\mathrm{P}^{\prime}=\left[p_{1}, \ldots, p_{i}^{\prime}, \ldots, p_{n}\right]^{T}$ be the strategic configuration after the $i^{t h}$ player's best response. Then,

$$
\begin{align*}
\Delta \Phi\left(\mathrm{P}, \mathrm{P}^{\prime}\right) & =\Delta C_{i}\left(\mathrm{P}, \mathrm{P}^{\prime}\right) \\
& =C_{i}\left(\mathrm{P}^{\prime}\right)-C_{i}(\mathrm{P}) \\
& =\sum_{e \in p_{i}^{\prime}} \frac{1}{n_{p^{\prime}}(e)}-\sum_{e \in p_{i}} \frac{1}{n_{p}(e)} \tag{7}
\end{align*}
$$

Lemma 1. $d(K, n) \triangleq\left|\sum_{i=1}^{K_{1}} \frac{1}{a_{i}}-\sum_{j=1}^{K_{2}} \frac{1}{b_{j}}\right| \geq n^{-2 K}$, for all integers $a_{i}, b_{j} \in\{1, \ldots, n\}$ and $K_{1}, K_{2} \in$ $\{1, \ldots, K\}: d(K, n) \neq 0$

Proof. (by Elsholtz) First notice that a sum of $K_{1}$ unit fractions, each of denominator $a_{i} \leq n$, can be rewritten as a single fraction with a denominator bounded by the product of the $a_{i}$, i.e, by $n^{K_{1}}$. Thus, $\sum_{i=1}^{K_{1}} \frac{1}{a_{i}}=\frac{x_{a}}{m_{a}}$, with $m_{a} \leq n^{K_{1}}$ and $\sum_{i=1}^{K_{2}} \frac{1}{b_{j}}=\frac{x_{b}}{m_{b}}$, with $m_{b} \leq n^{K_{2}}, \forall a_{i}, b_{j} \in\{1, \ldots, n\}$, and their absolute difference can be written as $d(K, n)=\left|\frac{x_{a}}{m_{a}}-\frac{x_{b}}{m_{b}}\right|=\frac{\left|m_{b} x_{a}-m_{a} x_{b}\right|}{m_{a} m_{b}}$. Since $d(K, n)$ is constrained to be nonzero, the smallest possible value for $\left|m_{b} x_{a}-m_{a} x_{b}\right|$ is one (must be integer). Hence, $d(K, n) \geq \frac{1}{m_{a} m_{b}} \geq \frac{1}{n^{\left(K_{1}+K_{2}\right)}} \geq n^{-2 K}, \forall K_{1}, K_{2} \in\{1, \ldots, K\}$.

Now, we can use Lemma 1 to lower bound the expression in Eq. 7 and get :

$$
\begin{equation*}
\left|\Delta \Phi\left(\mathrm{P}, \mathrm{P}^{\prime}\right)\right| \geq n^{-2|\mathrm{E}|} \tag{8}
\end{equation*}
$$

Hence, a player's response reduces the potential function $\Phi(\mathrm{P})$ by at least $1 / n^{2|E|}$.

### 3.3 The speed of convergence

Putting Eq. 6 and Eq. 8 together, we get:

$$
\begin{align*}
A(s) & \leq \frac{|\mathrm{E}|(\ln (n)+1)}{\min _{\left(v_{k}, v_{l}\right) \in R}\left\{\left|\Delta \Phi\left(v_{k}, v_{l}\right)\right|\right\}} \\
& \leq|\mathrm{E}|(\ln (n)+1) / n^{-2|E|}, \forall s \in P \tag{9}
\end{align*}
$$

Hence, the CSNR game reaches an equilibrium after $\mathcal{O}\left(|E| n^{2|E|} \log (n)\right)$ best responses.

## References

[1] S.-H Teng. Lecture notes CS599 - Games, Economics, Networks and Data Analysis, Fall 2010.
[2] D. Monderer and L.S. Shapley, Potential games. Games and Economic Behavior 14 (1996), pp. 124143.
[3] R. W. Rosenthal. A class of games possessing pure-strategy nash equilibria. International Journal of Game Theory, 2:65-67, 1973.
[4] J.F. Nash, Equilibrium points in n-person games. Proc. National Academy of Sciences 36 (1950), pp. 4849.


[^0]:    ${ }^{1}$ Given a graph $G(V, E)$, a path $p$ from $s \in V$ to $t \in V$ can be formally defined as the set of adjacent edges: $p=\left\{\left(s, v_{1}\right),\left(v_{1}, v_{2}\right), \ldots,\left(v_{k-1}, v_{k}\right),\left(v_{k}, t\right) \mid v_{i} \in V\right\}$

